



**TNC 426 TNC 430** 

NC Software 280 476-xx 280 477-xx

User's Manual HEIDENHAIN Conversational Format

10/2001



### Controls on the visual display unit



Split screen layout



Switch between machining or programming modes







Switching the soft-key rows



Changing the screen settings (only BC 120)

## Typewriter keyboard for entering letters and symbols











File names Comments

programs

ISO



# Machine operating modes



MANUAL OPERATION



ELECTRONIC HANDWHEEL



POSITIONING WITH MDI



PROGRAM RUN, SINGLE BLOCK



PROGRAM RUN, FULL SEQUENCE

## **Programming modes**



PROGRAMMING AND EDITING



**TEST RUN** 

#### Program/file management, TNC functions



Select or delete programs and files External data transfer



Enter program call in a program



MOD functions



Displaying help texts for NC error messages

CALC

Pocket calculator

# Moving the highlight, going directly to blocks, cycles and parameter functions







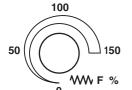


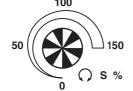
Move highlight

GОТО

Go directly to blocks, cycles and parameter functions

#### Override control knobs for feed rate/spindle speed





## **Programming path movements**



Approach/depart contour



FK free contour programming



Straight line



Circle center/pole for polar coordinates

°√c

Circle with center



Circle with radius



Circular arc with tangential connection



Chamfer



Corner rounding

#### **Tool functions**





Enter and call tool length and radius

# Cycles, subprograms and program section repeats





Define and call cycles



Enter and call labels for subprogramming and program section repeats



Program stop in a program



Enter touch probe functions in a program

## Coordinate axes and numbers: Entering and editing







Select coordinate axes or enter them into the program





Numbers







Change arithmetic sign



Polar coordinates



Incremental dimensions



Q parameters



Capture actual position



Skip dialog questions, delete words



Confirm entry and resume dialog



End block



Clear numerical entry or TNC error message



Abort dialog, delete program section





## **TNC Models, Software and Features**

This manual describes functions and features provided by the TNCs as of the following NC software numbers.

TNC Model	NC Software No.
TNC 426 CB, TNC 426 PB	280 476-xx
TNC 426 CF, TNC 426 PF	280 477-xx
TNC 426 M	280 476-xx
TNC 426 ME	280 477-xx
TNC 430 CA, TNC 430 PA	280 476-xx
TNC 430 CE, TNC 430 PE	280 477-xx
TNC 430 M	280 476-xx
TNC 430 ME	280 477-xx

The suffixes E and F indicate the export versions of the TNC which have the following limitations:

■ Linear movement is possible in no more than 4 axes simultaneously.

The machine tool builder adapts the useable features of the TNC to his machine by setting machine parameters. Some of the functions described in this manual may not be among the features provided by your machine tool.

TNC functions that may not be available on your machine include:

- Probing function for the 3-D touch probe
- Digitizing option
- Tool measurement with the TT 130
- Rigid tapping
- Returning to the contour after an interruption

Please contact your machine tool builder to become familiar with the features of your machine.

Many machine manufacturers, as well as HEIDENHAIN, offer programming courses for the TNCs. We recommend these courses as an effective way of improving your programming skill and sharing information and ideas with other TNC users.



## **Touch Probe Cycles User's Manual:**

All of the touch probe functions are described in a separate manual. Please contact HEIDENHAIN if you require a copy of this User's Manual. ID number: 329 203-xx.

#### Location of use

The TNC complies with the limits for a Class A device in accordance with the specifications in EN 55022, and is intended for use primarily in industrially-zoned areas.

### New features of the NC software 280 476-xx

- Thread milling cycles 262 to 267 (see "Fundamentals of thread milling" on page 235)
- Tapping Cycle 209 with chip breaking (see "TAPPING WITH CHIP BREAKING (Cycle 209)" on page 233)
- Cycle 247(see "DATUM SETTING (Cycle 247)" on page 324)
- Cycle run by means of point tables (see "Point Tables" on page 206)
- Entering two miscellaneous functions M (see "Entering Miscellaneous Functions M and STOP" on page 176)
- Program stop with M01 (see "Optional Program Run Interruption" on page 416)
- Starting NC programs automatically (see "Automatic Program Start" on page 414)
- Selecting datum tables in the NC program (see "Selecting a datum table in the part program" on page 322)
- Editing the active datum table in the program run mode of operation (see "Edit a pocket table in a Program Run operating mode." on page 323)
- Selecting the screen layout for pallet tables (see "Screen layout for executing pallet tables" on page 83)
- New columns in the tool table for managing TS calibration data (see "Entering tool data in tables" on page 101)
- Management of unlimited calibration data with the TS triggering touch probes (see User's Manual for Touch Probe Cycles)
- Cycles for automatic tool measurement with the TT tool touch probe in ISO (see User's Manual for Touch Probe Cycles)
- New Cycle 440 for measuring the axial displacement of a machine with the TT tool touch probe (see User's Manual for Touch Probe Cycles)
- Support of Teleservice functions (see "Teleservice" on page 444)
- Setting the display mode for blocks with more than one line, e.g. for cycle definitions (see "MP7281.0 Programming and Editing operating mode" on page 457)
- New SYSREAD function 501 for reading REF values from datum tables (see "FN18: SYS-DATUM READ Read system data" on page 373)
- M140 (see "Retraction from the contour in the tool-axis direction: M140" on page 188)
- M141 (see "Suppressing touch probe monitoring: M141" on page 189)
- M142 (see "Delete modal program information: M142" on page 190)
- M143 (see "Delete basic rotation: M143" on page 190)
- M144 (see "Compensating the machine's kinematic configuration for ACTUAL/NOMINAL positions at end of block: M144" on page 197)



- External access with the LSV-2 interface (see "Permitting/ Restricting external access" on page 445)
- Tool-oriented machining (see "Pallet Operation with Tool-Oriented Machining" on page 84)

# Changed features of the NC software 280 476-xx

- Programming PGM CALL (see "Separate Program as Subprogram" on page 345)
- Programming CYCLE CALL (see "Calling a cycle" on page 204)
- The feed-rate unit for M136 was changed from µm/rev to mm/rev. (see "Feed rate in millimeters per spindle revolution: M136" on page 184)
- The size of the contour memory for SL cycles was doubled. (see "SL cycles" on page 285)
- M91 and M92 are now also possible with tilted working plane. (see "Positioning in a tilted coordinate system" on page 332)
- Display of the NC program during the execution of pallet tables (see "Program Run, Full Sequence and Program Run, Single Block" on page 8) and (see "Screen layout for executing pallet tables" on page 83)

## New/changed descriptions in this manual.

- TNCremoNT (see "Data transfer between the TNC and TNCremoNT" on page 425)
- FK Free Contour Programming (see "Path Contours—FK Free Contour Programming" on page 158)
- Summary of input formats (see "Technical Information" on page 465)
- Mid-program startup of pallet tables (see "Mid-program startup (block scan)" on page 412)
- Exchanging the buffer battery (see "Exchanging the Buffer Battery" on page 469)

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Introduction

# 1.1 The TNC 426, the TNC 430

HEIDENHAIN TNC controls are workshop-oriented contouring controls that enable you to program conventional machining operations right at the machine in an easy-to-use conversational programming language. They are designed for milling, drilling and boring machines, as well as for machining centers. The TNC 426 can control up to 5 axes; the TNC 430 can control up to 9 axes. You can also change the angular position of the spindle under program control.

An integrated hard disk provides storage for as many programs as you like, even if they were created off-line or by digitizing. For quick calculations you can call up the on-screen pocket calculator at any time.

Keyboard and screen layout are clearly arranged in a such way that the functions are fast and easy to use.

# Programming: HEIDENHAIN conversational and ISO formats

HEIDENHAIN conversational programming is an especially easy method of writing programs. Interactive graphics illustrate the individual machining steps for programming the contour. If a production drawing is not dimensioned for NC, the HEIDENHAIN FK free contour programming carries out the necessary calculations automatically. Workpiece machining can be graphically simulated either during or before actual machining. It is also possible to program in ISO format or DNC mode.

You can also enter and test one program while the TNC is running another.

# Compatibility

2

The TNC can execute all part programs that were written on HEIDENHAIN controls TNC 150 B and later.



1 Introduction



# 1.2 Visual Display Unit and Keyboard

## Visual display unit

The TNC is available with either a color CRT screen (BC 120) or a TFT flat panel display (BF 120. The figure at top right shows the keys and controls on the BC 120, and the figure at center right shows those of the BF 120.

#### 1 Header

When the TNC is on, the selected operating modes are shown in the screen header: the machining mode at the left and the programming mode at right. The currently active mode is displayed in the larger box, where the dialog prompts and TNC messages also appear (unless the TNC is showing only graphics).

2 Soft keys

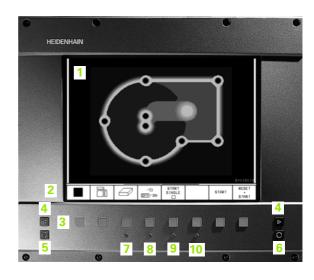
In the footer the TNC indicates additional functions in a soft-key row. You can select these functions by pressing the keys immediately below them. The lines immediately above the soft-key row indicate the number of soft-key rows that can be called with the black arrow keys to the right and left. The line representing the active soft-key row is highlighted.

- 3 Soft key selector keys
- 4 Switching the soft-key rows
- 5 Setting the screen layout
- 6 Shift key for switchover between machining and programmi 13 modes

#### Keys on BC 120 only

- 7 Screen demagnetization; Exit main menu for screen settings
- 8 Select main menu for screen settings:
  - In the main menu: Move highlight downward
  - In the submenu: Reduce value or move picture to the left or downward
- 9 In the main menu: Move highlight upward
  - In the submenu: Increase value or move picture to the right or upward
- 10 In the main menu: Select submenu
  - In the submenu: Exit submenu

Main menu dialog	Function
BRIGHTNESS	Adjust brightness
CONTRAST	Adjust contrast
H-POSITION	Adjust horizontal position





Main menu dialog	Function
V-POSITION	Adjust vertical position
V-SIZE	Adjust picture height
SIDE-PIN	Correct barrel-shaped distortion
TRAPEZOID	Correct trapezoidal distortion
ROTATION	Correct tilting
COLOR TEMP	Adjust color temperature
R-GAIN	Adjust strength of red color
B-GAIN	Adjust strength of blue color
RECALL	No function

The BC 120 is sensitive to magnetic and electromagnetic noise, which can distort the position and geometry of the picture. Alternating fields can cause the picture to shift periodically or to become distorted.

# **Screen layout**

You select the screen layout yourself: In the PROGRAMMING AND EDITING mode of operation, for example, you can have the TNC show program blocks in the left window while the right window displays programming graphics. You could also display the program structure in the right window instead, or display only program blocks in one large window. The available screen windows depend on the selected operating mode.

To change the screen layout:



Press the SPLIT SCREEN key: The soft-key row shows the available layout options (see "Modes of Operation," page 6).



Select the desired screen layout.

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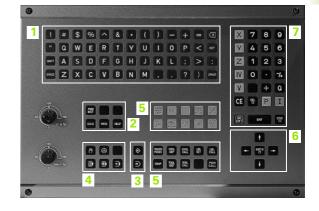


# **Keyboard**

The figure at right shows the keys of the keyboard grouped according to their functions:

- Alphanumeric keyboard for entering texts and file names, as well as for programming in ISO format
- 2 File management
  - Pocket calculator
  - MOD functions
  - HELP function
- 3 Programming modes
- 4 Machine operating modes
- 5 Initiation of programming dialog
- 6 Arrow keys and GOTO jump command
- 7 Numerical input and axis selection

The functions of the individual keys are described on the inside front cover. Machine panel buttons, e.g. NC START, are described in the manual for your machine tool.



# 1.3 Modes of Operation

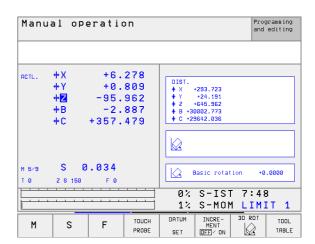
## **Manual Operation and Electronic Handwheel**

The Manual Operation mode is required for setting up the machine tool. In this operating mode, you can position the machine axes manually or by increments, set the datums, and tilt the working plane.

The Electronic Handwheel mode of operation allows you to move the machine axes manually with the HR electronic handwheel.

**Soft keys for selecting the screen layout** (select as described previously)

Screen windows	Soft key
Positions	POSITION
Left: positions. Right: status display.	POSITION STATUS

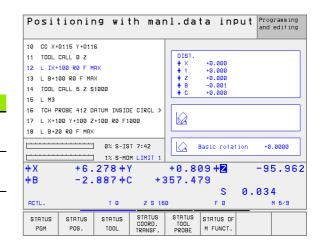


# Positioning with manual data input (MDI)

This mode of operation is used for programming simple traversing movements, such as for face milling or pre-positioning. You can also define point tables for setting the digitizing range in this mode.

#### Soft keys for selecting the screen layout

Screen windows	Soft key
Program	PGM
Left: program blocks, right: status display	PGM * STATUS



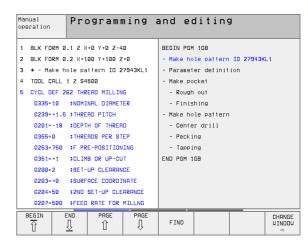
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## **Programming and Editing**

In this mode of operation you can write your part programs. The FK free programming feature, the various cycles and the Q parameter functions help you with programming and add necessary information. If desired, you can have the programming graphics show the individual steps, or you can use a separate screen window to prepare your program structure.

#### Soft keys for selecting the screen layout

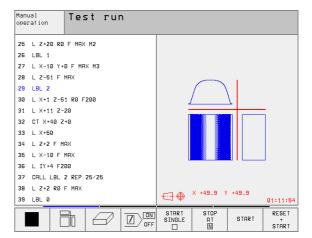
Screen windows	Soft key
Program	PGM
Left: program blocks, right: program structure	PGM * SECTS
Left: program. Right: programming graphics	PGM + GRAPHICS



## Test run

In the Test Run mode of operation, the TNC checks programs and program sections for errors, such as geometrical incompatibilities, missing or incorrect data within the program or violations of the work space. This simulation is supported graphically in different display modes.

Soft keys for selecting the screen layout: see "Program Run, Full Sequence and Program Run, Single Block," page 8.



# **Program Run, Full Sequence and Program Run, Single Block**

In the Program Run, Full Sequence mode of operation the TNC executes a part program continuously to its end or to a manual or programmed stop. You can resume program run after an interruption.

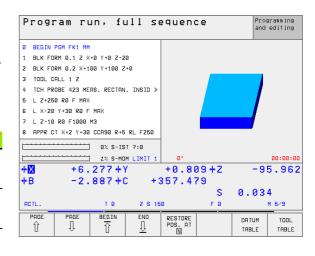
In the Program Run, Single Block mode of operation you execute each block separately by pressing the machine START button.

## Soft keys for selecting the screen layout

Screen windows	Soft key
Program	PGM
Left: program blocks, right: program structure	PGM + SECTS
Left: program. Right: status	PGM * STATUS
Left: program. Right: graphics	PGM + GRAPHICS
Graphics	GRAPHICS

#### Soft keys for selecting the screen layout for pallet tables

Screen windows	Soft key
Pallet table	PALLET
Left: program. Right: pallet table	PGM + PALLET
Left: pallet table. Right: status	PALLET + STATUS
Left: pallet table. Right: graphics	PALLET  GRAPHICS



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# 1.4 Status Displays

# "General" status display

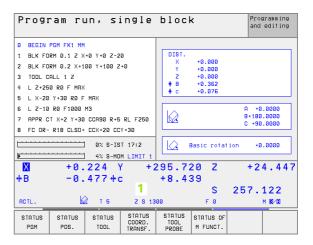
The status display 1 informs you of the current state of the machine tool. It is displayed automatically in the following modes of operation:

- Program Run, Single Block and Program Run, Full Sequence, except if the screen layout is set to display graphics only, and
- Positioning with Manual Data Input (MDI).

In the Manual mode and Electronic Handwheel mode the status display appears in the large window.

#### Information in the status display

Symbol	Meaning
ACTL.	Actual or nominal coordinates of the current position
XYZ	Machine axes; the TNC displays auxiliary axes in lower-case letters. The sequence and quantity of displayed axes is determined by the machine tool builder. Refer to your machine manual for more information
ESM	The displayed feed rate in inches corresponds to one tenth of the effective value. Spindle speed S, feed rate F and active M functions
*	Program run started
<b>→</b>	Axis locked
$\odot$	Axis can be moved with the handwheel
	Axes are moving in a tilted working plane
	Axes are moving under a basic rotation



i

## Additional status displays

The additional status displays contain detailed information on the program run. They can be called in all operating modes, except in the Programming and Editing mode of operation.

## To switch on the additional status display:



Call the soft-key row for screen layout.



Select the layout option for the additional status display.

## To switch on the additional status display:



Shift the soft-key rows until the STATUS soft keys appear.

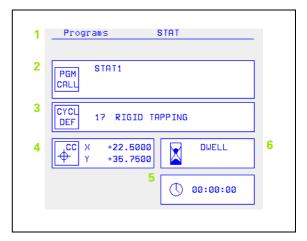


Select the desired additional status display, e.g. general program information.

You can choose between several additional status displays with the following soft keys:

#### **General program information** STATUS PGM

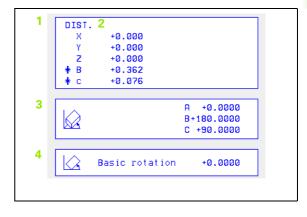
- Name of main program 1
- Active programs
- 3 Active machining cycle
- Circle center CC (pole)
- Operating time
- Dwell time counter



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## Positions and coordinates

- 1 Position display
- 2 Type of position display, e.g. actual position
- 3 Tilt angle of the working plane
- 4 Angle of a basic rotation

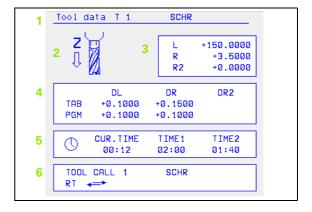


## Information on tools

- T: Tool number and nameRT: Number and name of a replacement tool
- 2 Tool axis

STATUS COORD. TRANSF.

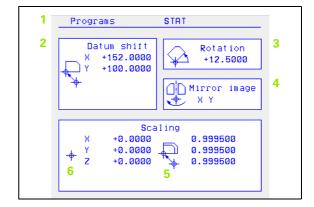
- 3 Tool length and radii
- 4 Oversizes (delta values) from TOOL CALL (PGM) and the tool table (TAB)
- 5 Tool life, maximum tool life (TIME 1) and maximum tool life for TOOL CALL (TIME 2)
- 6 Display of the active tool and the (next) replacement tool



## Coordinate transformations

- 1 Name of main program
- 2 Active datum shift (Cycle 7)
- 3 Active rotation angle (Cycle 10)
- 4 Mirrored axes (Cycle 8)
- 5 Active scaling factor(s) (Cycles 11 / 26)
- 6 Scaling datum

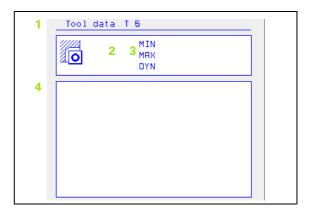
See "Coordinate Transformation Cycles" on page 319.





#### **Tool measurement**

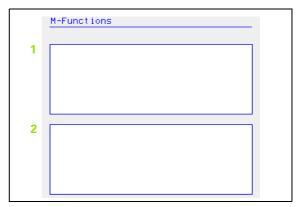
- Number of the tool to be measured
- Display whether the tool radius or the tool length is being measured
- MIN and MAX values of the individual cutting edges and the result of measuring the rotating tool (DYN = dynamic measurement)
- Cutting edge number with the corresponding measured value. If the measured value is followed by an asterisk, the allowable tolerance in the tool table was exceeded



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## STATUS OF Active miscellaneous functions M

- 1 List of the active M functions with fixed meaning.
- 2 List of the active M functions with function assigned by machine manufacturer.



# 1.5 Accessories: HEIDENHAIN 3-D Touch Probes and Electronic Handwheels

#### **3-D Touch Probes**

With the various HEIDENHAIN 3-D touch probe systems you can:

- Automatically align workpieces
- Quickly and precisely set datums
- Measure the workpiece during program run
- Digitize 3-D surfaces (option), and
- Measure and inspect tools



All of the touch probe functions are described in a separate manual. Please contact HEIDENHAIN if you require a copy of this User's Manual. ID number: 329 203-xx.

#### TS 220, TS 630 and TS 632 touch trigger probes

These touch probes are particularly effective for automatic workpiece alignment, datum setting, workpiece measurement and for digitizing. The TS 220 transmits the triggering signals to the TNC via cable and is a cost-effective alternative for applications where digitizing is not frequently required.

The TS 630 and TS 632 feature infrared transmission of the triggering signal to the TNC. This makes them highly convenient for use on machines with automatic tool changers.

Principle of operation: HEIDENHAIN triggering touch probes feature a wear resisting optical switch that generates an electrical signal as soon as the stylus is deflected. This signal is transmitted to the TNC, which stores the current position of the stylus as an actual value

During digitizing the TNC generates a program containing straight line blocks in HEIDENHAIN format from a series of measured position data. You can then output the program to a PC for further processing with the SUSA evaluation software. This evaluation software enables you to calculate male/female transformations or correct the program to account for special tool shapes and radii that differ from the shape of the stylus tip. If the tool has the same radius as the stylus tip you can run these programs immediately.



#### TT 130 tool touch probe for tool measurement

The TT 130 is a triggering 3-D touch probe for tool measurement and inspection. Your TNC provides three cycles for this touch probe with which you can measure the tool length and radius automatically either with the spindle rotating or stopped. The TT 130 features a particularly rugged design and a high degree of protection, which make it insensitive to coolants and swarf. The triggering signal is generated by a wear-resistant and highly reliable optical switch.

#### HR electronic handwheels

Electronic handwheels facilitate moving the axis slides precisely by hand. A wide range of traverses per handwheel revolution is available. Apart from the HR 130 and HR 150 integral handwheels, HEIDENHAIN also offers the HR 410 portable handwheel (see figure at center right).





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**Manual Operation and Setup** 

## 2.1 Switch-on, Switch-off

## Switch-on



Switch-on and traversing the reference points can vary depending on the individual machine tool. Refer to your machine manual.

Switch on the power supply for control and machine. The TNC automatically initiates the following dialog

#### **MEMORY TEST**

The TNC memory is automatically checked.

#### **POWER INTERRUPTED**



TNC message that the power was interrupted — clear the message.

#### TRANSLATE PLC PROGRAM

The PLC program of the TNC is automatically compiled.

#### RELAY EXT. DC VOLTAGE MISSING



Switch on external dc voltage. The TNC checks the functioning of the EMERGENCY STOP circuit.

## MANUAL OPERATION TRAVERSE REFERENCE POINTS



Cross the reference points manually in the displayed sequence: For each axis press the machine START button, or





Cross the reference points in any sequence: Press and hold the machine axis direction button for each axis until the reference point has been traversed.



The TNC is now ready for operation in the Manual Operation mode.



The reference points need only be traversed if the machine axes are to be moved. If you intend only to write, edit or test programs, you can select the Programming and Editing or Test Run modes of operation immediately after switching on the control voltage.

You can then traverse the reference points later by pressing the PASS OVER REFERENCE soft key in the Manual Operation mode.

#### Traversing the reference point in a tilted working plane

The reference point of a tilted coordinate system can be traversed by pressing the machine axis direction buttons. The "tilting the working plane" function must be active in the Manual Operation mode, see "To activate manual tilting:," page 27. The TNC then interpolates the corresponding axes.

The NC START button is not effective. Pressing this button may result in an error message.



Make sure that the angle values entered in the menu for tilting the working plane match the actual angles of the tilted axis.

#### Switch-off

To prevent data being lost at switch-off, you need to run down the operating system as follows:

Select the Manual mode.



- Select the function for run-down, confirm again with the YES soft key.
- ▶ When the TNC displays the message Now you can switch off the TNC in a superimposed window, you may cut off the power supply to the TNC.



Inappropriate switch-off of the TNC can lead to data loss.

## 2.2 Moving the Machine Axes

### Note



Traversing with the machine axis direction buttons is a machine-dependent function. The machine tool manual provides further information.

## To traverse with the machine axis direction buttons:



Select the Manual Operation mode.



Press the machine axis-direction button and hold it as long as you wish the axis to move, or



Move the axis continuously: Press and hold the machine axis direction button, then press the machine START button





To stop the axis, press the machine STOP button.

You can move several axes at a time with these two methods. You can change the feed rate at which the axes are traversed with the F soft key, see "Spindle Speed S, Feed Rate F and Miscellaneous Functions M," page 21.



## Traversing with the HR 410 electronic handwheel

The portable HR 410 handwheel is equipped with two permissive buttons. The permissive buttons are located below the star grip.

You can only move the machine axes when an permissive button is depressed (machine-dependent function).

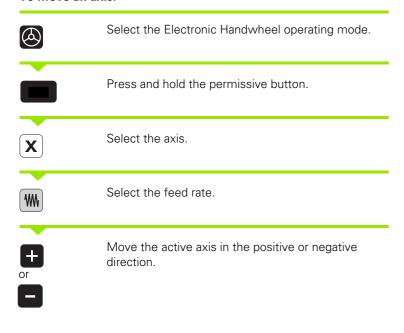
The HR 410 handwheel features the following operating elements:

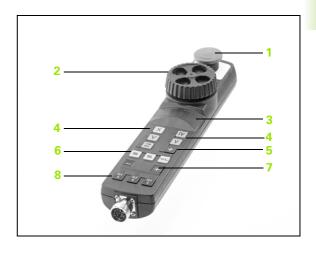
- **1** EMERGENCY STOP
- 2 Handwheel
- 3 Permissive buttons
- 4 Axis address keys
- 5 Actual-position-capture key
- 6 Keys for defining the feed rate (slow, medium, fast; the feed rates are set by the machine tool builder)
- 7 Direction in which the TNC moves the selected axis
- 8 Machine function (set by the machine tool builder)

The red indicators show the axis and feed rate you have selected.

It is also possible to move the machine axes with the handwheel during a program run.

#### To move an axis:





## Incremental jog positioning

With incremental jog positioning you can move a machine axis by a preset distance.



Select Manual or Electronic Handwheel mode of operation.



Select incremental jog positioning: Switch the INCREMENT soft key to ON

JOG INCREMENT =

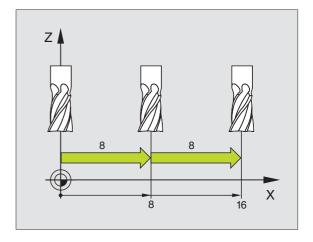




Enter the jog increment in millimeters, i.e. 8 mm.



Press the machine axis direction button as often as desired.



# 2.3 Spindle Speed S, Feed Rate F and Miscellaneous Functions M

#### **Function**

In the operating modes Manual Operation and Electronic Handwheel, you can enter the spindle speed S, feed rate F and the miscellaneous functions M with soft keys. The miscellaneous functions are described in Chapter 7 "Programming: Miscellaneous Functions."



The machine tool builder determines which miscellaneous functions M are available on your TNC and what effects they have.

## **Entering values**

#### Spindle speed S, miscellaneous function M



To enter the spindle speed, press the S soft key.

## SPINDLE SPEED S =

1000

Enter the desired spindle speed and confirm your entry with the machine START button.



The spindle speed S with the entered rpm is started with a miscellaneous function M. Proceed in the same way to enter a miscellaneous function M.

#### Feed rate F

After entering a feed rate F, you must confirm your entry with the ENT key instead of the machine START button.

The following is valid for feed rate F:

- If you enter F=0, then the lowest feed rate from MP1020 is effective
- F is not lost during a power interruption

## Changing the spindle speed and feed rate

With the override knobs you can vary the spindle speed S and feed rate F from 0% to 150% of the set value.



The override dial for spindle speed is only functional on machines with infinitely variable spindle drive.



# 2.4 Datum Setting(Without a 3-D Touch Probe)

### Note



For datum setting with a 3-D touch probe, refer to the new Touch Probe Cycles Manual.

You fix a datum by setting the TNC position display to the coordinates of a known position on the workpiece.

## **Preparation**

- ▶ Clamp and align the workpiece.
- Insert the zero tool with known radius into the spindle.
- ▶ Ensure that the TNC is showing the actual position values.

## **Datum setting**



#### Fragile workpiece?

If the workpiece surface must not be scratched, you can lay a metal shim of know thickness d on it. Then enter a tool axis datum value that is larger than the desired datum by the value d.



Select the Manual Operation mode.





Move the tool slowly until it touches the workpiece surface.

Select an axis (all axes can also be selected via the ASCII keyboard)

#### DATUM SET Z=

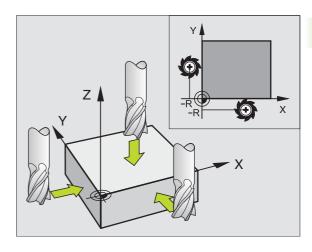




Zero tool in spindle axis: Set the display to a known workpiece position (here, 0) or enter the thickness d of the shim. In the tool axis, offset the tool radius.

Repeat the process for the remaining axes.

If you are using a preset tool, set the display of the tool axis to the length L of the tool or enter the sum Z=L+d.



## 2.5 Tilting the working plane

## Application, function



The functions for tilting the working plane are interfaced to the TNC and the machine tool by the machine tool builder. With some swivel heads and tilting tables, the machine tool builder determines whether the entered angles are interpreted as coordinates of the tilt axes or as angular components of a tilted plane. Refer to your machine manual.

The TNC supports the tilting functions on machine tools with swivel heads and/or tilting tables. Typical applications are, for example, oblique holes or contours in an oblique plane. The working plane is always tilted around the active datum. The program is written as usual in a main plane, such as the X/Y plane, but is executed in a plane that is tilted relative to the main plane.

There are two functions available for tilting the working plane

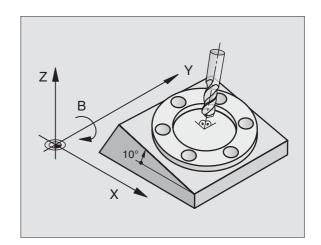
- 3-D ROT soft key in the Manual mode and Electronic Handwheel mode, see "To activate manual tilting:," page 27
- Tilting under program control, Cycle 19 WORKING PLANE in the part program (see "WORKING PLANE (Cycle 19)" on page 330)

The TNC functions for "tilting the working plane" are coordinate transformations in which the working plane is always perpendicular to the direction of the tool axis.

When tilting the working plane, the TNC differentiates between two machine types

#### ■ Machines with tilting tables:

- You must tilt the workpiece into the desired position for machining by positioning the tilting table, for example with an L block
- The position of the transformed tool axis **does not change** in relation to the machine-based coordinate system. Thus if you rotate the table—and therefore the workpiece—by 90° for example, the coordinate system **does not rotate**. If you press the Z+ axis direction button in the Manual Operation mode, the tool moves in Z+ direction.
- In calculating the transformed coordinate system, the TNC considers only the mechanically influenced offsets of the particular tilting table (the so-called "translational" components).



#### ■ Machines with swivel heads

- You must bring the tool into the desired position for machining by positioning the swivel head, for example with an L block.
- The position of the transformed tool axis changes in relation to the machine-based coordinate system. Thus if you rotate the swivel head of your machine—and therefore the tool—in the B axis by 90° for example, the coordinate system rotates also. If you press the Z+ axis direction button in the Manual Operation mode, the tool moves in X+ direction of the machine-based coordinate system
- In calculating the transformed coordinate system, the TNC considers both the mechanically influenced offsets of the particular swivel head (the so-called "translational" components) and offsets caused by tilting of the tool (3-D tool length compensation).

## Traversing the reference points in tilted axes

With tilted axes, you use the machine axis direction buttons to cross over the reference points. The TNC interpolates the corresponding axes. Be sure that the function for tilting the working plane is active in the Manual Operation mode and the actual angle of the tilted axis was entered in the menu field.

## Setting the datum in a tilted coordinate system

After you have positioned the rotary axes, set the datum in the same way as for a non-tilted system. The TNC then converts the datum for the tilted coordinate system. If your machine tool features axis control, the angular values for this calculation are taken from the actual position of the rotary axis.



You must not set the datum in the tilted working plane if in machine parameter 7500 bit 3 is set. If you do, the TNC will calculate the wrong offset.

If your machine tool is not equipped with axis control, you must enter the actual position of the rotary axis in the menu for manual tilting: The actual positions of one or several rotary axes must match the entry. Otherwise the TNC will calculate an incorrect datum.

## Datum setting on machines with rotary tables



The behavior of the TNC during datum setting depends on the machine. Refer to your machine manual.

The TNC automatically shifts the datum if you rotate the table and the tilted working plane function is active:

#### ■ MP 7500, bit 3=0

To calculate the datum, the TNC uses the difference between the REF coordinate during datum setting and the REF coordinate of the tilting axis after tilting. The method of calculation is to be used when you have clamped your workpiece in proper alignment when the rotary table is in the 0° position (REF value).

#### ■ MP 7500, bit 3=1

If you rotate the table to align a workpiece that has been clamped in an unaligned position, the TNC must no longer calculate the offset of the datum from the difference of the REF coordinates. Instead of the difference from the 0° position, the TNC uses the REF value of the tilting table after tilting. In other words, it assumes that you have properly aligned the workpiece before tilting.



MP 7500 is effective in the machine parameter list, or, if available, in the descriptive tables for tilted axis geometry. Refer to your machine manual.

## Position display in a tilted system

The positions displayed in the status window (ACTL. and NOML.) are referenced to the tilted coordinate system.

## Limitations on working with the tilting function

- The touch probe function Basic Rotation cannot be used.
- PLC positioning (determined by the machine tool builder) is not possible.



## To activate manual tilting:



To select manual tilting, press the 3-D ROT soft key. You can now select the desired menu items with the arrow keys

Enter the tilt angle.

To set the desired operating mode in menu option "Tilt working plane" to Active, select the menu option and shift with the ENT key.

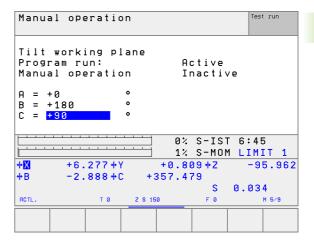


To conclude entry, press the END key.

To reset the tilting function, set the desired operating modes in menu "Tilt working plane" to Inactive.

If the Working Plane function is active and the TNC moves the machine axes in accordance with the tilted axes, the status display shows the symbol &

If you set the function "Tilt working plane" for the operating mode Program Run to Active, the tilt angle entered in the menu becomes active in the first block of the part program. If you are using Cycle 19 **WORKING PLANE** in the part program, the angular values defined in the cycle (starting at the cycle definition) are effective. Angular values entered in the menu will be overwritten.







3

Positioning with Manual Data Input (MDI)

# 3.1 Programming and Executing Simple Machining Operations

The operating mode Positioning with Manual Data Input is particularly convenient for simple machining operations or pre-positioning of the tool. It enables you to write a short program in HEIDENHAIN conversational programming or in ISO format, and execute it immediately. You can also call TNC cycles. The program is stored in the file \$MDI. In the operating mode Positioning with MDI, the additional status displays can also be activated.

## Positioning with manual data input (MDI)



Select the Positioning with MDI mode of operation. Program the file \$MDI as you wish.



To start program run, press the machine START button.



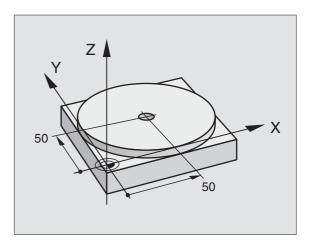
#### Limitation

FK free contour programming, programming graphics and program run graphics cannot be used. The \$MDI file must not contain a program call (**PGM CALL**).

#### Example 1

A hole with a depth of 20 mm is to be drilled into a single workpiece. After clamping and aligning the workpiece and setting the datum, you can program and execute the drilling operation in a few lines.

First you pre-position the tool in L blocks (straight-line blocks) to the hole center coordinates at a setup clearance of 5 mm above the workpiece surface. Then drill the hole with Cycle 1 **PECKING**.



O BEGIN PGM \$MDI MM	
1 TOOL DEF 1 L+0 R+5	Define tool: zero tool, radius 5
2 TOOL CALL 1 Z S2000	Call tool: tool axis Z
	Spindle speed 2000 rpm
3 L Z+200 RO F MAX	Retract tool (F MAX = rapid traverse)
4 L X+50 Y+50 RO F MAX M3	Move the tool at F MAX to a position above the hole.
	Spindle on
5 L Z+5 F2000	Position tool to 5 mm above hole.
6 CYCL DEF 1.0 PECKING	Define PECKING cycle:

7 CYCL DEF 1.1 SET UP 5	Setup clearance of the tool above the hole
8 CYCL DEF 1.2 DEPTH -20	Total hole depth (Algebraic sign=working direction)
9 CYCL DEF 1.3 PECKG 10	Depth of each infeed before retraction
10 CYCL DEF 1.4 DWELL 0.5	Dwell time in seconds at the hole bottom
11 CYCL DEF 1.5 F250	Feed rate for pecking
12 CYCL CALL	Call PECKING cycle
13 L Z+200 RO F MAX M2	Retract the tool
14 END PGM \$MDI MM	End of program

Straight-line function L (see "Straight line L" on page 140), PECKING cycle (see "PECKING (Cycle 1)" on page 211).

## Example 2: Correcting workpiece misalignment on machines with rotary tables

Use the 3-D touch probe to rotate the coordinate system. See "Touch Probe Cycles in the Manual and Electronic Handwheel Operating Modes," section "Compensating workpiece misalignment" in the new Touch Probes Cycles User's Manual.

Write down the Rotation Angle and cancel the Basic Rotation.



Select operating mode: Positioning with MDI.





Select the axis of the rotary table, enter the rotation angle you wrote down previously and set the feed rate. For example: L C+2.561 F50



Conclude entry.



Press the machine START button: The rotation of the table corrects the misalignment.

## Protecting and erasing programs in \$MDI

The \$MDI file is generally intended for short programs that are only needed temporarily. Nevertheless, you can store a program, if necessary, by proceeding as described below:



Select the Programming and Editing mode of operation



To call the file manager, press the PGM MGT key (program management).



Move the highlight to the \$MDI file.



To select the file copying function, press the COPY soft key.

#### Target file =

**BOREHOLE** 

Enter the name under which you want to save the current contents of the \$MDI file.



Copy the file.



To close the file manager, press the END soft key.

Erasing the contents of the \$MDI file is done in a similar way: Instead of copying the contents, however, you erase them with the DELETE soft key. The next time you select the operating mode Positioning with MDI, the TNC will display an empty \$MDI file.



If you wish to delete \$MDI, then

- you must not have selected the Positioning with MDI mode (not even in the background).
- you must not have selected the \$MDI file in the Programming and Editing mode.

For further information, see "Copying a single file," page 54.







Programming: Fundamentals of NC, File Management, Programming Aids, Pallet Management

## 4.1 Fundamentals

#### Position encoders and reference marks

The machine axes are equipped with position encoders that register the positions of the machine table or tool. When a machine axis moves, the corresponding position encoder generates an electrical signal. The TNC evaluates this signal and calculates the precise actual position of the machine axis.

If there is an interruption of power, the calculated position will no longer correspond to the actual position of the machine slide. The TNC can re-establish this relationship with the aid of reference marks when power is returned. The scales of the position encoders contain one or more reference marks that transmit a signal to the TNC when they are crossed over. From the signal the TNC identifies that position as the machine-axis reference point and can re-establish the assignment of displayed positions to machine axis positions.

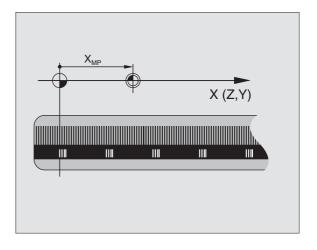
Linear encoders are generally used for linear axes. Rotary tables and tilt axes have angle encoders. If the position encoders feature distance-coded reference marks, you only need to move each axis a maximum of 20 mm (0.8 in.) for linear encoders, and 20° for angle encoders, to re-establish the assignment of the displayed positions to machine axis positions.

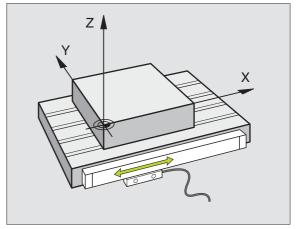
## Reference system

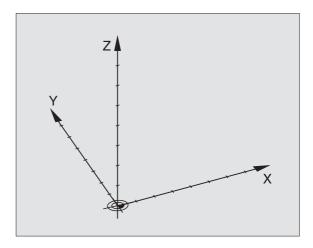
A reference system is required to define positions in a plane or in space. The position data are always referenced to a predetermined point and are described through coordinates.

The Cartesian coordinate system (a rectangular coordinate system) is based on the three coordinate axes X, Y and Z. The axes are mutually perpendicular and intersect at one point called the datum. A coordinate identifies the distance from the datum in one of these directions. A position in a plane is thus described through two coordinates, and a position in space through three coordinates.

Coordinates that are referenced to the datum are referred to as absolute coordinates. Relative coordinates are referenced to any other known position (datum) you define within the coordinate system. Relative coordinate values are also referred to as incremental coordinate values.





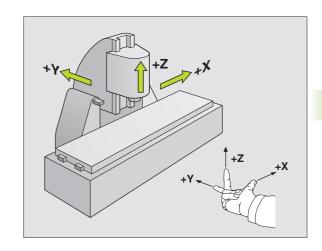


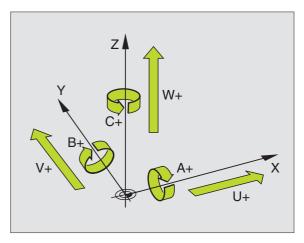


## Reference system on milling machines

When using a milling machine, you orient tool movements to the Cartesian coordinate system. The illustration at right shows how the Cartesian coordinate system describes the machine axes. The figure at center right illustrates the "right-hand rule" for remembering the three axis directions: the middle finger is pointing in the positive direction of the tool axis from the workpiece toward the tool (the Z axis), the thumb is pointing in the positive X direction, and the index finger in the positive Y direction.

The TNC 426 can control a machine tool in up to 5 axes; the TNC 430 controls up to 9 axes. The axes U, V and W are secondary linear axes parallel to the main axes X, Y and Z, respectively. Rotary axes are designated as A, B and C. The illustration at lower right shows the assignment of secondary axes and rotary axes to the main axes.





#### **Polar coordinates**

If the production drawing is dimensioned in Cartesian coordinates, you also write the part program using Cartesian coordinates. For parts containing circular arcs or angles it is often simpler to give the dimensions in polar coordinates.

While the Cartesian coordinates X, Y and Z are three-dimensional and can describe points in space, polar coordinates are two-dimensional and describe points in a plane. Polar coordinates have their datum at a circle center (CC), or pole. A position in a plane can be clearly defined by the:

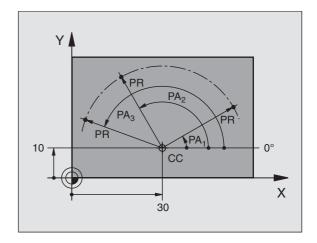
- Polar Radius, the distance from the circle center CC to the position, and the
- Polar Angle, the size of the angle between the reference axis and the line that connects the circle center CC with the position.

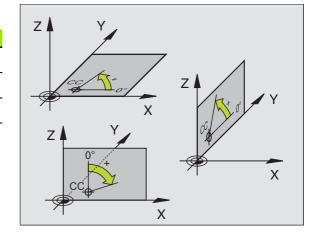
See figure at upper right.

#### Definition of pole and angle reference axis

The pole is set by entering two Cartesian coordinates in one of the three planes. These coordinates also set the reference axis for the polar angle PA.

Coordinates of the pole (plane)	Reference axis of the angle
X/Y	+X
Y/Z	+Y
Z/X	+Z







## Absolute and incremental workpiece positions

#### Absolute workpiece positions

Absolute coordinates are position coordinates that are referenced to the datum of the coordinate system (origin). Each position on the workpiece is uniquely defined by its absolute coordinates.

Example 1: Holes dimensioned in absolute coordinates

Hole 1	Hole 2	Hole 3
X = 10  mm	X = 30  mm	X = 50  mm
Y = 10 mm	Y = 20  mm	Y = 30  mm

#### Incremental workpiece positions

Incremental coordinates are referenced to the last programmed nominal position of the tool, which serves as the relative (imaginary) datum. When you write a part program in incremental coordinates, you thus program the tool to move by the distance between the previous and the subsequent nominal positions. Incremental coordinates are therefore also referred to as chain dimensions.

To program a position in incremental coordinates, enter the prefix "I" before the axis.

Example 2: Holes dimensioned in incremental coordinates

Absolute coordinates of hole 4

X = 10 mmY = 10 mm

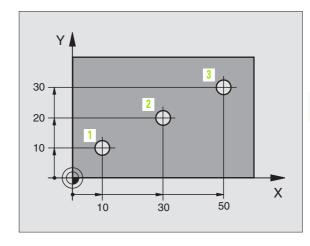
Hole 5, referenced to 4 Hole 5, referenced to 4

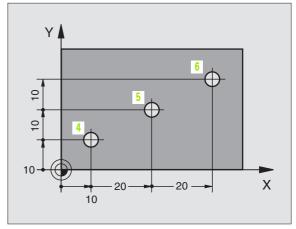
X = 20 mm X = 20 mm Y = 10 mm Y = 10 mm

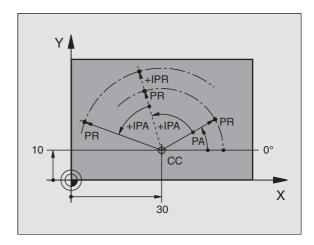
#### Absolute and incremental polar coordinates

Absolute polar coordinates always refer to the pole and the reference axis.

Incremental coordinates always refer to the last programmed nominal position of the tool.







## Setting the datum

A production drawing identifies a certain form element of the workpiece, usually a corner, as the absolute datum. Before setting the datum, you align the workpiece with the machine axes and move the tool in each axis to a known position relative to the workpiece. You then set the TNC display to either zero or a predetermined position value. This establishes the reference system for the workpiece, which will be used for the TNC display and your part program.

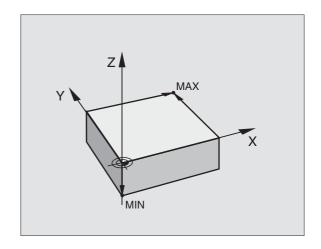
If the production drawing is dimensioned in relative coordinates, simply use the coordinate transformation cycles. (see "Coordinate Transformation Cycles" on page 319).

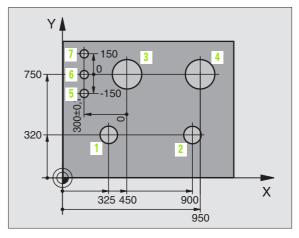
If the production drawing is not dimensioned for NC, set the datum at a position or corner on the workpiece, which is the most suitable for deducing the dimensions of the remaining workpiece positions.

The fastest, easiest and most accurate way of setting the datum is by using a 3-D touch probe from HEIDENHAIN. See the new Touch Probe Cycles User's Manual, chapter "Setting the Datum with a 3-D Touch Probe."

#### Example

The workpiece drawing at right shows holes (1 to 4) whose dimensions are shown with respect to an absolute datum with the coordinates X=0, Y=0. The holes (5 to 7) are dimensioned with respect to a relative datum with the absolute coordinates X=450, Y=750. With the **DATUM SHIFT** cycle you can temporarily set the datum to the position X=450, Y=750, to be able to program the holes (5 to 7) without further calculations.







# 4.2 File Management: Fundamentals



Using the MOD function PGM MGT (see "Configuring PGM MGT" on page 433), select between standard and advanced file management.

If the TNC is connected to a network (optional), then use file management with additional functions.

#### **Files**

Files in the TNC	Туре
Programs In HEIDENHAIN format In ISO format	.H .l
Tables for Tools Tool changers Pallets Datums Points (digitizing range of measuring touch probe) Cutting data Cutting materials, workpiece materials	.T .TCH .P .D .PNT .CDT .TAB
Texts as ASCII files	.A

When you write a part program on the TNC, you must first enter a file name. The TNC saves the program to the hard disk as a file with the same name. The TNC can also save texts and tables as files.

The TNC provides a special file management window in which you can easily find and manage your files. Here you can call, copy, rename and erase files.

You can manage any number of files on the TNC's hard disk. Their total size, however, must not exceed **1,500 MB**.

#### File names

When you store programs, tables and texts as files, the TNC adds an extension to the file name, separated by a point. This extension indicates the file type.

PROG20	.H
File name	File type
Maximum Length	See table "Files in the TNC."

## **Data security**

We recommend saving newly written programs and files on a PC at regular intervals.

You can do this with the free backup program TNCBACK.EXE from HEIDENHAIN. Your machine tool builder can provide you with a copy of TNCBACK.EXE.

In addition, you need a floppy disk on which all machine-specific data, such as PLC program, machine parameters, etc., are stored. Please contact your machine tool builder for more information on both the backup program and the floppy disk.



Saving the contents of the entire hard disk (up to 1500 MB) can take up to several hours. In this case, it is a good idea to save the data outside of working hours, (e.g. overnight), or to use the PARALLEL EXECUTE function to copy in the background while you work.



Depending on operating conditions (e.g., vibration load), hard disks generally have a higher failure rate after three to five years of service. HEIDENHAIN therefore recommends having the hard disk inspected after three to five years.

## 4.3 Standard File Management

## Note



The standard file management is best if you wish to save all files in one directory, or if you are well practiced in the file management of old TNC controls.

To use the standard file management, set the MOD function **PGM MGT** (see "Configuring PGM MGT" on page 433) to **Standard**.

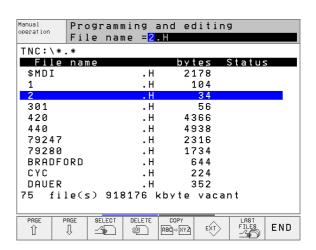
## Calling the file manager



Press the PGM MGT key: The TNC displays the file management window (see figure at right)

The window shows you all of the files that are stored in the TNC. Each file is shown with additional information:

Display	Meaning
FILE NAME	Name with up to 16 characters and file type
ВҮТЕ	File size in bytes
STATUS	Properties of the file:
Е	Program is selected in the Programming and Editing mode of operation.
S	Program is selected in the Test Run mode of operation.
М	Program is selected in a program run operating mode.
Р	File is protected against editing and erasure.



## Selecting a file



Call the file manager.

Use the arrow keys or the arrow soft keys to move the highlight to the file you wish to select:





Moves the highlight up or down **file by file** in the window.



Moves the highlight up or down **page by page** in the window.



ENT

To select the file: Press the SELECT soft key or the ENT key.

## **Deleting a file**



Call the file manager.

Use the arrow keys or the arrow soft keys to move the highlight to the file you wish to delete:





Moves the highlight up or down **file by file** in the window.



Moves the highlight up or down **page by page** in the window.



To delete the file: Press the DELETE soft key.

#### Delete ..... file?



Confirm with the YES soft key.

NO

Abort with the NO soft key.

## Copying a file



Call the file manager.

Use the arrow keys or the arrow soft keys to move the highlight to the file you wish to copy:





Moves the highlight up or down **file by file** in the window.



Moves the highlight up or down **page by page** in the window.



To copy the file: Press the COPY soft key.

#### Target file =

Enter the new name, and confirm your entry with the AUSFÜHREN soft key or the ENT key. A status window appears on the TNC, informing about the copying progress. As long as the TNC is copying, you can no longer work, or

If you wish to copy very long programs, enter the new file name and confirm with the PARALLEL EXECUTE soft key. The file will now be copied in the background, so you can continue to work while the TNC is copying.

## Data transfer to or from an external data medium



Before you can transfer data to an external data medium, you must setup the data interface(see "Setting the Data Interfaces" on page 422).



Call the file manager.



Activate data transfer: Press the EXT soft key. In the left half of the screen (1) the TNC shows all files saved on its hard disk. In the right half of the screen (2) it shows all files saved on the external data medium.

Manual operation Programming and editing File name =2.H2 TNC: \\*. \* RS232:\\*.\* [NO DIR] File r \$MDI 2178 .н 104 301 56 420 4366 440 4938 79247 2316 79280 1734 BRADFORD 224 CYC DAUER 352 75 file(s) 918176 kbyte vacant PAGE PAGE COPY TNC EXT TNC END Û Û TNC = EXT D = D

Use the arrow keys to highlight the file(s) that you want to transfer:





Moves the highlight up and down within a window





Moves the highlight from the left to the right window, and vice versa.

If you wish to copy from the TNC to the external data medium, move the highlight in the left window to the file to be transferred.

If you wish to copy from the external data medium to the TNC, move the highlight in the right window to the file to be transferred.

Tagging functions	Soft key
Tag a single file	TAG FILE
Tag all files	TAG ALL FILES
Untag a single file	UNTAG FILE
Untag all files	UNTAG ALL FILES
Copy all tagged files	COPY TAG



Transfer a single file: Press the COPY soft key, or



Transfer several files: Press the TAG soft key, or



Transfer all files: Press the TNC => EXT soft key.

Confirm with the EXECUTE or with the ENT key. A status window appears on the TNC, informing about the copying progress, or

If you wish to transfer more than one file or longer files, press the PARALLEL EXECUTE soft key. The TNC then copies the file in the background.



To stop transfer, press the TNC soft key. The standard file manager window is displayed again.

## Selecting one of the last 10 files selected



Call the file manager.



Display the last 10 files selected: Press the LAST FILES soft key.

Use the arrow keys to move the highlight to the file you wish to select:



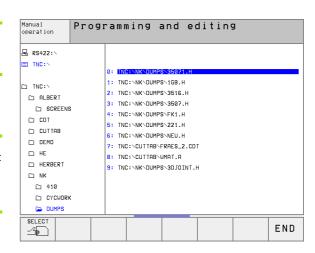


Move the highlight up or down.



To select the file: Press the SELECT soft key or the ENT key.





## Renaming a file



Call the file manager.

Use the arrow keys or the arrow soft keys to move the highlight to the file you wish to rename:





Moves the highlight up or down **file by file** in the window.



Moves the highlight up or down **page by page** in the window.



Press the RENAME soft key to select the renaming function

## Target file =

Enter the name of the new file and confirm your entry with the ENT key or EXECUTE soft key.



## Converting an FK program into HEIDENHAIN conversational format



Call the file manager.

Use the arrow keys or the arrow soft keys to move the highlight to the file you wish to convert:





Moves the highlight up or down **file by file** in the window.



Moves the highlight up or down **page by page** in the window.



Convert the file: Press the CONVERT FK -> H soft key.

#### Target file =

Enter the name of the new file and confirm your entry with the ENT key or EXECUTE soft key.

## **Protect file / Cancel file protection**



Call the file manager.

Use the arrow keys or arrow soft keys to move the highlight to the file you wish to protect or whose protection you wish to cancel:





Moves the highlight up or down **file by file** in the window.



Moves the highlight up or down **page by page** in the window.



To enable file protection: Press the PROTECT soft key. The file now has status P, or



Press the UNPROTECT soft key to cancel file protection. The P status is canceled.

## 4.4 Advanced File Management

#### Note



Use the advanced file manager if you wish to keep your files in individual directories.

To use it, set the MOD function PGM MGT (see "Configuring PGM MGT" on page 433).

See also "File Management: Fundamentals" on page 39.

#### **Directories**

To ensure that you can easily find your files, we recommend that you organize your hard disk into directories. You can divide a directory up into further directories, which are called subdirectories.



The TNC can manage up to 6 directory levels!

If you save more than 512 files in one directory, the TNC no longer sorts them alphabetically!

#### **Directory names**

The name of a directory can contain up to 8 characters and does not have an extension. If you enter more than 8 characters for the directory name, the TNC will display an error message.

#### **Paths**

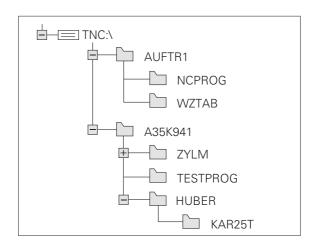
A path indicates the drive and all directories and subdirectories under which a file is saved. The individual names are separated by the symbol "\".

#### Example

On drive **TNC:**\ the subdirectory AUFTR1 was created. Then, in the directory **AUFTR1** the directory NCPROG was created and the part program PROG1.H was copied into it. The part program now has the following path:

#### TNC:\AUFTR1\WCPROG\PROG1.H

The chart at right illustrates an example of a directory display with different paths.



# Overview: Functions of the expanded file manager

Function	Soft key
Copy (and convert) individual files	COPY  ABC  → XYZ
Display a specific file type	SELECT TYPE
Display the last 10 files that were selected	LAST FILES
Erase a file or directory	DELETE
Tag a file	TAG
Renaming a file	RENAME (ABC) = [XYZ]
Convert an FK program into HEIDENHAIN conversational format	CONVERT FK->H
Protect a file against editing and erasure	PROTECT
Cancel file protection	UNPROTECT
Network drive management (Ethernet option only)	NET
Copy a directory	COPY DIR
Display all the directories of a particular drive	ESHOW
Delete directory with all its subdirectories	DELETE DELETE

### Calling the file manager



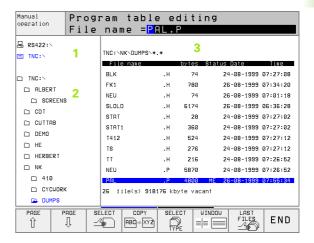
Press the PGM MGT key: The TNC displays the file management window (see figure at top right for default setting. If the TNC displays a different screen layout, press the WINDOW soft key.)

The narrow window at left shows three drives (1). If the TNC is connected to a network, it also displayed the connected network drives. Drives designate devices with which data are stored or transferred. One drive is the hard disk of the TNC. Other drives are the interfaces (RS232, RS422, Ethernet), which can be used, for example, to connect a personal computer. The selected (active) drive is shown in a different color.

In the lower part of the narrow window the TNC shows all directories (2) of the selected drive. A drive is always identified by a file symbol to the left and the directory name to the right. The TNC displays a subdirectory to the right of and below its parent directory. The selected (active) directory is depicted in a different color.

The wide window at right 3 shows you all of the files that are stored in the selected directory. Each file is shown with additional information that is illustrated in the table on the next page.

Display	Meaning
FILE NAME	Name with up to 16 characters and file type
ВҮТЕ	File size in bytes
STATUS	Properties of the file:
Е	Program is selected in the Programming and Editing mode of operation.
S	Program is selected in the Test Run mode of operation.
М	Program is selected in a program run operating mode.
Р	File is protected against editing and erasure.
DATE	Date the file was last changed
TIME	Time the file was last changed



## Selecting drives, directories and files



Call the file manager.

With the arrow keys or the soft keys, you can move the highlight to the desired position on the screen:





Move the highlight from the left to the right window, and vice versa.





Moves the highlight up and down within a window



Moves the highlight one page up or down within a window

1. step: Select a drive

Move the highlight to the desired drive in the left window:



Select a drive: Press the SELECT soft key or the ENT key

or



2. step: Select a directory

Move the highlight to the desired directory in the left window — the right window automatically shows all files stored in the highlighted directory.





Press the SELECT TYPE soft key.



Press the soft key for the desired file type, or



Press the SHOW ALL soft key to display all files, or







Use wild card characters, e.g. to show all files of the file type .H that begin with 4.

Move the highlight to the desired file in the right window



The selected file is opened in the operating mode from which you have the called file manager: Press SELECT soft key or the ENT key.



## Creating a new directory (only possible on the drive TNC:\)

Move the highlight in the left window to the directory in which you want to create a subdirectory.





Enter the new file name, and confirm with ENT.

#### Create \NEW directory?



Press the YES soft key to confirm, or



Abort with the NO soft key.

#### Copying a single file

Move the highlight to the file you wish to copy.



- Press the COPY soft key to select the copying function.
- ▶ Enter the name of the destination file and confirm your entry with the ENT key or EXECUTE soft key: The TNC copies the file into the active directory. The original file is retained, or
- ▶ Press the PARALLEL EXECUTE soft key to copy the file in the background. Copying in the background permits you to continue working while the TNC is copying. This can be useful if you are copying very large files that take a long time. While the TNC is copying in the background you can press the INFO PARALLEL EXECUTE soft key (under MORE FUNCTIONS, second soft-key row) to check the progress of copying.

#### Copying a table

If you are copying tables, you can overwrite individual lines or columns in the target table with the REPLACE FIELDS soft key. Prerequisites:

- The target table must exist.
- The file to be copied must only contain the columns or lines you want to replace.



The **REPLACE FIELDS** soft key does not appear when you want to overwrite the table in the TNC with an external data transfer software, such as TNCremoNT. Copy the externally created file into a different directory, and then copy the desired fields with the TNC file management.

#### Example

With a tool presetter you have measured the length and radius of 10 new tools. The tool presetter then generates the tool table TOOL.T with 10 lines (for the 10 tools) and the columns

- Tool number (column T)
- Tool length (column L)
- Tool radius (column R)

Copy this file to a directory other than the one containing the previous TOOL.T. If you wish to copy this file over the existing table using the TNC file management, the TNC asks if you wish to overwrite the existing TOOL.T tool table:

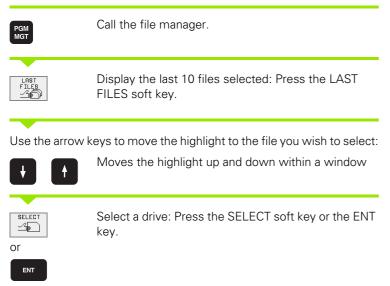
- ▶ If you press the YES soft key, the TNC will completely overwrite the current TOOL.T tool table. After this copying process the new TOOL.T table consists of 10 lines. The only remaining columns in the table are tool number, tool length and tool radius.
- Or, if you press the REPLACE FIELDS soft key, the TNC merely overwrites the first 10 lines of the columns number, length and radius in the TOOL.T file. The TNC does not change the data in the other lines and columns.

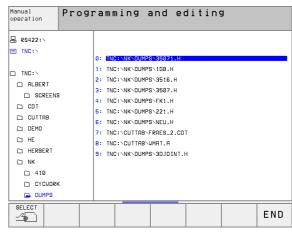


## Copying a directory

Move the highlight in the left window onto the directory you want to copy. Instead of the COPY soft key, press the COPY DIR soft key. Subdirectories are also copied at the same time.

### Choosing one of the last 10 files selected





## **Deleting a file**

Move the highlight to the file you want to delete.



- ➤ To select the erasing function, press the DELETE soft key. The TNC inquires whether you really intend to erase the file.
- ▶ To confirm, press the YES soft key;
- ▶ To abort erasure, press the NO soft key.

## **Deleting a directory**

- ▶ Delete all files and subdirectories stored in the directory that you wish to erase.
- Move the highlight to the directory you want to delete.



- ▶ To select the erasing function, press the DELETE soft key. The TNC inquires whether you really intend to erase the directory.
- ► To confirm, press the YES soft key;
- To abort erasure, press the NO soft key.



## **Tagging files**

Tagging fund	etions	Soft key
Tag a single f	ile	TAG FILE
Tag all files in	the directory	TAG ALL FILES
Untag a singl	e file	UNTAG FILE
Untag all files		UNTAG ALL FILES
Copy all tagg	ed files	COPY TAG
	s, such as copying or erasing files, ca es, but also for several files at once. ows:	
Move the high	light to the first file.	
TAG	To display the tagging functions, pkey.	ress the TAG soft
TAG FILE	Tag a file by pressing the TAG FIL	E soft key.
Move the high	light to the next file you wish to tag:	
TAG FILE	You can tag several files in this wa	ay, as desired.
COPY TAG	To copy the tagged files, press the key, or	COPY TAG soft
END DELETE	Delete the tagged files by pressing marking function, and then the DE tagged files.	

## Renaming a file

▶ Move the highlight to the file you want to rename.



- ▶ Select the renaming function.
- ▶ Enter the new file name; the file type cannot be changed.
- To execute renaming, press the ENT key.

#### **Additional Functions**

#### **Protect file / Cancel file protection**

Move the highlight to the file you want to protect.



▶ To select the additional functions, press the MORE FUNCTIONS soft key.



- ▶ To enable file protection, press the PROTECT soft key. The file now has status P.
- ▶ To cancel file protection, proceed in the same way using the UNPROTECT soft key.

## Converting an FK program into HEIDENHAIN conversational format

▶ Move the highlight to the file you want to convert.



➤ To select the additional functions, press the MORE FUNCTIONS soft key.



- ▶ To select the converting function, press the CONVERT FK->H soft key
- ▶ Enter the name of the destination file.
- To convert, press the ENT key.

#### Erase a directory together with all its subdirectories and files.

Move the highlight in the left window onto the directory you want to erase.



▶ To select the additional functions, press the MORE FUNCTIONS soft key.



- Press DELETE ALL to erase the directory together with its subdirectories.
- ▶ To confirm, press the YES soft key; To abort erasure, press the NO soft key.



## Data transfer to or from an external data medium



Before you can transfer data to an external data medium, you must setup the data interface(see "Setting the Data Interfaces" on page 422).



Call the file manager.



Select the screen layout for data transfer: press the WINDOW soft key. In the left half of the screen (1) the TNC shows all files saved on its hard disk. In the right half of the screen (2) it shows all files saved on the external data medium.

Use the arrow keys to highlight the file(s) that you want to transfer:





Moves the highlight up and down within a window





Moves the highlight from the left to the right window, and vice versa.

If you wish to copy from the TNC to the external data medium, move the highlight in the left window to the file to be transferred.

If you wish to copy from the external data medium to the TNC, move the highlight in the right window to the file to be transferred.



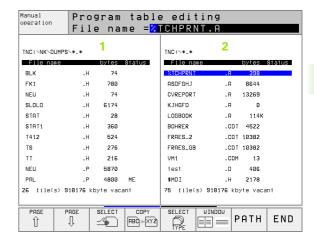
Transfer a single file: Press the COPY soft key, or



Transfer several files: Press the TAG soft key (in the second soft-key row, see "Tagging files," page 57), or



Transfer all files: Press the TNC => EXT soft kev.



Confirm with the EXECUTE or with the ENT key. A status window appears on the TNC, informing about the copying progress, or

If you wish to transfer more than one file or longer files, press the PARALLEL EXECUTE soft key. The TNC then copies the file in the background.



To end data transfer, move the highlight into left window and then press the WINDOW soft key. The standard file manager window is displayed again.



To select another directory, press the PATH soft key and then select the desired directory using the arrow keys and the ENTkey!

## Copying files into another directory

- ▶ Select the screen layout with the two equally sized windows.
- ▶ To display directories in both windows, press the PATH soft key.

In the right window

▶ Move the highlight to the directory into which you wish to copy the files, and display the files in this directory with the ENT key.

In the left window

Select the directory with the files that you wish to copy and press ENT to display them.



▶ Display the file tagging functions.



Move the highlight to the file you want to copy and tag it. You can tag several files in this way, as desired.



Copy the tagged files into the target directory.

Additional tagging functions: see "Tagging files," page 57

If you have marked files in the left and right windows, the TNC copies from the directory in which the highlight is located.

#### **Overwriting files**

If you copy files into a directory in which other files are stored under the same name, the TNC will ask whether the files in the target directory should be overwritten:

- To overwrite all files, press the YES soft key, or
- To overwrite no files, press the NO soft key, or
- To confirm each file separately before overwriting it, press the CONFIRM soft key.

If you wish to overwrite a protected file, this must also be confirmed or aborted separately.

## The TNC in a network (applies only for Ethernet interface option)



To connect the Ethernet card to your network, (see "Ethernet Interface" on page 427).

The TNC logs error messages during network operation(see "Ethernet Interface" on page 427).

If the TNC is connected to a network, the directory window 1 displays up to 7 drives (see figure at right). All the functions described above (selecting a drive, copying files, etc.) also apply to network drives, provided that you have been given the corresponding rights.

#### Connecting and disconnecting a network drive

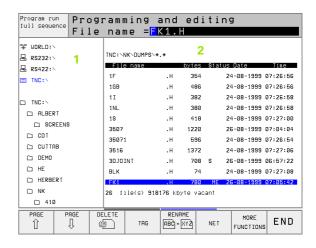


▶ To select the program management: Press the PGM MGT key. If necessary, press the WINDOW soft key to set up the screen as it is shown at the upper right.



▶ To manage the network drives: Press the NETWORK soft key (second soft-key row). In the right-hand window 2 the TNC shows the network drives available for access. With the following soft keys you can define the connection for each drive.

Function	Soft key
Establish network connection. If the connection is active, the TNC shows an <b>M</b> in the <b>Mnt</b> column. You can connect up to 7 additional drives with the TNC.	MOUNT DEVICE
Delete network connection	UNMOUNT DEVICE
Automatically establish network connection whenever the TNC is switched on. The TNC shows an <b>A</b> in the <b>Auto</b> column if the connection is established automatically.	AUTO MOUNT
Do not establish network connection automatically when the TNC is switched on.	NO AUTO MOUNT



It may take some time to mount a network device. At the upper right of the screen the TNC displays **[READ DIR]** to indicate that a connection is being established. The maximum data transmission rate lies between 200 and 1000 kilobaud, depending on the file type being transmitted.

#### Printing file with a network printer

If you have defined a network printer (see "Ethernet Interface" on page 427), you can print the files directly:

- ▶ To call the file manager, press the PGM MGT key.
- Move the highlight to the file you wish to print.
- ▶ Press the COPY soft key.
- ▶ Press the PRINT soft key: If you have define only one printer, the TNC will print the file immediately. If you have defined more than one printer, the TNC opens a window listing all defined printers. Use the arrow keys to select the desired printer, then press ENT

## 4.5 Creating and Writing Programs

## Organization of an NC program in HEIDENHAIN conversational format.

A part program consists of a series of program blocks. The figure at right illustrates the elements of a block.

The TNC numbers the blocks in ascending sequence.

The first block of a program is identified by **BEGIN PGM**, the program name and the active unit of measure.

The subsequent blocks contain information on:

- The workpiece blank
- Tool definitions, tool calls
- Feed rates and spindle speeds, as well as
- Path contours, cycles and other functions

The last block of a program is identified by **END PGM**, the program name and the active unit of measure.

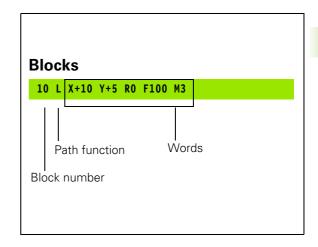
## Defining the blank form-BLK FORM

Immediately after initiating a new program, you define a cuboid workpiece blank. If you wish to define the blank at a later stage, press the BLK FORM soft key. This definition is needed for the TNC's graphic simulation feature. The sides of the workpiece blank lie parallel to the X, Y and Z axes and can be up to 100 000 mm long. The blank form is defined by two of its corner points:

- MIN point: the smallest X, Y and Z coordinates of the blank form, entered as absolute values.
- MAX point: the largest X, Y and Z coordinates of the blank form, entered as absolute or incremental values.



You only need to define the blank form if you wish to run a graphic test for the program!



### Creating a new part program

You always enter a part program in the **Programming and Editing** mode of operation. Program initiation in an example:



Select the **Programming and Editing** mode of operation.



To call the file manager, press the PGM MGT key.

Select the directory in which you wish to store the new program

#### File name = OLD.H



Enter the new program name and confirm your entry with the ENT key.



To select the unit of measure, press the MM or INCH soft key. The TNC switches the screen layout and initiates the dialog for defining the **BLK-FORM**.

#### Working spindle axis X/Y/Z ?

Enter the spindle axis.

#### Def BLK FORM: Min-corner ?

0 ENT

Enter in sequence the X, Y and Z coordinates of the MIN point.

0

ENT

ENT

-40

#### Def BLK FORM: MAX-corner ?

100 ENT

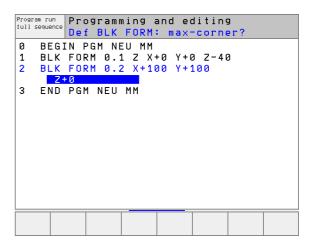
Enter in sequence the X, Y and Z coordinates of the MAX point.

100

ENT

0

ENT



#### **Example: Display the BLK form in the NC program.**

O BEGIN PGM NEW MM	Program begin, name, unit of measure	
1 BLK FORM 0.1 Z X+0 Y+0 Z-40	Spindle axis, MIN point coordinates	
2 BLK FORM 0.2 X+100 Y+100 Z+0	MAX point coordinates	
3 END PGM NEW MM	Program end, name, unit of measure	

The TNC automatically generates the block numbers as well as the  ${\bf BEGIN}$  and  ${\bf END}$  blocks.



If you do not wish to define a blank form, cancel the dialog at **Working spindle axis X/Y/Z** by pressing the DEL key!

The TNC can display the graphic only if the ratio of the short side to the long sides of the **BLK FORM** is greater than 1:64!

## Programming tool movements in conversational format

To program a block, initiate the dialog by pressing a function key. In the screen headline, the TNC then asks you for all the information necessary to program the desired function.

#### Example of a dialog



Dialog initiation

#### Coordinates ?



Enter the target coordinate for the X axis.





Enter the target coordinate for the Y axis, and go to the next question with ENT.

#### Radius comp. RL/RR/no comp. ?



Enter "No radius compensation" and go to the next question with ENT.

#### Feed rate F=? / F MAX = ENT

100



Enter a feed rate of 100 mm/min for this path contour; go to the next question with ENT.

#### Miscellaneous function M ?

3

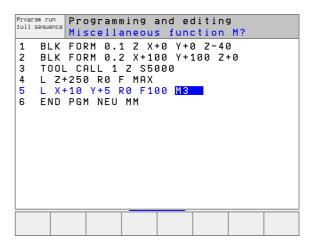


Enter the miscellaneous function **M3** "spindle ON"; pressing the ENT key will terminate this dialog.

The program blocks window will display the following line:

#### 3 L X+10 Y+5 R0 F100 M3

Functions for setting the feed rate	Soft key
Rapid traverse	F MAX
Traverse feed rate automatically calculated in TOOL CALL	F AUTO





Function	Key
Ignore the dialog question	NO
End the dialog immediately	END
Abort the dialog and erase the block	DEL.

## **Editing a program**

While you are creating or editing a part program, you can select any desired line in the program or individual words in a block with the arrow keys or the soft keys:

Function	Soft keys/keys
Go to the previous page	PAGE
Go to the next page	PAGE
Go to beginning of program	BEGIN
Go to end of program	END
Move from one block to the next	+ +
Select individual words in a block	<b>- -</b>
Function	Key
Set the selected word to zero	CE
Erase an incorrect number	CE
Clear a (non-blinking) error message	CE
Delete the selected word	NO
Delete the selected block	DEL 🗆

Function Key

Erase cycles and program sections: First select the last block of the cycle or program section to be erased, then erase with the DEL key.



#### Inserting blocks at any desired location

Select the block after which you want to insert a new block and initiate the dialog.

#### Editing and inserting words

- Select a word in a block and overwrite it with the new one. The plainlanguage dialog is available while the word is highlighted.
- To accept the change, press the END key.

If you want to insert a word, press the horizontal arrow key repeatedly until the desired dialog appears. You can then enter the desired value.

#### Looking for the same words in different blocks

Set the AUTO DRAW soft key to OFF.



To select a word in a block, press the arrow keys repeatedly until the highlight is on the desired word.



Select a block with the arrow keys.

The word that is highlighted in the new block is the same as the one you selected previously.

#### Finding any text

- To select the search function, press the FIND soft key. The TNC displays the dialog prompt Find text:
- ▶ Enter the text that you wish to find.
- ▶ To find the text, press the EXECUTE soft key.



#### Marking, copying, deleting and inserting program sections

The TNC provides certain functions for copying program sections within an NC program or into another NC program—see the table at right.

To copy a program section, proceed as follows:

- ▶ Select the soft-key row using the marking function.
- ▶ Select the first (last) block of the section you wish to copy.
- ▶ To mark the first (last) block: Press the SELECT BLOCK soft key. The TNC then highlights the first character of the block and superimposes the soft key CANCEL SELECTION.
- ▶ Move the highlight to the last (first) block of the program section you wish to copy or delete. The TNC shows the marked blocks in a different color. You can end the marking function at any time by pressing the CANCEL SELECTION soft key.
- ▶ To copy the selected program section: Press the COPY BLOCK soft key, and to delete the selected section: Press the DELETE BLOCK soft key. The TNC stores the selected block.
- ▶ Using the arrow keys, select the block after which you wish to insert the copied (deleted) program section.



To insert the section into another program, select the corresponding program using the File Manager and then mark the block after which you wish to insert the copied block.

▶ To insert the block: Press the INSERT BLOCK soft key.

Function	Soft key
Switch on marking function	SELECT BLOCK
Switch off marking function	CANCEL SELECTION
Delete marked block	DELETE
Insert block that is stored in the buffer memory	INSERT BLOCK
Copy marked block	BLOCK

# 4.6 Interactive Programming Graphics

## To generate/not generate graphics during programming:

While you are writing the part program, you can have the TNC generate a 2-D pencil-trace graphic of the programmed contour.

▶ To switch the screen layout to displaying program blocks to the left and graphics to the right, press the SPLIT SCREEN key and PGM + GRAPHICS soft key.



Set the AUTO DRAW soft key to ON. While you are entering the program lines, the TNC generates each path contour you program in the graphics window in the right screen half.

If you do not wish to have graphics generated during programming, set the AUTO DRAW soft key to OFF.

Even when AUTO DRAW is switched ON, graphics are not generated for program section repeats.

## Generating a graphic for an existing program

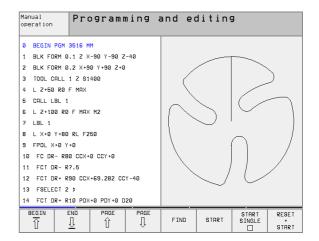
▶ Use the arrow keys to select the block up to which you want the graphic to be generated, or press GOTO and enter the desired block number.



▶ To generate graphics, press the RESET + START soft kev.

#### Additional functions:

Function	Soft key
Generate a complete graphic	RESET + START
Generate interactive graphic blockwise	START SINGLE
Generate a complete graphic or complete it after RESET + START	START
Stop the programming graphics. This soft key only appears while the TNC generates the interactive graphics	STOP



## **Block number display ON/OFF**



▶ Shift the soft-key row (see figure at upper right).



- ➤ To show block numbers: Set the SHOW OMIT BLOCK NR. soft key to SHOW.
- To show block numbers: Set the SHOW OMIT BLOCK NR. soft key to OMIT.

## To erase the graphic:



CLEAR

GRAPHICS

- ▶ Shift the soft-key row (see figure at upper right).
- ▶ Delete graphic: Press CLEAR GRAPHIC soft key.

## Magnifying or reducing a detail

You can select the graphics display by selecting a detail with the frame overlay. You can now magnify or reduce the selected detail.

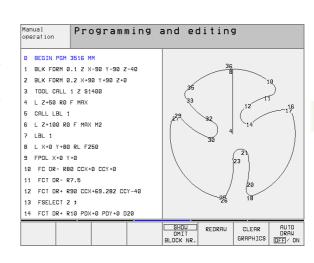
Select the soft-key row for detail magnification/reduction (second row, see figure at center right).

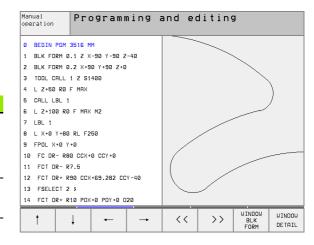
The following functions are available:

Function	Soft key
Show and move the frame overlay. Press and hold the desired soft key to move the frame overlay.	<ul><li>←</li></ul>
Reduce the frame overlay — press and hold the soft key to reduce the detail	<<
Enlarge the frame overlay — press and hold the soft key to magnify the detail	>>

WINDOW DETAIL ► Confirm the selected area with the WINDOW DETAIL soft key.

With the WINDOW BLK FORM soft key, you can restore the original section.





## 4.7 Structuring Programs

### **Definition and applications**

This TNC function enables you to comment part programs in structuring blocks. Structuring blocks are short texts with up to 244 characters and are used as comments or headlines for the subsequent program lines.

With the aid of appropriate structuring blocks, you can organize long and complex programs in a clear and comprehensible way.

This function is particularly convenient if you want to change the program later. Structuring blocks can be inserted into the part program at any point. They can also be displayed in a separate window, and edited or added to, as desired. A second level is provided for subdividing a structuring block: the TNC indents texts in the second level.

## To display the program structure window / change the active window:

PGM + SECTS To display the program structure window, select the screen display PGM+SECTS.



To change the active window, press the CHANGE WINDOW soft key.

## To insert a structuring block in the (left) program window

▶ Select the block after which the structuring block is to be inserted.



- ▶ Press the INSERT SECTION soft key.
- Enter the structuring text with the alphabetic keyboard.
- To switch levels: Press the CHANGE LEVEL soft key.

## To insert a structuring block in the (right) structure window

- Select the structuring block after which the new block is to be inserted.
- Enter the text with the alphabetic keyboard the TNC automatically inserts the new block.

## Selecting blocks in the program structure window

If you are scrolling through the program structure window block by block, the TNC at the same time automatically moves the corresponding NC blocks in the program window. This way you can quickly skip large program sections.

	nual eration	Pro	gramı	ning a	and ed	diting	3	
1	BLK FO	RM 0.1 Z X	+0 Y+0 Z-4	0	BEGIN PGM	I 1GB		
2	BLK FO	RM 0.2 X+1	00 Y+100 Z	+0	- Make hole pattern ID 27943KL1			
3	* - Mai	ke hole pa	ttern ID 2	7943KL1	- Parameter definition			
4	TOOL C	ALL 1 Z S4	500		- Make pocket			
5	CYCL D	EF 262 THR	EAD MILLIN	G	- Rough out			
	0335=	10 \$NOMI	NAL DIAMET	ER	- Finishing			
Q239=+1.5 \$THREAD PITCH			- Make hole pattern					
Q201=-18 \$DEPTH OF THREAD			- Center drill					
Q355=0 \$THREADS PER STEP			- Pecking					
Q253=750 \$F PRE-POSITIONING			- Tapping					
Q351=+1			END PGM 1	GB				
	0200=	2 SET-	UP CLEARAN	CE				
	Q203=	+0 \$SURF	ACE COORDI	NATE				
	Q204=50 \$2ND SET-UP CLEARANCE							
0207=500 3FEED RATE FOR MILLING								
E	EG IN	END	PAGE	PAGE	FIND			CHANGE WINDOW

## 4.8 Adding Comments

#### **Function**

You can add comments to any desired block in the part program to explain program steps or make general notes. There are three possibilities to add comments:

### **Entering comments during programming**

- Enter the data for a program block, then press the semicolon key ";" on the alphabetic keyboard—the TNC displays the dialog prompt COMMENT?
- Enter your comment and conclude the block by pressing the END key.

## Inserting comments after program entry

- ▶ Select the block to which a comment is to be added.
- ► Select the last word in the block with the right arrow key:
  A semicolon appears at the end of the block and the TNC displays the dialog prompt **COMMENT?**
- Enter your comment and conclude the block by pressing the END key.

### Entering a comment in a separate block

- ▶ Select the block after which the comment is to be inserted.
- Initiate the programming dialog with the semicolon key ";" on the alphabetic keyboard.
- ► Enter your comment and conclude the block by pressing the END key.

```
Programming and editing
   RND R1
  FC DR+ R2.5 CLSD+
10
   FLT AN+180.925
   FCT DR+ R10.5 CCX+0 CCY+0
    ; USE SOLUTION 1
13
    FSELECT 1
14
    FLT AN+269.025
15
   RND R2.5
   FL AN+0.975
17
   FCT DR+ R10.5 CCX+0 CCY+0
18
   FLT AN+89.025
19
    FCT DR+ R2.5 CLSD-
   END PGM 35071 MM
```

## 4.9 Creating Text Files

### **Function**

You can use the TNC's text editor to write and edit texts. Typical applications:

- Recording test results
- Documenting working procedures
- Creating formularies

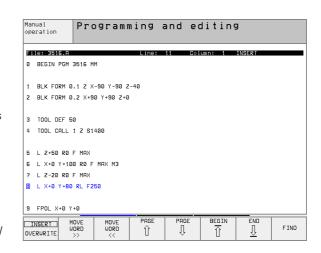
Text files are type .A files (ASCII files). If you want to edit other types of files, you must first convert them into type .A files.

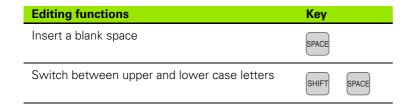
## Opening and exiting text files

- ▶ Select the Programming and Editing mode of operation.
- To call the file manager, press the PGM MGT key.
- ▶ To display type .A files, press the SELECT TYPE and then the SHOW .A soft keys.
- ▶ Select a file and open it with the SELECT soft key or ENT key, or create a new file by entering the new file name and confirming your entry with the ENT key.

To leave the text editor, call the file manager and select a file of a different file type, for example a part program.

Cursor movements	Soft key
Move one word to the right	MOVE WORD >>
Move one word to the left	MOVE WDRD <<
Go to the next screen page	PAGE
Go to the previous screen page	PAGE
Go to beginning of file	BEGIN
Go to end of file	END
Editing functions	Key
Begin a new line	RET
Erase the character to the left of the cursor	(x)





## **Editing texts**

The first line of the text editor is an information headline which displays the file name, and the location and writing mode of the cursor:

File: Name of the text file

Line:Line in which the cursor is presently locatedColumn:Column in which the cursor is presently locatedINSERT:Insert new text, pushing the existing text to the rightOVERWRITE:Write over the existing text, erasing it where it is

replaced with the new text.

The text is inserted or overwritten at the location of the cursor. You can move the cursor to any desired position in the text file by pressing the arrow keys.

The line in which the cursor is presently located is depicted in a different color. A line can have up to 77 characters. To start a new line, press the RET key or the ENT key.

## Erasing and inserting characters, words and lines

With the text editor, you can erase words and even lines, and insert them at any desired location in the text.

- Move the cursor to the word or line you wish to erase and insert at a different place in the text.
- ▶ Press the DELETE WORD or DELETE LINE soft key: The text is put in the buffer memory
- Move the cursor to the location where you wish insert the text, and press the RESTORE LINE/WORD soft key.

Function	Soft key
Delete and temporarily store a line	DELETE LINE
Delete and temporarily store a word	DELETE WORD
Delete and temporarily store a character	DELETE CHAR
Insert a line or word from temporary storage	INSERT LINE / WORD

### **Editing text blocks**

You can copy and erase text blocks of any size, and insert them at other locations. Before carrying out any of these editing functions, you must first select the desired text block:

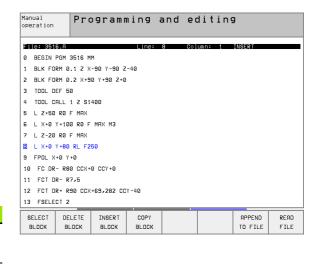
▶ To select a text block, move the cursor to the first character of the text you wish to select.



- ▶ Press the SELECT BLOCK soft key.
- Move the cursor to the last character of the text you wish to select. You can select whole lines by moving the cursor up or down directly with the arrow keys the selected text is shown in a different color.

After selecting the desired text block, you can edit the text with the following soft keys:

Function	Soft key
Delete the selected text and store temporarily	DELETE BLOCK
Store marked block temporarily without erasing (copy )	INSERT BLOCK



If necessary, you can now insert the temporarily stored block at a different location

Move the cursor to the location where you want to insert the temporarily stored text block.



Press the INSERT BLOCK soft key: The text block is inserted.

You can insert the temporarily stored text block as often as desired.

#### To transfer the selected text to a different file:

▶ Select the text block as described previously.



- ▶ Press the APPEND TO FILE soft key. The TNC displays the dialog prompt **Destination file** =
- ▶ Enter the path and name of the target file. The TNC appends the selected text to the end of the specified file. If no target file with the specified name is found, the TNC creates a new file with the selected text.

#### To insert another file at the cursor position:

Move the cursor to the location in the text where you wish to insert another file.



- Press the READ FILE soft key. The TNC displays the dialog prompt File name =
- ▶ Enter the path and name of the file you want to insert.

## Finding text sections

With the text editor, you can search for words or character strings in a text. Two functions are available:

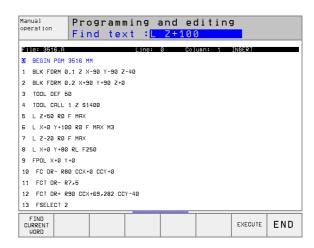
#### Finding the current text

The search function is to find the next occurrence of the word in which the cursor is presently located:

- Move the cursor to the desired word.
- ▶ To select the search function, press the FIND soft key.
- ▶ Press the FIND CURRENT WORD soft key.
- To leave the search function, press the END soft key.

#### Finding any text

- To select the search function, press the FIND soft key. The TNC displays the dialog prompt Find text:
- ▶ Enter the text that you wish to find.
- To find the text, press the EXECUTE soft key.
- To leave the search function, press the END soft key.



## 4.10 Integrated Pocket Calculator

## Operation

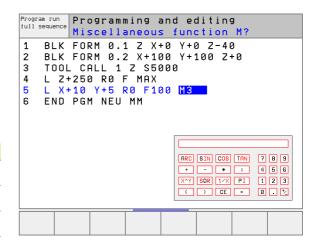
The TNC features an integrated pocket calculator with the basic mathematical functions.

With the CALC key you can open and close an additional window for calculations. You can move the window to any desired location on the TNC screen with the arrow keys.

The calculator is operated with short commands through the alphabetic keyboard. The commands are shown in a special color in the calculator window:

Mathematical function	Command (key)
Addition	+
Subtraction	-
Multiplication	*
Division	:
Sine	S
Cosine	С
Tangent	Т
Arc sine	AS
Arc cosine	AC
Arc tangent	AT
Powers	٨
Square root	Q
Inversion	1
Parenthetic calculations	()
p (3.14159265359)	Р
Display result	=

If you are writing a program and the programming dialog is active, you can use the actual-position-capture key to transfer the result to the highlight position in the current block.



# 4.11 Immediate Help for NC Error Messages

#### Displaying error messages

The TNC automatically generates error messages when it detects problems such as

- Incorrect data input
- Logical errors in the program
- Contour elements that are impossible to machine
- Incorrect use of the touch probe system

An error message that contains a program block number was caused by an error in the indicated block or in the preceding block. The TNC error messages can be canceled with the CE key, after the cause of the error has been removed.

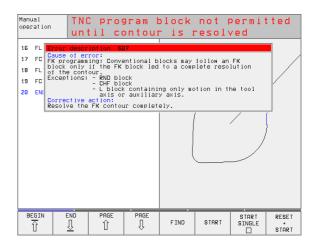
If you require more information on a particular error message, press the HELP key. A window is then superimposed where the cause of the error is explained and suggestions are made for correcting the error.

## **Display HELP**



- ▶ To display Help, press the HELP key.
- Read the description of the error and the possibilities for correcting it. Close the Help window with the CE, thus canceling the error message.
- Remove the cause of the error as described in the Help window.

The TNC displays the Help text automatically if the error message is flashing. The TNC needs to be restarted after blinking error messages. To restart the TNC, press the END key and hold for two seconds.



## 4.12 Pallet Management

## **Application**



Pallet table management is a machine-dependent function. The standard functional range will be described in the following. Refer to your machine manual for more information.

Pallet tables are used for machining centers with pallet changer: The pallet table calls the part programs that are required for the different pallets, and activates datum shifts or datum tables.

You can also use pallet tables to run in succession several programs that have different datums.

Pallet tables contain the following information:

- PAL/PGM (entry obligatory):
  - Identification for pallet or NC program (select with ENT or NO ENT)
- NAME (entry obligatory):

Pallet or program name. The machine tool builder determines the pallet name (see Machine Manual). The program name must be stored in the same directory as the pallet table. Otherwise you must enter the full path name for the program.

- DATUM (entry optional):
  - Name of the datum table. The datum table must be stored in the same directory as the pallet table. Otherwise you must enter the full path name for the datum table. Datums from the datum table can be activated in the NC program with Cycle 7 **DATUM SHIFT.**
- **X, Y, Z** (entry optional, other axes also possible):

For pallet names, the programmed coordinates are referenced to the machine datum. For NC programs, the programmed coordinates are referenced to the pallet datum. These entries overwrite the datum that you last set in the Manual mode of operation. With the miscellaneous function M104 you can reactivate the datum that was last set. With the actual-position-capture key, the TNC opens a window that enables you to have the TNC enter various points as datums (see table below):

Position	Meaning
Actual values	Enter the coordinates of the current tool position relative to the active coordinate system.
Reference values	Enter the coordinates of the current tool position relative to the machine datum.
ACTL measured values	Enter the coordinates relative to the active coordinate system of the datum last probed in the Manual operating mode.
<b>REF</b> measured values	Enter the coordinates relative to the machine datum of the datum last probed in the Manual operating mode.

Manua! operat	anual Program table editing Pallet=PAL / NC program=PGM							
Fil	e: PAL.F							>>
NR	PAL/F	GM NAM	E					
0	PAL	123	59					
1	PGM	TNC	TNC:\DRILL\PA35.H					
2	PGM	TNC	TNC:\DRILL\PA36.H					
3	PGM	TNC	TNC:\MILL\SLII35.I					
4	PGM	TNC	TNC:\MILL\FK35.H					
5	PAL	123	123510					
6	PGM	TNC:\DRILL\QST35.H						
7	PGM	TNC:\DRILL\K15.I						
8	PAL	123511						
9	PGM	TNC:\CYCLE\MILLING\C210.H						
10	PGM	TNC:\DRILL\K17.H						
11								
12								
BEG	IN	END	PAGE	PAGE	INSERT	DELETE	NEXT	APPEN
- ÎÎ		Įļ.	Î	↓↓	LINE	LINE	LINE	N LINE

With the arrow keys and ENT, select the position that you wish to confirm. Then press the ALL VALUES soft key so that the TNC saves the respective coordinates of all active axes in the pallet table. With the PRESENT VALUE soft key, the TNC saves the coordinates of the axis on which the highlight in the pallet table is presently located.



If you have not defined a pallet before an NC program, the programmed coordinates are then referenced to the machine datum. If you do not define an entry, the datum that was set manually remains active.

Editing function	Soft key
Select beginning of table	BEGIN
Select end of table	END
Select previous page in table	PAGE
Select next page in table	PAGE
Insert the last line in the table	INSERT LINE
Delete the last line in the table	DELETE LINE
Go to the beginning of the next line	NEXT LINE
Add the entered number of lines to the end of the table	APPEND N LINES
Copy the highlighted field (2nd soft-key row)	COPY FIELD
Insert the copied field (2nd soft-key row)	PASTE FIELD

### Selecting a pallet table

- ▶ Call the file manager in the Programming and Editing or Program Run mode: Press the PGM MGT key.
- Display all type .P files: Press the soft keys SELECT TYPE and SHOW .P.
- Select a pallet table with the arrow keys, or enter a new file name to create a new table.
- Confirm your entry with the ENT key.

### To leave the pallet file:

- To call the file manager, press the PGM MGT soft key.
- To select a different type of file, press the SELECT TYPE soft key and the soft key for the desired file type, for example SHOW.H.
- ▶ Select the desired file.

## **Executing the pallet file**



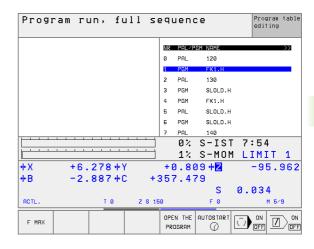
In machine parameter 7683, set whether the pallet table is to be executed blockwise or continuously (see "General User Parameters" on page 448).

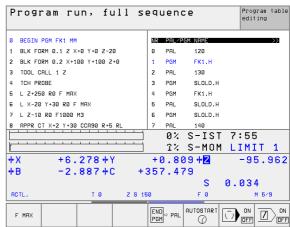
- Select the file manager in the operating mode Program Run, Full Sequence or Program Run, Single Block: Press the PGM MGT key.
- Display all type .P files: Press the soft keys SELECT TYPE and SHOW .P.
- ▶ Select pallet table with the arrow keys and confirm with ENT.
- ▶ To execute pallet table: Press the NC Start button. The TNC executes the pallets as set in Machine Parameter 7683.

#### Screen layout for executing pallet tables

You can have the TNC display the program contents and pallet file contents on the screen together by selecting the screen layout PGM + PALLET. During execution, the TNC then shows program blocks to the left and the pallet to the right. To check at the program contents before execution, proceed as follows:

- ▶ Select a pallet table.
- ▶ With the arrow keys, choose the program you would like to check.
- ▶ Press the OPEN PGM soft key: The TNC displays the selected program on the screen. You can now page through the program with the arrow keys.
- ▶ To return to the pallet table, press the END PGM soft key.





## 4.13 Pallet Operation with Tool-Oriented Machining

#### **Application**



Pallet management in combination with tool-oriented machining is a machine-dependent function. The standard functional range will be described in the following. Refer to your machine manual for more information.

Pallet tables are used for machining centers with pallet changer: The pallet table calls the part programs that are required for the different pallets, and activates datum shifts or datum tables.

You can also use pallet tables to run in succession several programs that have different datums.

Pallet tables contain the following information:

#### ■ PAL/PGM (entry obligatory):

The entry **PAL** identifies the pallet, **FIX** marks the fixture plane and **PGM** is used to enter the workpiece.

#### ■ W-STATE:

Current machining status. The machining status is used to determine the current stage of machining. Enter **BLANK** for an unmachined (raw) workpiece. During machining, the TNC changes this entry to **INCOMPLETE**, and after machining has finished, to **ENDED.** The entry **EMPTY** is used to identify a space at which no workpiece is to be clamped or where no machining is to take place.

#### ■ METHOD (entry obligatory):

Entry which determines the method of program optimization. Machining is workpiece-oriented if **WPO** is entered. Machining of the piece is tool-oriented if **TO** is entered. In order to include subsequent workpieces in the tool-oriented machining, you must enter **CTO** (continued tool oriented). Tool-oriented machining is also possible with pallet fixtures, but not for multiple pallets.

#### ■ NAME (entry obligatory):

Pallet or program name. The machine tool builder determines the pallet name (see Machine Manual). Programs must be stored in the same directory as the pallet table. Otherwise you must enter the full path name for the program.

Manual operation						edi PROGE		a M	
Fil	PALLET=PAL / PROGRAM=PGM								
NR		GM W-S	TATE	METHOD	NAM	E			
0	PAL				PAL	4-208-11			
1	FIX								
2	PGM	BLA	NK	СТО	TNC	: RK TEST	442AAU77.H		
3	PGM	BLA	NK	СТО	TNC	:\RK\TEST\	442AAU77.H		
4	PGM	BLA	NK	СТО	TNC	:\RK\TEST\	448AAU77.H		
5	FIX								
6	PGM	BLA	NK	TO	TNC	: RK TEST	863FFV52.H		
7	PGM	BLA	NK	CTO	TNC	: RK TEST	863FFV52.H		
8	PGM	BLA	NK	CTO	TNC	: \RK\TEST\	863FFV52.H		
9	PGM	BLA	NK	CTO	TNC	: \RK\TEST\	863FFV52.H		
10	PGM	BLA	NK	WP0	TNC	: \RK\TEST\	862LLU77.H		
11	PGM	BLA	NK	WPO	TNC	: \RK\TEST\	862LLU77.H		
12	FIX								
BEG	IN	END	PAGE	PAC	ìΕ	INSERT	DELETE	NEXT	APPEN
Î		<u>₩</u>	Û	1)		LINE	LINE	LINE	N LINE

#### ■ **DATUM** (entry optional):

Name of the datum table. The datum table must be stored in the same directory as the pallet table. Otherwise you must enter the full path name for the datum table. Datums from the datum table can be activated in the NC program with Cycle 7 **DATUM SHIFT.** 

■ X, Y, Z (entry optional, other axes also possible):
For pallets and fixtures, the programmed coordinates are referenced to the machine datum. For NC programs, the programmed coordinates are referenced to the pallet or fixture datum. These entries overwrite the datum that you last set in the Manual mode of operation. With the miscellaneous function M104 you can reactivate the datum that was last set. With the actual-position-capture key, the TNC opens a window that enables you to have the TNC enter various points as datums (see table below):

Position	Meaning
Actual values	Enter the coordinates of the current tool position relative to the active coordinate system.
Reference values	Enter the coordinates of the current tool position relative to the machine datum.
<b>ACTL</b> measured values	Enter the coordinates relative to the active coordinate system of the datum last probed in the Manual operating mode.
REF measured values	Enter the coordinates relative to the machine datum of the datum last probed in the Manual operating mode.

With the arrow keys and ENT, select the position that you wish to confirm. Then press the ALL VALUES soft key so that the TNC saves the respective coordinates of all active axes in the pallet table. With the PRESENT VALUE soft key, the TNC saves the coordinates of the axis on which the highlight in the pallet table is presently located.



If you have not defined a pallet before an NC program, the programmed coordinates are then referenced to the machine datum. If you do not define an entry, the datum that was set manually remains active.

■ SP-X, SP-Y, SP-Z (entry optional, other axes also possible):
Safety positions can be entered for the axes. These positions can be read with SYSREAD FN18 ID510 NR 6 from NC macros. SYSREAD FN18 ID510 NR 5 can be used to determine if a value was programmed in the column. The positions entered are only approached if these values are read and correspondingly programmed in the NC macros.

#### ■ CTID (entered by the TNC):

The context ID number is assigned by the TNC and contains instructions about the machining progress. Machining cannot be resumed if the entry is deleted or changed.

resurrice in the entry is deleted of changed.	
Editing function in table mode	Soft key
Select beginning of table	BEGIN
Select end of table	<u>∏</u>
Select previous page in table	PAGE Û
Select next page in table	PAGE
Insert the last line in the table	INSERT LINE
Delete the last line in the table	DELETE LINE
Go to the beginning of the next line	NEXT LINE
Add the entered number of lines to the end of the table	APPEND N LINES
Copy the highlighted field (2nd soft-key row)	COPY FIELD
Insert the copied field (2nd soft-key row)	PASTE FIELD
Editing function in entry-form mode	Soft key
Select previous pallet	PALLET
Select next pallet	PALLET
Select previous fixture	FIXTURE
Select next fixture	FIXTURE
Select previous workpiece	WORKPIECE Î
Select next workpiece	PALLET

Editing function in entry-form mode	Soft key
Switch to pallet plane	VIEW PALLET PLANE
Switch to fixture plane	VIEW FIXTURE PLANE
Switch to workpiece plane	VIEW WORKPIECE PLANE
Select standard pallet view	PALLET DETAIL PALLET
Select detailed pallet view	PALLET DETAIL PALLET
Select standard fixture view	FIXTURE DETAIL FIXTURE
Select detailed fixture view	FIXTURE DETRIL FIXTURE
Select standard workpiece view	WORKPIECE DETAIL WORKPIECE
Select detailed workpiece view	WORKPIECE DETAIL WORKPIECE
Insert pallet	INSERT PALLET
Insert fixture	INSERT FIXTURE
Insert workpiece	INSERT WORKPIECE
Delete pallet	DELETE PALLET
Delete fixture	DELETE FIXTURE
Delete workpiece	DELETE WORKPIECE
Copy all fields to clipboard	COPY ALL FIELDS
Copy highlighted field to clipboard	COPY SELECTED FIELD
Insert the copied field	PASTE FIELDS
Delete clipboard contents	ERASE INTERMED. MEMORY

Editing function in entry-form mode	Soft key
Tool-optimized machining	WORKPIECE ORIENTAT.
Workpiece-optimized machining	TOOL ORIENTAT.
Connecting or separating the types of machining	CONNECT/ DIS- CONNECT
Mark plane as being empty	EMPTY POSITION
Mark plane as being unmachined	BLANK

#### Selecting a pallet file

- Call the file manager in the Programming and Editing or Program Run mode: Press the PGM MGT kev.
- Display all type .P files: Press the soft keys SELECT TYPE and SHOW .P.
- Select a pallet table with the arrow keys, or enter a new file name to create a new table.
- Confirm your entry with the ENT key.

#### Setting up the pallet file with the entry form

Pallet operation with tool- or workpiece-oriented machining is divided into three planes:

- Pallet plane PAL
- Fixture plane **FIX**
- Workpiece plane **PGM**

You can switch to a detail view in each plane. Set the machining method and the pallet, fixture and workpiece statuses in the standard view. If you are editing an existing pallet file, the updated entries are displayed. Use the detail view for setting up the pallet file.

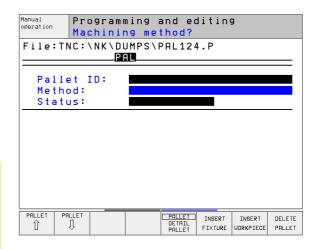


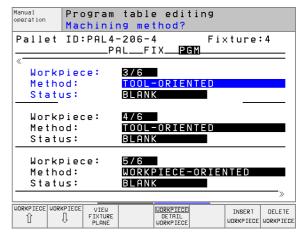
Set up the pallet file according to the machine configuration. If you only have one fixture with multiple workpieces, then defining one fixture FIX with the workpieces PGM is sufficient. However, if one pallet contains several fixtures, or if a fixture is machined from more than one side, you must define the pallet PAL with the corresponding fixture planes FIX.

Use the screen layout button to switch between table view and form view.

Graphic support for form entry is not yet available.

The various planes of the entry form can be reached with the appropriate soft keys. The current plane is highlighted in the status line of the entry form. When you switch to table view with the screen layout button, the cursor is placed in the same plane as it was in the form view.





#### Setting up the pallet plane

- Pallet Id: The pallet name is displayed
- Method: You can choose between the WORKPIECE ORIENTED and TOOL ORIENTED machining methods. The selected method is assumed for the workpiece plane and overwrites any existing entries. In tabular view, WORKPIECE ORIENTED appears as WPO, and TOOL ORIENTED appears as TO.



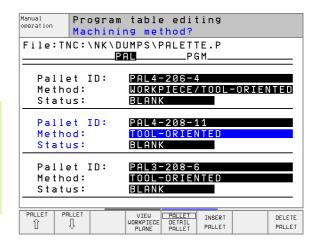
The TO-/WP-ORIENTED entry cannot be made via soft key. It only appears when different machining methods were chosen for the workpieces in the workpiece or machining plane.

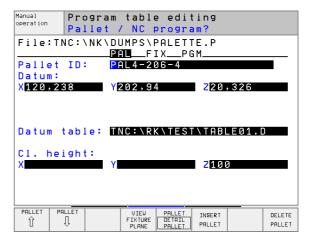
If the machining method was determines in the fixture plane, the entries are carried over to the workpiece plane, where they overwrite any existing entries.

■ Status: The soft key BLANK identifies the pallet and the corresponding fixtures and workpieces as not yet having been machined, and enters BLANK in the Status field. Use the soft key EMPTY POSITION if you want to skip the pallet during machining. EMPTY appears in the Status field.

#### Setting up details in the pallet plane

- Pallet ID: Enter the pallet name
- Datum: Enter the pallet datum
- **Datum table:** Enter the name and path of the datum table of the workpiece. The data is carried over to the fixture and workpiece planes.
- Safe height: (optional): Safe position for the individual axes referenced to the pallet. The positions entered are only approached if these values were read and correspondingly programmed in the NC macros.





#### Setting up the fixture plane

- **Fixture:** The number of the fixture is displayed. The number of fixtures within this plane is shown after the slash.
- Method: You can choose between the WORKPIECE ORIENTED and TOOL ORIENTED machining methods. The selected method is assumed for the workpiece plane and overwrites any existing entries. In tabular view, entry WORKPIECE ORIENTED appears as WPO, and TOOL ORIENTED appears as TO.

Use the **CONNECT/SEPARATE** soft key to mark fixtures that are to be included for calculating the machining process for tool-oriented machining. Connected fixtures are marked with a dashed line, whereas separated fixtures are connected with a solid line. Connected workpieces are marked in tabular view with the entry **CTO** in the METHOD column.



The TO-/WP-ORIENTED entry cannot be made via soft key. It only appears when different machining methods were chosen for the workpieces in the workpiece plane.

If the machining method was determines in the fixture plane, the entries are carried over to the workpiece plane, where they overwrite any existing entries.

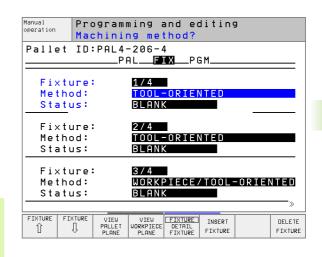
■ Status: The soft key BLANK identifies the fixture and the corresponding workpieces as not yet having been machined, and enters BLANK in the Status field. Use the soft key EMPTY POSITION if you want to skip the fixture during machining. EMPTY appears in the Status field.

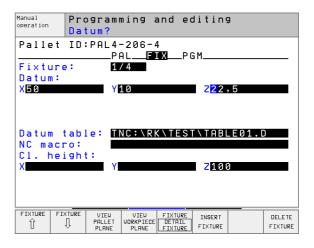
#### Setting up details in the fixture plane

- **Fixture:** The number of the fixture is displayed. The number of fixtures within this plane is shown after the slash.
- Datum: Enter the fixture datum
- **Datum table:** Enter the name and path of the datum table valid for machining the workpiece. The data is carried over to the workpiece plane.
- NC macro: In tool-oriented machining, the macro TCTOOLMODE is carried out instead of the normal tool-change macro.
- Safe height: (optional): Safe position for the individual axes referenced to the fixture.



Safety positions can be entered for the axes. These positions can be read with SYSREAD FN18 ID510 NR 6 from NC macros. SYSREAD FN18 ID510 NR 5 can be used to determine if a value was programmed in the column. The positions entered are only approached if these values are read and correspondingly programmed in the NC macros.







#### Setting up the workpiece plane

- Workpiece: The number of the workpiece is displayed. The number of workpieces within this fixture plane is shown after the slash.
- **Method**: You can choose between the WORKPIECE ORIENTED and TOOL ORIENTED machining methods. In tabular view, entry WORKPIECE ORIENTED appears as **WPO**, and TOOL ORIENTED appears as **TO**.
  - Use the **CONNECT/SEPARATE** soft key to mark workpieces that are to be included for calculating the machining process for tool-oriented machining. Connected workpieces are marked with a dashed line, whereas separated workpieces are connected with a solid line. Connected workpieces are marked in tabular view with the entry **CTO** in the METHOD column.
- **Status**: The soft key **BLANK** identifies the workpiece as not yet having been machined, and enters BLANK in the Status field. Use the soft key **EMPTY POSITION** if you want to skip the workpiece during machining. EMPTY appears in the Status field.

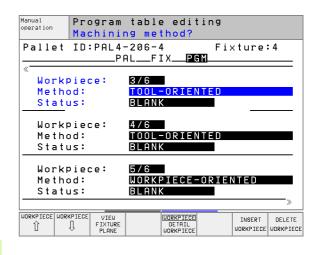


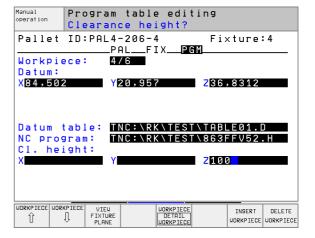
Enter the method and status in the pallet or fixture plane. Then the entry will be assumed for all corresponding workpieces.

For several workpiece variants within one plane, the workpieces of one variant should be entered together. This way, the workpieces of each variant can be marked with the CONNECT/SEPARATE soft key, and can be machined in groups.

#### Setting up details in the workpiece plane

- Workpiece: The number of the workpiece is displayed. The number of workpieces within this fixture or pallet plane is shown after the slash.
- **Datum:** Enter the workpiece datum
- Datum table: Enter the name and path of the datum table valid for machining the workpiece. If you use the same datum table for all workpieces, enter the name and path in the pallet or fixture planes. The data is automatically carried over to the workpiece plane.
- NC program: Enter the path of the NC program that is necessary for machining the workpiece
- Safe height: (optional): Safe position for the individual axes referenced to the workpiece. The positions entered are only approached if these values were read and correspondingly programmed in the NC macros.





#### Sequence of tool-oriented machining



The TNC only carries out tool-oriented machining if the TOOL ORIENTED method was selected, and TO or CTO is entered in the table.

- The entry TO or CTO in the Method field tells the TNC that the oriented machining is valid beyond these lines.
- The pallet management starts the NC program given in the line with the entry TO.
- The first workpiece is machined until the next tool call is pending. Departure from the workpiece is coordinated by a special tool-change macro.
- The entry in the column W-STATE is changed from BLANK to INCOMPLETE, and the TNC enters a hexadecimal value in the field CTID.



The value entered in the field CTID is a unique identifier of the machining progress for the TNC. If these value is deleted or changed, machining cannot be continued, nor is mid-program startup or resumption of machining possible.

- All lines in the pallet file that contain the entry CTO in the Method field are machined in the same manner as the first workpiece. Workpieces in several fixtures can be machined.
- The TNC uses the next tool for the following machining steps again from the line with the entry TO if one of the following situations applies:
  - If the entry PAL is in the PAL/PGM field in the next line.
  - If the entry TO or WPO is in the Method field in the next line.
  - If in the lines already machined there are entries under Method which do not have the status EMPTY or ENDED.
- The NC program is continued at the stored location based on the value entered in the CTID field. Usually the tool is changed for the first piece, but the TNC suppresses the tool change for the following workpieces.
- The entry in the CTID field is updated after every machining step. If an END PGM or M02 is executed in an NC program, then an existing entry is deleted and ENDED is entered in the Machining Status field.



■ If the entries TO or CTO for all workpieces within a group contain the status ENDED, the next lines in the pallet file are run.



In mid-program startup, only one tool-oriented machining is possible. Following pieces are machined according to the method entered.

The value entered in the CTID field is stored for a maximum of one week. Within this time the machining can be continued at the stored location. After this time the value is deleted, in order to prevent large amounts of unnecessary data on the hard disk.

The operating mode can be changed after executing a group of entries with TO or CTO.

The following functions are not permitted:

- Switching the traverse range
- PLC datum shift
- M118

#### To leave the pallet file:

- ▶ To call the file manager, press the PGM MGT soft key.
- ➤ To select a different type of file, press the SELECT TYPE soft key and the soft key for the desired file type, for example SHOW.H.
- ▶ Select the desired file.

#### Executing the pallet file



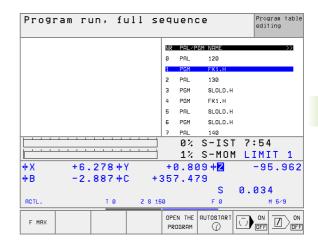
In machine parameter 7683, set whether the pallet table is to be executed blockwise or continuously (see "General User Parameters" on page 448).

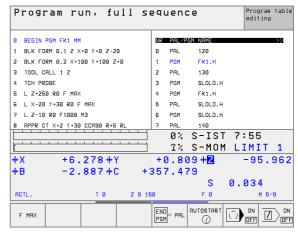
- Select the file manager in the operating mode Program Run, Full Sequence or Program Run, Single Block: Press the PGM MGT key.
- Display all type .P files: Press the soft keys SELECT TYPE and SHOW .P.
- ▶ Select pallet table with the arrow keys and confirm with ENT.
- To execute pallet table: Press the NC Start button. The TNC executes the pallets as set in Machine Parameter 7683.

#### Screen layout for executing pallet tables

You can have the TNC display the program contents and pallet file contents on the screen together by selecting the screen layout PGM + PALLET. During execution, the TNC then shows program blocks to the left and the pallet to the right. To check at the program contents before execution, proceed as follows:

- ▶ Select a pallet table.
- ▶ With the arrow keys, choose the program you would like to check.
- ▶ Press the OPEN PGM soft key: The TNC displays the selected program on the screen. You can now page through the program with the arrow keys.
- ▶ To return to the pallet table, press the END PGM soft key.









5

**Programming: Tools** 

### 5.1 Entering Tool-Related Data

#### Feed rate F

The feed rate  $\mathbf{F}$  is the speed (in millimeters per minute or inches per minute) at which the tool center moves. The maximum feed rates can be different for the individual axes and are set in machine parameters.

#### Input

You can enter the feed rate in the **T00L CALL** block and in every positioning block (see "Creating the program blocks with the path function keys" on page 131).

#### Rapid traverse

If you wish to program rapid traverse, enter  $\mathbf{F}$  MAX. To enter  $\mathbf{F}$  MAX, press the ENT key or the  $\mathbf{F}$  MAX soft key when the dialog question **FEED RATE**  $\mathbf{F}$  = ? appears on the TNC screen.

#### **Duration of effect**

A feed rate entered as a numerical value remains in effect until a block with a different feed rate is reached. **F MAX** is only effective in the block in which it is programmed. After the block with **F MAX** is executed, the feed rate will return to the last feed rate entered as a numerical value.

#### Changing during program run

You can adjust the feed rate during program run with the feed-rate override knob.

#### Spindle speed S

The spindle speed S is entered in revolutions per minute (rpm) in a **TOOL CALL** block.

#### **Programmed change**

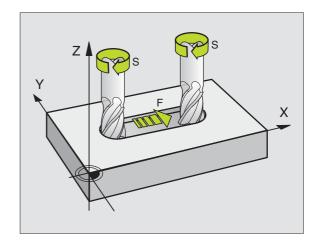
In the part program, you can change the spindle speed in a TOOL CALL block by entering the spindle speed only:



- To program a tool call, press the TOOL CALL key.
- ▶ Ignore the dialog question for Tool number ? with the NO ENT kev.
- Ignore the dialog question for Working spindle axis X/Y/Z? with the NO ENT key.
- ▶ Enter the new spindle speed for the dialog question **Spindle speed S=?**, and confirm with END.

#### Changing during program run

You can adjust the spindle speed during program run with the spindlespeed override knob.



#### 5.2 Tool Data

#### Requirements for tool compensation

You usually program the coordinates of path contours as they are dimensioned in the workpiece drawing. To allow the TNC to calculate the tool center path - i.e. the tool compensation - you must also enter the length and radius of each tool you are using.

Tool data can be entered either directly in the part program with TOOL DEF or separately in a tool table. In a tool table, you can also enter additional data on the specific tool. The TNC will consider all the data entered for the tool when executing the part program.

#### Tool numbers and tool names

Each tool is identified by a number between 0 and 254. If you are working with tool tables, you can use higher numbers and you can also enter a tool name for each tool.

The tool number 0 is automatically defined as the zero tool with the length L=0 and the radius R=0. In tool tables, tool 0 should also be defined with L=0 and R=0.

# 1 8 12 13 18 Z

#### **Tool length L**

There are two ways to determine the tool length L:

# Determining the difference between the length of the tool and that of a zero tool ${\sf L0}$

For the algebraic sign:

L>L0: The tool is longer than the zero tool L<L0: The tool is shorter than the zero tool

To determine the length:

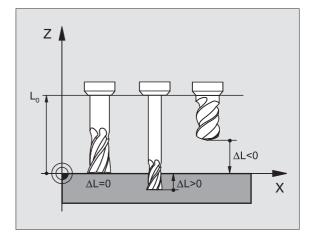
- ▶ Move the zero tool to the reference position in the tool axis (e.g. workpiece surface with Z=0).
- ▶ Set the datum in the tool axis to 0 (datum setting).
- Insert the desired tool.
- Move the tool to the same reference position as the zero tool.
- ▶ The TNC displays the difference between the current tool and the zero tool
- ▶ Enter the value in the TOOL DEF block or in the tool table by pressing the actual-position-capture key.

#### Determining the length L with a tool presetter

Enter the determined value directly in the TOOL DEF tool definition block or in the tool table without further calculations.

#### Tool radius R

You can enter the tool radius R directly.



#### Delta values for lengths and radii

Delta values are offsets in the length and radius of a tool.

A positive delta value describes a tool oversize (DL, DR, DR2>0). If you are programming the machining data with an allowance, enter the oversize value in the TOOL CALL block of the part program.

A negative delta value describes a tool undersize (DL, DR, DR2<0). An undersize is entered in the tool table for wear.

Delta values are usually entered as numerical values. In a TOOL CALL block, you can also assign the values to Q parameters.

Input range: You can enter a delta value with up to ± 99.999 mm.

#### Entering tool data into the program

The number, length and radius of a specific tool is defined in the TOOL DEF block of the part program.

To select tool definition, press the TOOL DEF key.



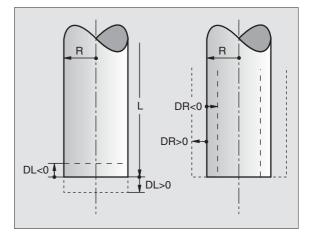
- ▶ Tool number :Each tool is uniquely identified by its tool number.
- ▶ Tool length : Compensation value for the tool length
- ▶ Tool radius : Compensation value for the tool radius



In the programming dialog, you can transfer the value for tool length directly into the input line with the actual-position-capture key. You only need to make sure that the highlight in the status display is placed on the tool axis.

#### Example

4 TOOL DEF 5 L+10 R+5



#### **Entering tool data in tables**

You can define and store up to 32767 tools and their tool data in a tool table. In Machine Parameter 7260, you can define how many tools are to be stored by the TNC when a new table is set up. See also the Editing Functions at a later stage in this Chapter. In order to be able to assign various compensation data to a tool (indexing tool number), machine parameter 7262 must not be equal to 0.

You must use tool tables if

- you wish to use indexed tools such as stepped drills with more than one length compensation value (see page 104)
- vour machine tool has an automatic tool changer,
- you want to measure tools automatically with the TT 130 touch probe (see the new Touch Probe Cycles User's Manual, Chapter 4),
- you want to rough-mill the contour with Cycle 22 (see "ROUGH-OUT (Cycle 22)" on page 292)
- you want to work with automatic cutting data calculations.

#### Tool table: Standard tool data

Abbr.	Input	Dialog
T	Number by which the tool is called in the program (e.g. 5, indexed: 5.2)	-
NAME	Name by which the tool is called in the program	Tool name?
L	Value for tool length compensation L	Tool length?
R	Compensation value for the tool radius R	Tool radius R?
R2	Tool radius R2 for toroid cutters (only for 3-D radius compensation or graphical representation of a machining operation with spherical or toroid cutters)	Tool radius R2?
DL	Delta value for tool radius R2	Tool length oversize?
DR	Delta value for tool radius R	Tool radius oversize?
DR2	Delta value for tool radius R2	Tool radius oversize R2?
LCUTS	Tooth length of the tool for Cycle 22	Tool length in the tool axis?
ANGLE	Maximum plunge angle of the tool for reciprocating plunge-cut in Cycles 22 and 208	Maximum plunge angle?
TL	Set tool lock (TL: Tool Locked)	Tool locked? Yes = ENT / No = NO ENT
RT	Number of a replacement tool (RT), if available (see also TIME2)	Replacement tool?
TIME1	Maximum tool life in minutes. This function can vary depending on the individual machine tool. Your machine manual provides more information on TIME1.	Maximum tool age?

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Abbr.	Input	Dialog
TIME2	Maximum tool life in minutes during TOOL CALL: If the current tool age exceeds this value, the TNC changes the tool during the next TOOL CALL (see also CUR.TIME).	Maximum tool age for TOOL CALL?
CUR.TIME	Time in minutes the tool has been in use: The TNC automatically counts the current tool age. A starting value can be entered for used tools.	Current tool life?
DOC	Comment on tool (up to 16 characters)	Tool description?
PLC	Information on this tool that is to be sent to the PLC	PLC status?
PLC VAL	Value of this tool that is to be sent to the PLC	PLC value?

#### Tool table: Tool data required for automatic tool measurement



For a description of the cycles governing automatic tool measurement, see the new Touch Probe Cycles Manual, Chapter 4.

Abbr.	Input	Dialog
CUT	Number of teeth (20 teeth maximum)	Number of teeth ?
LT0L	Permissible deviation from tool length L for wear detection. If the entered value is exceeded, the TNC locks the tool (status $\bf L$ ). Input range: 0 to 0.9999 mm	Wear tolerance: length ?
RTOL	Permissible deviation from tool radius R for wear detection. If the entered value is exceeded, the TNC locks the tool (status $\bf L$ ). Input range: 0 to 0.9999 mm	Wear tolerance: radius ?
DIRECT.	Cutting direction of the tool for measuring the tool during rotation	Cutting direction (M3 = -) ?
TT:R-OFFS	For tool length measurement: tool offset between stylus center and tool center. Preset value: Tool radius R (NO ENT means R).	Tool offset: radius ?
TT:L-OFFS	Tool radius measurement: tool offset in addition to MP6530 between upper surface of stylus and lower surface of tool. Preset value: 0	Tool offset: length ?
LBREAK	Permissible deviation from tool length L for breakage detection. If the entered value is exceeded, the TNC locks the tool (status $\bf L$ ). Input range: 0 to 0.9999 mm	Breakage tolerance: length ?
RBREAK	Permissible deviation from tool radius R for breakage detection. If the entered value is exceeded, the TNC locks the tool (status L). Input range: 0 to 0.9999 mm	Breakage tolerance: radius ?

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#### Tool table: Tool data for automatic speed/feed rate calculations.

Abbr.	Input	Dialog
ТҮРЕ	Tool type (MILL=for milling, DRILL for drilling or boring, TAP for tapping): Press the SELECT TYPE soft key (3rd soft-key row): The TNC superimposes a window where you can select the type of tool you want.	Tool type?
TMAT	Tool material: Press the SELECT MATERIAL soft key (3rd soft-key row): The TNC superimposes a window where you can select the type of material you want.	Tool material ?
CDT	Cutting data table: Press the SELECT CDT soft key (3rd soft-key row): The TNC superimposes a window where you can select a cutting data table.	Name of cutting data table ?

# Tool table: Tool data for 3-D touch trigger probe (only when bit 1 is set in MP7411 = 1, see also the Touch Probe Cycles Manual)

Abbr.	Input	Dialog
CAL-0F1	During calibration, the TNC stores in this column the center misalignment in the reference axis of the 3-D probe, if a tool number is indicated in the calibration menu	Center misalignmt. in ref. axis?
CAL-0F2	During calibration, the TNC stores in this column the center misalignment in the minor axis of the 3-D probe, if a tool number is indicated in the calibration menu	Center misalignment minor axis?
CAL-ANG	During calibration, the TNC stores in this column the spindle angle at which the 3-D probe was calibrated, if a tool number is indicated in the calibration menu	Spindle angle for calibration?

#### **Editing tool tables**

The tool table that is active during execution of the part program is designated as TOOL.T. You can only edit TOOL.T in one of the machine operating modes. Other tool tables that are used for archiving or test runs are given different file names with the extension .T .

To open the tool table TOOL.T:

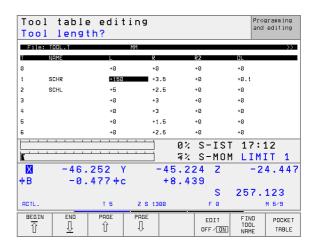
▶ Select any machine operating mode.



To select the tool table, press the TOOL TABLE soft key.



▶ Set the EDIT soft key to ON.



To open any other tool table:

▶ Select the Programming and Editing mode of operation.



- ▶ Call the file manager.
- To select the file type, press the SELECT TYPE soft key.
- To show type .T files, press the SHOW .T soft key.
- Select a file or enter a new file name. Conclude your entry with the ENT key SELECT soft key.

When you have opened the tool table, you can edit the tool data by moving the cursor to the desired position in the table with the arrow keys or the soft keys. You can overwrite the stored values, or enter new values at any position. The available editing functions are illustrated in the table below.

If the TNC cannot show all positions in the tool table in one screen page, the highlight bar at the top of the table will display the symbol ">>" or "<<".

#### Leaving the tool table

▶ Call the file manager and select a file of a different type, e.g. a part program.

Editing functions for tool tables	Soft key
Select beginning of table	BEGIN
Select end of table	END .
Select previous page in table	PAGE
Select next page in table	PAGE
Look for the tool name in the table	FIND TOOL NAME
Show tool information in columns or show all information on one tool on one screen page	LIST FORMULAR
Move to beginning of line	BEGIN LINE
Move to end of line	END LINE
Copy the highlighted field	COPY FIELD
Insert the copied field	PASTE FIELD

Editing functions for tool tables	Soft key
Add the entered number of lines (tools) to the end of the table.	APPEND N LINES
Insert a line for the indexed tool number after the active line. The function is only active if you are permitted to store various compensation data for a tool (machine parameter 7262 not equal to 0). The TNC inserts a copy of the tool data after the last available index and increases the index by 1. Application: e.g. stepped drill with more than one length compensation value.	INSERT LINE
Delete current line (tool)	DELETE LINE
Display / Do not display pocket numbers	SHOW OMIT POCKET NR
Display all tools / only those tools that are stored in the pocket table	HIDE TOOLS QFE/ ON

#### Additional notes on tool tables

Machine parameter 7266.x defines which data can be entered in the tool table and in what sequence the data is displayed.



You can overwrite individual columns or lines of a tool table with the contents of another file. Prerequisites:

- The target file must exist.
- The file to be copied must contain only the columns (or lines) you want to replace.

To copy individual columns or lines, press the REPLACE FIELDS soft key(see "Copying a single file" on page 54).



#### Pocket table for tool changer

For automatic tool changing you need the pocket table TOOL\_P.TCH. The TNC can manage several pocket tables with any file names. To activate a specific pocket table for program run you must select it in the file management of a Program Run mode of operation (status M). In order to be able to manage various magazines in a tool-pocket table (indexing pocket number), machine parameters 7261.0 to 7261.3 must not be equal to 0.

#### Editing a pocket table in a Program Run operating mode



To select the tool table, press the TOOL TABLE soft key.



To select the pocket table, press the POCKET TABLE soft key.



▶ Set the EDIT soft key to ON.

# Selecting a pocket table in the Programming and Editing Editing operating mode



- Call the file manager.
- To select the file type, press the SELECT TYPE soft key.
- To show files of the type .TCH, press the soft key TCH FILES (second soft-key row).
- Select a file or enter a new file name. Conclude your entry with the ENT key SELECT soft key.

Poc	ket	tak	ole e	d i t	ing	3			gramming   editing
Spe	cia	1 to	ool	Y	es:	ENT/N	10=N0E	NT	culting
File	: TOOL	_P.TCH							
Р	Ť	TNAME		ST	FL	PLC			
ø	5					200000000			
1	1	SCHR		S	F	%00000000			
2	2	SCHL				%00000000			
3	3					×00000000			
4	4					<b>%00000000</b>			
5	0					%00000000			
6	6					%00000000			
						0%	S-IST	16:	36
						3%	S-MOM	1 LIM	IT 1
X		-45.	524	Y	-	-46.35	52 Z	-2	3.354
<b>+</b> B		-0.	421+0	:		+8.44	10		
							S	46.6	75
ACTL.			T 5	5 Z S 1300 F 8			F 0		M 5/9
BEGIN	4	END <u>∏</u>	PAGE Î		AGE []	RESET POCKET TABLE	EDIT OFF/ON	NEXT LINE	TOOL TABLE

Abbr.	Input	Dialog
P	Pocket number of the tool in the tool magazine	-
T	Tool number	Tool number ?
ST	Special tool with a large radius requiring several pockets in the tool magazine. If your special tool takes up pockets in front of and behind its actual pocket, these additional pockets need to be locked in column L (status L).	Special tool ?
F	Fixed tool number. The tool is always returned to the same pocket in the tool magazine	Fixed pocket? Yes = ENT / No = NO ENT
L	Locked pocket (see also column ST)	Pocket locked Yes = ENT / No = NO ENT
PLC	Information on this tool pocket that is to be sent to the PLC	PLC status?
TNAME	Display of the tool name from TOOL.T	-
DOC	Display of the comment to the tool from TOOL.T	-

Editing functions for pocket tables	Soft key
Select beginning of table	BEGIN
Select end of table	END
Select previous page in table	PAGE
Select next page in table	PAGE
Reset pocket table	RESET POCKET TABLE
Go to the beginning of the next line	NEXT LINE
Reset tool number column T	RESET COLUMN T
Move to end of line	END LINE

#### **Calling tool data**

A TOOL CALL block in the part program is defined with the following data:

▶ Select the tool call function with the TOOL CALL key.



- ▶ Tool number: Enter the number or name of the tool. The tool must already be defined in a TOOL DEF block or in the tool table. To call a tool by the tool name, enter the name in quotation marks. The tool name always refers to the entry in the active tool table TOOL .T. If you wish to call a tool with other compensation values, enter also the index you defined in the tool table after the decimal point.
- ▶ Working spindle axis X/Y/Z: Enter the tool axis.
- ➤ Spindle speed S: Enter the spindle speed directly or allow the TNC to calculate the spindle speed if you are working with cutting data tables. Press the S CALCULATE AUTOMAT. soft key. The TNC limits the spindle speed to the maximum value set in MP 3515.

- ▶ Feed rate F: Enter the feed rate directly or allow the TNC to calculate the feed rate if you are working with cutting data tables. Press the F CALCULATE AUTOMAT. soft key. The TNC limits the feed rate to the maximum feed rate of the longest axis (set in MP 1010). F is effective until you program a new feed rate in a positioning block or a TOOL CALL block.
- ▶ Tool length oversize DL: Enter the delta value for the tool length.
- ▶ Tool radius oversize DR: Enter the delta value for the tool radius.
- ▶ Tool radius oversize 2: Enter the delta value for the tool radius 2.

#### **Example: Tool call**

Call tool number 5 in the tool axis Z with a spindle speed 2500 rpm and a feed rate of 350 mm/min. The tool length is to be programmed with an oversize of 0.2 mm, the tool radius 2 with an oversize of 0.05 mm, and the tool radius with an undersize of 1 mm.

20 TOOL CALL 5.2 Z S2500 F350 DL+0.2 DR-1 DR2+0.05

The character **D** preceding **L** and **R** designates delta values.

#### Tool preselection with tool tables

If you are working with tool tables, use **TOOL DEF** to preselect the next tool. Simply enter the tool number or a corresponding  $\Omega$  parameter, or type the tool name in quotation marks.

#### **Tool change**



The tool change function can vary depending on the individual machine tool. The machine tool manual provides further information.

#### Tool change position

A tool change position must be approachable without collision. With the miscellaneous functions M91 and M92, you can enter machine-referenced (rather than workpiece-referenced) coordinates for the tool change position. If T00L CALL 0 is programmed before the first tool call, the TNC moves the tool spindle in the tool axis to a position that is independent of the tool length.

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#### Manual tool change

To change the tool manually, stop the spindle and move the tool to the tool change position:

- ▶ Move to the tool change position under program control.
- Interrupt program run, see "Interrupting machining," page 409
- Change the tool.
- ▶ Resume the program run, see "Resuming program run after an interruption," page 411

#### **Automatic tool change**

If your machine tool has automatic tool changing capability, the program run is not interrupted. When the TNC reaches a **TOOL CALL**, it replaces the inserted tool by another from the tool magazine.

#### Automatic tool change if the tool life expires: M101



The function of **M101** can vary depending on the individual machine tool. The machine tool manual provides further information.

The TNC automatically changes the tool if the tool life **TIME2** expires during program run. To use this miscellaneous function, activate **M101** at the beginning of the program. **M101** is reset with **M102**.

The tool is not always changed immediately, but, depending on the workload of the control, a few NC blocks later.

# Prerequisites for standard NC blocks with radius compensation R0, RR, RL

The radius of the replacement tool must be the same as that of the original tool. If the radii are not equal, the TNC displays an error message and does not replace the tool.

# Prerequisites for NC blocks with surface-normal vectors and 3-D compensation

See "Three-Dimensional Tool Compensation," page 114The radius of the replacement tool can differ from the radius of the original tool. The tool radius is not included in program blocks transmitted from CAD systems. You can enter the delta value (DR) either in the tool table or in the TOOL CALL block.

If  $\mathbf{DR}$  is positive, the TNC displays an error message and does not replace the tool. You can suppress this message with the M function  $\mathbf{M107}$ , and reactivate it with  $\mathbf{M108}$ .

## **5.3 Tool Compensation**

#### Introduction

The TNC adjusts the spindle path in the tool axis by the compensation value for the tool length. In the working plane, it compensates the tool radius.

If you are writing the part program directly on the TNC, the tool radius compensation is effective only in the working plane. The TNC accounts for the compensation value in up to five axes including the rotary axes.



If a part program generated by a CAD system contains surface-normal vectors, the TNC can perform threedimensional tool compensation, see "Three-Dimensional Tool Compensation," page 114.

#### **Tool length compensation**

Length compensation becomes effective automatically as soon as a tool is called and the tool axis moves. To cancel length compensation call a tool with the length L=0.



If you cancel a positive length compensation with **T00L CALL 0**, the distance between tool and workpiece will be reduced.

After **T00L CALL**, the path of the tool in the tool axis, as entered in the part program, is adjusted by the difference between the length of the previous tool and that of the new one.

For tool length compensation, the TNC takes the delta values from both the **T00L CALL** block and the tool table into account:

Compensation value =  $\mathbf{L} + \mathbf{D}\mathbf{L}_{TOOL\ CALL} + \mathbf{D}\mathbf{L}_{TAB}$  where

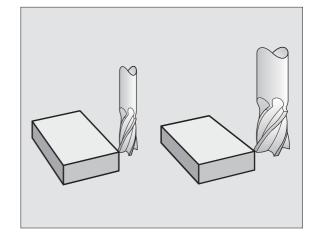
L is the tool length L from the T00L DEF block or tool

table.

**DL** TOOL CALL: is the oversize for length **DL** in the **TOOL CALL** block

(not taken into account by the position display).

 $DL_{TAB}$  is the oversize for length DL in the tool table



 $egin{pmatrix} \mathbf{i} \end{bmatrix}$ 

#### **Tool radius compensation**

The NC block for programming a tool movement contains:

- RL or RR for radius compensation.
- R+ or R-, for radius compensation in single-axis movements.
- RO, if there is no radius compensation.

Radius compensation becomes effective as soon as a tool is called and is moved in the working plane with RL or RR.



The TNC automatically cancels radius compensation if vou:

- program a positioning block with RO
- depart the contour with the **DEP** function
- program a PGM CALL
- select a new program with PGM MGT

For tool radius compensation, the TNC takes the delta values from both the **T00L CALL** block and the tool table into account:

Compensation value =  $\mathbf{R} + \mathbf{D}\mathbf{R}_{TOOL\ CALL} + \mathbf{D}\mathbf{R}_{TAB}$  where

**R** is the tool radius **R** from the **TOOL DEF** block or tool

table.

 $\label{eq:decomposition} \textbf{DR}_{\mbox{TOOL CALL}} : \qquad \mbox{is the oversize for radius } \textbf{DR} \mbox{ in the } \textbf{TOOL CALL} \mbox{block}$ 

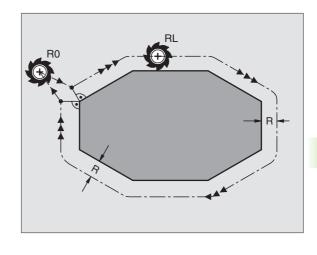
(not taken into account by the position display).

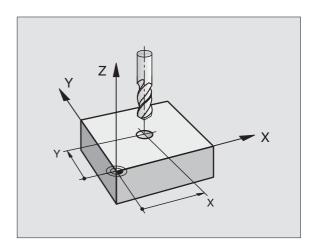
 $\mathbf{DR}_{\mathsf{TAB}}$  is the oversize for radius  $\mathbf{DR}$  in the tool table



The tool center moves in the working plane to the programmed path or coordinates.

Applications: Drilling and boring, pre-positioning.





#### Tool movements with radius compensation: RR and RL

The tool moves to the left of the programmed contour.

The tool moves to the left of the programmed contour.

**RL** The tool moves to the left of the programmed contour

The tool center moves along the contour at a distance equal to the radius. "Right" or "left" are to be understood as based on the direction of tool movement along the workpiece contour See figures at right.



Between two program blocks with different radius compensations (**RR** and **RL**) you must program at least one traversing block in the working plane without radius compensation (that is, with **R0**).

Radius compensation does not take effect until the end of the block in which it is first programmed.

You can also activate the radius compensation for secondary axes in the working plane. Program the secondary axes too in each following block, since otherwise the TNC will execute the radius compensation in the principal axis again.

Whenever radius compensation is activated with RR/RL or canceled with R0, the TNC positions the tool perpendicular to the programmed starting or end position. Position the tool at a sufficient distance from the first or last contour point to prevent the possibility of damaging the contour.

#### **Entering radius compensation**

Program any desired path function, enter the coordinates of the target point and confirm your entry with ENT.

#### Radius comp. RL/RR/no comp. ?

RL

To select tool movement to the left of the contour, press the RL soft key, or

RR

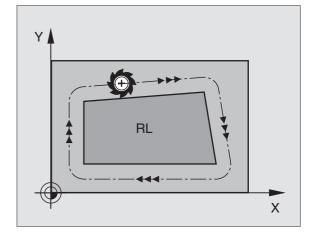
To select tool movement to the right of the contour, press the RR soft key, or

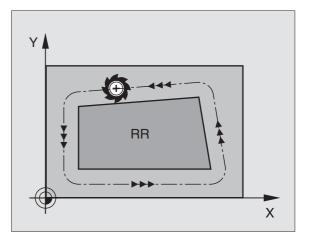


To select tool movement without radius compensation or to cancel radius compensation, press the ENT key.



To terminate the block, press the END key.







#### Radius compensation: Machining corners

#### Outside corners

If you program radius compensation, the TNC moves the tool around outside corners either on a transitional arc or on a spline (selectable via MP7680). If necessary, the TNC reduces the feed rate at outside corners to reduce machine stress, for example at very great changes of direction.

#### ■ Inside corners

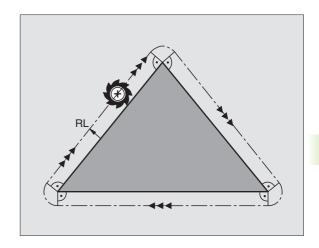
The TNC calculates the intersection of the tool center paths at inside corners under radius compensation. From this point it then starts the next contour element. This prevents damage to the workpiece. The permissible tool radius, therefore, is limited by the geometry of the programmed contour.

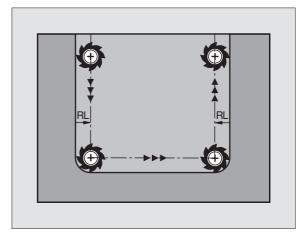


To prevent the tool from damaging the contour, be careful not to program the starting or end position for machining inside corners at a corner of the contour.

#### Machining corners without radius compensation

If you program the tool movement without radius compensation, you can change the tool path and feed rate at workpiece corners with the miscellaneous function **M90**, See "Smoothing corners: M90," page 181.





# 5.4 Three-Dimensional Tool Compensation

#### Introduction

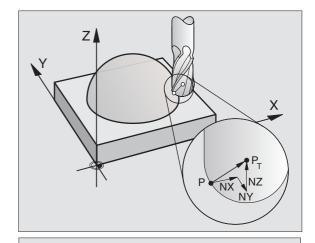
The TNC can carry out a three-dimensional tool compensation (3-D compensation) for straight-line blocks. Apart from the X, Y and Z coordinates of the straight-line end point, these blocks must also contain the components NX, NY and NZ of the surface-normal vector (see figure above right and explanation further down on this page).

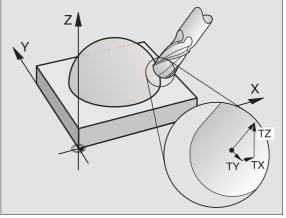
If, in addition, you want to carry out a tool orientation or a threedimensional radius compensation, these blocks need also a normalized vector with the components TX, TY and TZ, which determines the tool orientation (see figure at center right).

The straight-line end point, the components for the surface-normal vector as well as those for the tool orientation must be calculated by a CAD system.

#### **Application possibilities**

- Use of tools with dimensions that do not correspond with the dimensions calculated by the CAD system (3-D compensation without definition of the tool orientation)
- Face milling: compensation of the milling machine geometry in the direction of the surface-normal vector (3-D compensation with and without definition of the tool orientation). Cutting is usually with the end face of the tool
- Peripheral milling: compensation of the mill radius perpendicular to the direction of movement and perpendicular to the tool direction (3-D radius compensation with definition of the tool orientation). Cutting is usually with the lateral surface of the tool





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#### **Definition of a normalized vector**

A normalized vector is a mathematical quantity with a value of 1 and a direction. The TNC requires up to two normalized vectors for LN blocks, one to determine the direction of the surface-normal vector, and another (optional) to determine the tool orientation direction. The direction of a surface-normal vector is determined by the components NX, NY and NZ. With an end mill and a radius mill, this direction is perpendicular from the workpiece surface to be machined to the tool datum PT, and with a toroid cutter through PT' or PT (see figure at upper right). The direction of the tool orientation is determined by the components TX, TY and TZ.



The coordinates for the X, Y, Z positions and the surfacenormal components NX, NY, NZ, as well as TX, TY, TZ must be in the same sequence in the NC block.

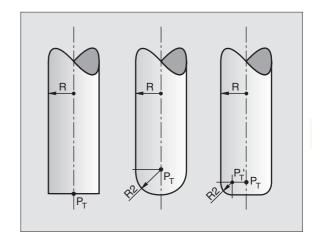
Always indicate all of the coordinates and all of the surface-normal vectors in an LN block, even if the values have not changed from the previous block.

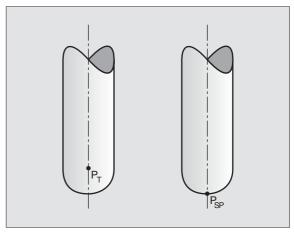
3-D compensation with surface-normal vectors is only effective for coordinates in the main axes X, Y, Z.

If you insert a tool with oversize (positive delta value), the TNC outputs an error message. You can suppress the error message with the M function **M107** (see "Prerequisites for NC blocks with surface-normal vectors and 3-D compensation," page 109).

The TNC will not display an error message if an entered tool oversize would cause damage to the contour.

Machine parameter 7680 defines whether the CAD system has calculated the tool length compensation from the center of sphere  $P_T$  or the south pole of the sphere  $P_{SP}$  (see figure at right).





#### Permissible tool forms

You can describe the permissible tool shapes in the tool table via tool radius **R** and **R2** (see figure at upper right):

- Tool radius **R:** Distance from the tool center to the tool circumference
- Tool radius 2: R2: Radius of the curvature between tool tip and tool circumference.

The ratio of **R** to **R2** determines the shape of the tool:

- **R2** = 0: End mill
- R2 = R: ball-nose cutter.
- $\blacksquare$  0 < **R2** < **R:** Toroid cutter

These data also specify the coordinates of the tool datum PT.

#### Using other tools: Delta values

If you want to use tools that have different dimensions than the ones you originally programmed, you can enter the difference between the tool lengths and radii as delta values in the tool table or **TOOL CALL**:

- Positive delta value **DL**, **DR**, **DR2**: The tool is larger than the original tool (oversize).
- Negative delta value DL, DR, DR2: The tool is smaller than the original tool (undersize).

The TNC then compensates the tool position by the sum of the delta values from the tool table and the tool call.

#### 3-D compensation without tool orientation

The TNC displaces the tool in the direction of the surface-normal vectors by the sum of the delta values (tool table and **T00L CALL**).

#### **Example: Block format with surface-normal vectors**

1 LN X+31.737 Y+21.954 Z+33.165 NX+0.2637581 NY+0.0078922 NZ-0.8764339 F1000 M3

**LN**: Straight line with 3-D compensation

X, Y, Z: Compensated coordinates of the straight-line end point

NX, NY, NZ: Components of the surface-normal vector

**F**: Feed rate

M: Miscellaneous function

The feed rate F and miscellaneous function M can be entered and changed in the Programming and Editing mode of operation.

The coordinates of the straight-line end point and the components of the surface-normal vectors are to be defined by the CAD system.

# Face Milling: 3-D compensation with and without tool orientation

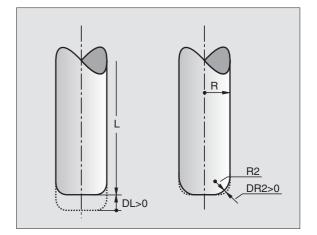
The TNC displaces the tool in the direction of the surface-normal vectors by the sum of the delta values (tool table and **T00L CALL**).

If **M128** (see "Maintaining the position of the tool tip when positioning with tilted axes (TCPM\*): M128," page 194) is active, the TNC maintains the tool perpendicular to the workpiece contour if no tool orientation is programmed in the LN block.

If there is a tool orientation defined in the LN block, then the TNC will position the rotary axes automatically so that the tool can reach the defined orientation.



The TNC is not able to automatically position the rotary axes on all machines. Refer to your machine manual.



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#### Danger of collision

On machines whose rotary axes only allow limited traverse, sometimes automatic positioning can require the table to be rotated by 180°. In this case, make sure that the tool head does not collide with the workpiece or the clamps.

# Example: Block format with surface-normal vectors without tool orientation

LN X+31.737 Y+21.954 Z+33.165 NX+0.2637581 NY+0.0078922 NZ-0.8764339 F1000 M128

# Example: Block format with surface-normal vectors and tool orientation

LN X+31.737 Y+21.954 Z+33.165 NX+0.2637581 NY+0.0078922 NZ0.8764339 TX+0.0078922 TY-0.8764339 TZ+0.2590319 F1000 M128

**LN**: Straight line with 3-D compensation

X, Y, Z: Compensated coordinates of the straight-line end point

NX, NY, NZ: Components of the surface-normal vector

TX, TY, TZ: Components of the normalized vector for workpiece

orientation

**F**: Feed rate

M: Miscellaneous function

The feed rate  ${\bf F}$  and miscellaneous function  ${\bf M}$  can be entered and changed in the Programming and Editing mode of operation.

The coordinates of the straight-line end point and the components of the surface-normal vectors are to be defined by the CAD system.



# Peripheral milling: 3-D radius compensation with workpiece orientation

The TNC displaces the tool perpendicular to the direction of movement and perpendicular to the tool direction by the sum of the delta values **DR** (tool table and **TOOL CALL**). Determine the compensation direction with radius compensation **RL/RR** (see figure at upper right, traverse direction Y+). For the TNC to be able to reach the set tool orientation, you need to activate the function **M128** (see "Maintaining the position of the tool tip when positioning with tilted axes (TCPM\*): M128" on page 194). The TNC then positions the rotary axes automatically so that the tool can reach the defined orientation with the active compensation.



The TNC is not able to automatically position the rotary axes on all machines. Refer to your machine manual.



#### **Danger of collision**

On machines whose rotary axes only allow limited traverse, sometimes automatic positioning can require the table to be rotated by 180°. In this case, make sure that the tool head does not collide with the workpiece or the clamps.

There are two ways to define the tool orientation:

- In an LN block with the components TX, TY and TZ
- In an L block by indicating the coordinates of the rotary axes

#### **Example: Block format with tool orientation**

1 LN X+31.737 Y+21.954 Z+33.165 TX+0.0078922 TY0.8764339 TZ+0.2590319 F1000 M128

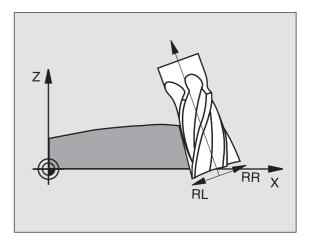
**LN**: Straight line with 3-D compensation

X, Y, Z: Compensated coordinates of the straight-line end point TX, TY, TZ: Components of the normalized vector for workpiece

orientation

**F**: Feed rate

M: Miscellaneous function



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#### **Example: Block format with rotary axes**

1 L X+31.737 Y+21.954 Z+33.165 B+12.357 C+5.896 F1000 M128

L Straight line

X, Y, Z: Compensated coordinates of the straight-line end point B, C: Coordinates of the rotary axes for tool orientation

**F**: Feed rate

M: Miscellaneous function

# 5.5 Working with Cutting Data Tables

#### Note



The TNC must be specially prepared by the machine tool builder for the use of cutting data tables.

Some functions or additional functions described here may not be provided on your machine tool. Refer to your machine manual.

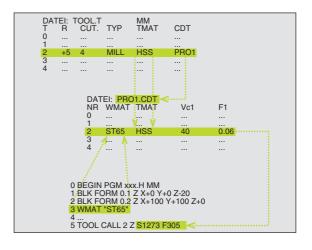
#### **Applications**

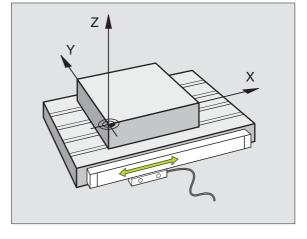
In cutting data tables containing various workpiece and cutting material combinations, the TNC can use the cutting speed  $V_{\rm C}$  and the tooth feed  $f_{\rm Z}$  to calculate the spindle speed S and the feed rate F. This calculation is only possible if you defined the workpiece material in the program and various tool-specific features in the tool table.



Before you let the TNC automatically calculate the cutting data, the tool table from which the TNC is to take the tool-specific data must be first be activated in the Test Run mode (status S).

Editing function for cutting data tables	Soft key
Insert line	INSERT LINE
Delete line	DELETE LINE
Go to the beginning of the next line	NEXT LINE
Sort the table	ORDER N
Copy the highlighted field (2nd soft-key row)	COPY FIELD
Insert the copied field (2nd soft-key row)	PASTE FIELD
Edit the table format (2nd soft-key row)	EDIT FORMAT





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#### **Table for workpiece materials**

Workpiece materials are defined in the table WMAT.TAB (see figure at upper right). WMAT.TAB is stored in the TNC:\ directory and can contain as many materials as you want. The name of the material type can have a max. of 32 characters (including spaces). The TNC displays the contents of the NAME column when you are defining the workpiece material in the program (see the following section).



If you change the standard workpiece material table, you must copy it into a new directory. Otherwise your changes will be overwritten during a software update by the HEIDENHAIN standard data. Define the path in the TNC.SYS file with the code word WMAT= (see "Configuration file TNC.SYS," page 126).

To avoid losing data, save the WMAT.TAB file at regular intervals.

#### Defining the workpiece material in the NC program

In the NC program select the workpiece material from the WMAT.TAB table using the WMAT soft key:



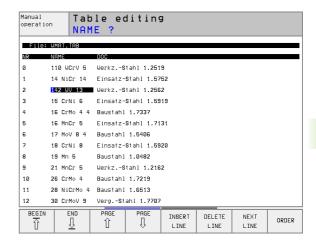
Program the workpiece material: In the Programming and Editing operating mode, press the WMAT soft key.



- ▶ The WMAT.TAB table is superimposed: Press the SELECT WORKPIECE MATERIAL soft key and the TNC displays in a second window the list of materials that are stored in the WMAT.TAB table.
- Select your workpiece material by using the arrow keys to move the highlight onto the material you wish to select and confirming with the ENT key. The TNC transfers the selected material to the WMAT block. To scroll through the table more quickly, press and hold SHIFT and then the arrow keys. The TNC then moves page by page.
- To terminate the dialog, press the END key.



If you change the WMAT block in a program, the TNC outputs a warning. Check whether the cutting data stored in the TOOL CALL block are still valid.



#### Table for tool cutting materials

Tool cutting materials are defined in the TMAT.TAB table. TMAT.TAB is stored in the TNC:\ directory and can contain as many material names as you want (see figure at upper right). The name of the cutting material type can have a max. of 16 characters (including spaces). The TNC displays the NAME column when you are defining the tool cutting material in the TOOL.T tool table.



If you change the standard tool cutting material table, you must copy it into a new directory. Otherwise your changes will be overwritten during a software update by the HEIDENHAIN standard data. Define the path in the TNC.SYS file with the code word TMAT= (see "Configuration file TNC.SYS," page 126).

To avoid losing data, save the TMAT.TAB file at regular intervals.

Manual Table editing operation Cutting material?							
File	: TMAT.TAB						
NR	NAME	DOC					
0	HC-K15	■ HM besch	ichtet				
1	HC-P25	HM besch	ichtet				
2	HC-P35	HM besch	ichtet				
3	HSS						
4	HSSE-C⊙5	HSS + Kobalt					
5	HSSE-C≎8	HSS + Ko	HSS + Kobalt				
6	HSSE-C≎8-Ti	N HSS + Ko	HSS + Kobalt				
7	HSSE/TiCN	TiCN-bes	TiCN-beschichtet				
8	HSSE/TiN	TiN-besc	TiN-beschichtet				
9	HT-P15	Cermet					
10	HT-M15	Cermet	Cermet				
11	HW-K15	HM unbeschichtet					
12 HW-K25 HM unbeschichtet							
BEGIN	END	PAGE Î	PAGE	INSERT LINE	DELETE LINE	NEXT LINE	ORDER

#### Table for cutting data

Define the workpiece material/cutting material combinations with the corresponding cutting data in a file table with the file name extension .CDT; see figure at center right. You can freely configure that entries in the cutting data table. Besides the obligatory columns NR, WMAT and TMAT, the TNC can also manage up to four cutting speed ( $V_{\rm C}$ )/ feed rate (F)combinations.

The standard cutting data table FRAES\_2 .CDT is stored in the directory TNC:\. You can edit FRAES\_2.CDT, or add as many new cutting-data tables as you wish.



If you change the standard cutting data table, you must copy it into a new directory. Otherwise your changes will be overwritten during a software update by the HEIDENHAIN standard data (see "Configuration file TNC.SYS," page 126).

All of the cutting data tables must be stored in the same directory. If the directory is not the standard directory TNC:\, then behind the code word PCDT= you must enter the path in which your cutting data is stored.

To avoid losing data, save your cutting data tables at regular intervals.

	sequence .	le editing ting speed		?			
F i l	e: FRAES_2.CDT						
NR	UMAT	TMAT	Vc1	F 1	Vc2	F2	
0	St 33-1	HSSE/TiN	40	0,016	55	0,0	20
1	St 33-1	HSSE/TiCN	40	0,016	55	0,0	20
2	St 33-1	HC-P25	100	0,200	130	0,2	50
3	St 37-2	HSS-C∘5	20	0,025	45	0,03	30
4	St 37-2	HSSE/TiCN	40	0,016	55	0,0	20
5	St 37-2	HC-P25	100	0,200	130	0,25	i0
6	St 50-2	HSSE/TiN	40	0,016	55	0,0	20
7	St 50-2	HSSE/TiCN	40	0,016	55	0,0	20
8	St 50-2	HC-P25	100	0,200	130	0,2	50
9	St 60-2	HSSE/TiN	40	0,016	55	0,0	20
10	St 60-2	HSSE/TiCN	40	0,016	55	0,0	20
11	St 60-2	HC-P25	100	0,200	130	0,2	50
12	C 15	HSS-Co5	20	0,040	45	0,08	50
BEG		PAGE PAGE ↑	INSERT	DELETE		EXT	ORDER

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#### Creating a new cutting data table.

- ▶ Select the Programming and Editing mode of operation.
- ▶ To select the file manager, press the Taste PGM MGT key.
- ▶ Select the directory where the cutting data table is to be stored.
- ▶ Enter any file name with file name extension .CDT, and confirm with ENT.
- ▶ On the right half of the screen, the TNC displays various table formats (machine-dependent, see example in figure at right). These tables differ from each other in the number of cutting speed/feed rate combinations they allow. Use the arrow keys to move the highlight onto the table format you wish to select and confirm with ENT. The TNC generates a new, empty cutting data table.

#### Data required for the tool table

- Tool radius under R (DR)
- Number of teeth (only with tools for milling) under CUT
- Tool type under TYPE
- The tool type influences the calculation of the feed rate:

Milling tool:  $F = S \cdot f_Z \cdot z$ 

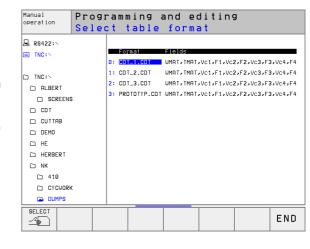
All other tools:  $F = S \cdot f_U$ 

S: Spindle speed

f<sub>Z</sub>: Feed per tooth

f<sub>U</sub>: Feed per revolution

- z. Number of teeth
- Tool cutting material under TMAT
- Name of the cutting data table for which this tool will be used under CDT
- In the tool table, select the tool type, tool cutting material and the name of the cutting data table via soft key (see "Tool table: Tool data for automatic speed/feed rate calculations.," page 103).



## Working with automatic speed/feed rate calculation

- 1 If it has not already been entered, enter the type of workpiece material in the file WMAT.TAB
- 2 If it has not already been entered, enter the type of cutting material in the file TMAT.TAB.
- **3** If not already entered, enter all of the required tool-specific data in the tool table:
  - Tool radius
  - Number of teeth
  - Tool type
  - Tool material
  - The cutting data table for each tool
- 4 If not already entered, enter the cutting data in any cutting data table (CDT file).
- **5** Test Run operating mode: Activate the tool table from which the TNC is to take the tool-specific data (status S).
- 6 In the NC program, set the workpiece material by pressing the WMAT soft key.
- 7 In the NC program, let the TOOL CALL block automatically calculate spindle speed and feed rate via soft key.

#### Changing the table structure

Cutting data tables constitute so-called "freely-definable tables" for the TNC. You can change the format of freely definable tables by using the structure editor.

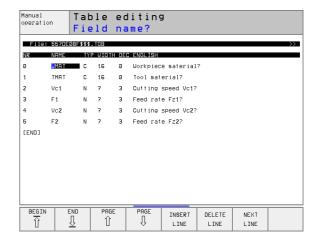


The TNC can process up to 200 characters per line and up to 30 column.

If you insert an additional column into an existing table, the TNC does not automatically shift the values that have been entered.

#### Calling the structure editor

Press the EDIT FORMAT soft key (2nd soft-key level). The TNC opens the editing window (see figure at right), in which the table structure is shown "rotated by 90°." In other words, a line in the editing window defines a column in the associated table. The meanings of the structure commands (header entries) are shown in the table at right.



5 Programming: Tools

#### **Exiting the structure editor**

Press the END key. The TNC changes data that was already in the table into the new format. Elements that the TNC could not convert into the new structure are indicated with a hash mark # (e.g., if you have narrowed the column width).

Structure command	Meaning
NR	Column number
NAME	Overview of columns
TYPE	N: Numerical input C: Alphanumeric input
WIDTH	Width of column For type Nincluding algebraic sign, comma, and decimalplaces
DEC	Number of decimal places (max. 4, effective only for type N)
ENGLISH to HUNGARIAN	Language-dependent dialogs (max. 32 characters)

#### Data transfer from cutting data tables

If you output a file type .TAB or .CDT via an external data interface, the TNC also transfers the structural definition of the table. The structural definition begins with the line #STRUCTBEGIN and ends with the line #STRUCTEND. The meanings of the individual code words are shown in the table "Structure Command" (see "Changing the table structure," page 124). Behind #STRUCTEND the TNC saves the actual content of the table.

#### **Configuration file TNC.SYS**

You must use the configuration file TNC.SYS if your cutting data tables are not stored in the standard directory TNC:\. In TNC.SYS you must then define the paths in which you have stored your cutting data tables.



The TNC.SYS file must be stored in the root directory TNC:\.

Entries in TNC.SYS	Meaning
WMAT=	Path for workpiece material table
TMAT=	Path for cutting material table
PCDT=	Path for cutting data tables

#### **Example of TNC.SYS**

WMAT=TNC:\CUTTAB\WMAT_GB.TAB	
TMAT=TNC:\CUTTAB\TMAT_GB.TAB	
PCDT=TNC:\CUTTAB\	





6

**Programming: Programming Contours** 

#### 6.1 Tool movements

#### Path functions

A workpiece contour is usually composed of several contour elements such as straight lines and circular arcs. With the path functions, you can program the tool movements for **straight lines** and **circular arcs**.

#### **FK Free Contour Programming**

If a production drawing is not dimensioned for NC and the dimensions given are not sufficient for creating a part program, you can program the workpiece contour with the FK free contour programming and have the TNC calculate the missing data.

With FK programming, you also program tool movements for straight lines and circular arcs.



With the TNC's miscellaneous functions you can affect

- Program run, e.g., a program interruption
- Machine functions, such as switching spindle rotation and coolant supply on and off
- Contouring behavior of the tool

#### **Subprograms and Program Section Repeats**

If a machining sequence occurs several times in a program, you can save time and reduce the chance of programming errors by entering the sequence once and then defining it as a subprogram or program section repeat. If you wish to execute a specific program section only under certain conditions, you also define this machining sequence as a subprogram. In addition, you can have a part program call a separate program for execution.

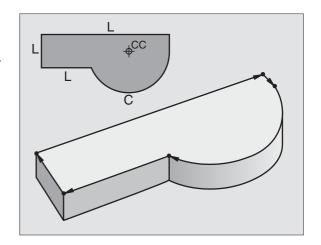
Programming with subprograms and program section repeats is described in Chapter 9.

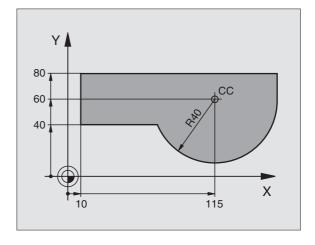
#### Programming with Q parameters

Instead of programming numerical values in a part program, you enter markers called Q parameters. You assign the values to the Q parameters separately with the Q parameter functions. You can use the Q parameters for programming mathematical functions that control program execution or describe a contour.

In addition, parametric programming enables you to measure with the 3-D touch probe during program run.

Programming with Q parameters is described in Chapter 10.





## 6.2 Fundamentals of Path Functions

## Programming tool movements for workpiece machining

You create a part program by programming the path functions for the individual contour elements in sequence. You usually do this by entering **the coordinates if the end points of the contour elements** given in the production drawing. The TNC calculates the actual path of the tool from these coordinates, and from the tool data and radius compensation.

The TNC moves all axes programmed in a single block simultaneously.

#### Movement parallel to the machine axes

The program block contains only one coordinate. The TNC thus moves the tool parallel to the programmed axis.

Depending on the individual machine tool, the part program is executed by movement of either the tool or the machine table on which the workpiece is clamped. Nevertheless, you always program path contours as if the tool moves and the workpiece remains stationary.

Example:

#### L X+100

L Path function for "straight line"

X+100 Coordinate of the end point

The tool retains the Y and Z coordinates and moves to the position X=100 (see figure at upper right).

#### Movement in the main planes

The program block contains two coordinates. The TNC thus moves the tool in the programmed plane.

Example:

#### L X+70 Y+50

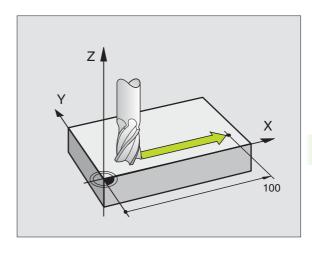
The tool retains the Z coordinate and moves in the XY plane to the position X=70, Y=50 (see figure at center right).

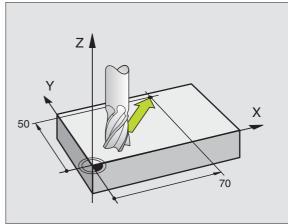
#### Three-dimensional movement

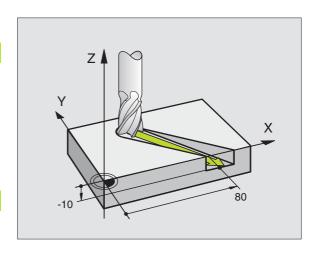
The program block contains three coordinates. The TNC thus moves the tool in space to the programmed position.

Example:

#### L X+80 Y+0 Z-10







#### **Entering more than three coordinates**

The TNC can control up to 5 axes simultaneously. Machining with 5 axes, for example, moves 3 linear and 2 rotary axes simultaneously.

Such programs are too complex to program at the machine, however, and are usually created with a CAD system.

Example:

#### L X+20 Y+10 Z+2 A+15 C+6 R0 F100 M3



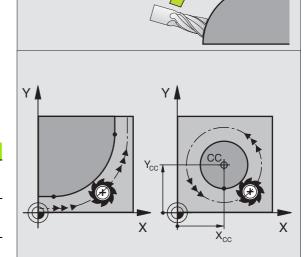
The TNC graphics cannot simulate movements in more than three axes.

#### Circles and circular arcs

The TNC moves two axes simultaneously in a circular path relative to the workpiece. You can define a circular movement by entering the circle center CC.

When you program a circle, the TNC assigns it to one of the main planes. This plane is defined automatically when you set the spindle axis during a TOOL CALL:

Tool axis	Main plane	
Z	<b>XY</b> , also UV, XV, UY	
Υ	<b>ZX</b> , also WU, ZU, WX	
Х	<b>YZ</b> , also VW, YW, VZ	



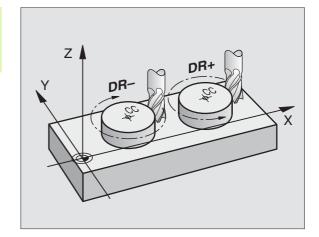


You can program circles that do not lie parallel to a main plane by using the function for tilting the working plane (see "WORKING PLANE (Cycle 19)," page 330) or Q parameters (see "Principle and Overview," page 356).

#### Direction of rotation DR for circular movements

When a circular path has no tangential transition to another contour element, enter the direction of rotation DR:

Clockwise direction of rotation: DR–
Counterclockwise direction of rotation: DR+



#### Radius compensation

The radius compensation must be in the block in which you move to the first contour element. You cannot begin radius compensation in a circle block. It must be activated beforehand an a straight-line block (see "Path Contours — Cartesian Coordinates," page 139) or approach block (APPR block, see "Contour Approach and Departure," page 133).

#### **Pre-positioning**

Before running a part program, always pre-position the tool to prevent the possibility of damaging it or the workpiece.

#### Creating the program blocks with the path function keys

The gray path function keys initiate the plain language dialog. The TNC asks you successively for all the necessary information and inserts the program block into the part program.

Example — programming a straight line:



Initiate the programming dialog, e.g. for a straight line.

#### Coordinates ?



10

Enter the coordinates of the straight-line end point.



5

ENT

#### Radius comp. RL/RR/no comp. ?



Select the radius compensation (here, press the RL soft key - the tool moves to the left of the programmed contour).

#### Feed rate F=? / F MAX = ENT

100



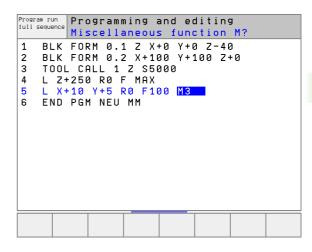
Enter the feed rate (here, 100 mm/min), and confirm your entry with ENT. For programming in inches, enter 100 for a feed rate of 10 ipm.

F MAX

Move at rapid traverse: press the FMAX soft key, or

F AUTO

Move at automatically calculated speed (cutting data table): press the FAUTO soft key.



#### Miscellaneous function M ?

3



Enter a miscellaneous function (here, M3), and terminate the dialog with ENT.

The part program now contains the following line:

L X+10 Y+5 RL F100 M3



# 6.3 Contour Approach and Departure

## Overview: Types of paths for contour approach and departure

The functions for contour approach APPR and departure DEP are activated with the APPR/DEP key. You can then select the desired path function with the corresponding soft key:

Function Soft key	Approach	Departure
Straight line with tangential connection	APPR LT	DEP LT
Straight line perpendicular to a contour point	APPR LN	DEP LN
Circular arc with tangential connection	APPR CT	DEP CT
Circular arc with tangential connection to the contour. Approach and departure to an auxiliary point outside of the contour on a tangentially connecting line.	APPR LCT	DEP LCT

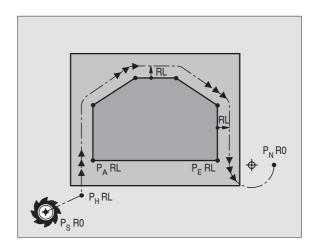
Manual operation	Programming and editing	
2 BLK 3 TOOL 4 L Z+ 5 L X+	FORM 0.1 Z X+0 Y+0 Z-40 FORM 0.2 X+100 Y+100 Z+0 - CALL 1 Z S5000 +250 R0 F MAX +10 Y+5 R0 F100 M3 PGM NEU MM	
9. 6	PR IN APPR CT APPR LCT DEP LT DEP LN DEP CT DE	P LC

#### Approaching and departing a helix

The tool approaches and departs a helix on its extension by moving in a circular arc that connects tangentially to the contour. You program helix approach and departure with the APPR CT and DEP CT functions.

#### Important positions for approach and departure

- Starting point P<sub>S</sub>
  - You program this position in the block before the APPR block. Ps lies outside the contour and is approached without radius compensation (R0).
- Auxiliary point P<sub>H</sub> Some of the paths for approach and departure go through an auxiliary point P<sub>H</sub> that the TNC calculates from your input in the APPR or DEP block.
- First contour point P<sub>A</sub> and last contour point P<sub>E</sub> You program the first contour point P<sub>A</sub> in the APPR block. The last contour point P<sub>E</sub> can be programmed with any path function. If the APPR block also contains a Z axis coordinate, the TNC will first move the tool to P<sub>H</sub> in the working plane, and then move it to the entered depth in the tool axis.



■ End point P<sub>N</sub>
The position P<sub>N</sub> lies outside of the contour and results from your input in the DEP block. If the DEP block also contains a Z axis coordinate, the TNC will first move the tool to P<sub>H</sub> in the working plane, and then move it to the entered depth in the tool axis.

Abbreviation	Meaning
APPR	Approach
DEP	Departure
L	Line
С	Circle
Т	Tangential (smooth connection)
N	Normal (perpendicular)

You can enter the position data in absolute or incremental coordinates and in Cartesian or polar coordinates.

The TNC does not check whether the programmed contour will be damaged when moving from the actual position to the auxiliary point  $P_{\rm H}$ . Use the test graphics to simulate approach and departure before executing the part program.

When approaching the contour, allow sufficient distance between the starting point  $P_S$  and the first contour point  $P_A$  to assure that the TNC will reach the programmed feed rate for machining.

The TNC moves the tool from the actual position to the auxiliary point  $P_H$  at the feed rate that was last programmed.

#### Radius compensation

The tool radius compensation is programmed together with the first contour point  $P_A$  in the APPR block. The DEP blocks automatically remove the tool radius compensation.

Contour approach without radius compensation: If you program the APPR block with R0, the TNC will calculate the tool path for a tool radius of 0 mm and a radius compensation RR! The radius compensation is necessary to set the direction of contour approach and departure in the APPR/DEP LN and APPR/DEP CT functions.

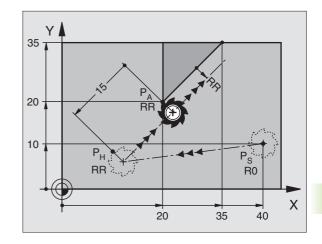
## Approaching on a straight line with tangential connection: APPR LT

The tool moves on a straight line from the starting point  $P_S$  to an auxiliary point  $P_H$ . It then moves to the first contour point  $P_A$  on a straight line that connects tangentially to the contour. The auxiliary point  $P_H$  is separated from the first contour point  $P_A$  by the distance LEN.

- ▶ Use any path function to approach the starting point P<sub>S</sub>.
- ▶ Initiate the dialog with the APPR/DEP key and APPR LT soft key:



- ► Coordinates of the first contour point P<sub>A</sub>
- ▶ LEN: Distance from the auxiliary point P<sub>H</sub> to the first contour point P<sub>A</sub>
- ▶ Radius compensation RR/RL for machining



#### **Example NC blocks**

7 L X+40 Y+10 RO FMAX M3	Approach P <sub>S</sub> without radius compensation
8 APPR LT X+20 Y+20 Z-10 LEN15 RR F100	$P_A$ with radius compensation RR, distance $P_H$ to $P_A$ : LEN=15
9 L Y+35 Y+35	End point of the first contour element
10 L	Next contour element

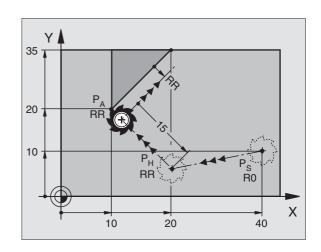
## Approaching on a straight line perpendicular to the first contour point: APPR LN

The tool moves on a straight line from the starting point  $P_S$  to an auxiliary point  $P_H$ . It then to the first contour point  $P_A$  on a straight line perpendicular to the first contour element. The auxiliary point  $P_H$  is separated by the distance LEN plus the tool radius from the first contour point  $P_A$ .

- ▶ Use any path function to approach the starting point P<sub>S</sub>.
- ▶ Initiate the dialog with the APPR/DEP key and APPR LCT soft key:



- ► Coordinates of the first contour point P<sub>A</sub>
- ▶ Length: Distance to the auxiliary point P<sub>H</sub>. Always enter LEN as a positive value!
- ▶ Radius compensation RR/RL for machining



#### **Example NC blocks**

7 L X+40 Y+10 RO FMAX M3	Approach P <sub>S</sub> without radius compensation
8 APPR LN X+10 Y+20 Z-10 LEN15 RR F100	P <sub>A</sub> with radius comp. RR
9 L X+20 Y+35	End point of the first contour element
10 L	Next contour element

i

## Approaching on a circular path with tangential connection: APPR CT

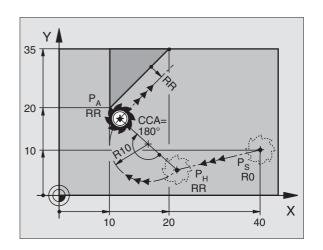
The tool moves on a straight line from the starting point  $P_S$  to an auxiliary point  $P_H$ . It then moves to the first contour point  $P_A$  following a circular arc that is tangential to the first contour element.

The arc from  $P_H$  to  $P_A$  is determined through the radius R and the center angle CCA. The direction of rotation of the circular arc is automatically derived from the tool path for the first contour element.

- ▶ Use any path function to approach the starting point P<sub>S</sub>.
- ▶ Initiate the dialog with the APPR/DEP key and APPR CT soft key:



- ► Coordinates of the first contour point P<sub>A</sub>
- Radius R of the circular arc
  - If the tool should approach the workpiece in the direction defined by the radius compensation: Enter R as a positive value.
  - If the tool should approach the workpiece opposite to the radius compensation: Enter R as a negative value.
- Center angle CCA of the arc
  - CCA can be entered only as a positive value.
  - Maximum input value 360°
- ▶ Radius compensation RR/RL for machining



#### **Example NC blocks**

7 L X+40 Y+10 RO FMAX M3	Approach P <sub>S</sub> without radius compensation	
8 APPR CT X+10 Y+20 Z-10 CCA180 R+10 RR F100	P <sub>A</sub> with radius comp. RR, radius R=10	
9 L X+20 Y+35	End point of the first contour element	
10 L Next contour element		

# Approaching on a circular arc with tangential connection from a straight line to the contour: APPR LCT

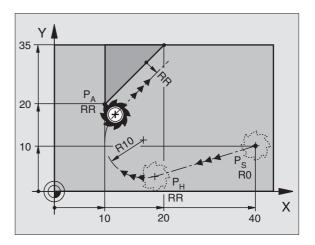
The tool moves on a straight line from the starting point  $P_S$  to an auxiliary point  $P_H$ . It then moves to the first contour point  $P_A$  on a circular arc.

The arc is connected tangentially both to the line  $P_S - P_H$  as well as to the first contour element. Once these lines are known, the radius then suffices to completely define the tool path.

- ▶ Use any path function to approach the starting point P<sub>S</sub>.
- ▶ Initiate the dialog with the APPR/DEP key and APPR LCT soft key:



- $\triangleright$  Coordinates of the first contour point  $P_{\Delta}$
- ▶ Radius R of the circular arc. Enter R as a positive value.
- ▶ Radius compensation RR/RL for machining





#### **Example NC blocks**

7 L X+40 Y+10 RO FMAX M3	Approach P <sub>S</sub> without radius compensation	
APPR LCT X+10 Y+20 Z-10 R10 RR F100 P <sub>A</sub> with radius comp. RR, radius R=10		
9 L X+20 Y+35	End point of the first contour element	
10 L	Next contour element	

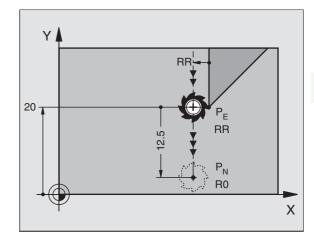
## Departing on a straight line with tangential connection: DEP LT

The tool moves on a straight line from the last contour point  $P_E$  to the end point  $P_N$ . The line lies in the extension of the last contour element.  $P_N$  is separated from  $P_E$  by the distance LEN.

- Program the last contour element with the end point P<sub>E</sub> and radius compensation.
- ▶ Initiate the dialog with the APPR/DEP key and DEP LT soft key:



► LEN: Enter the distance from the last contour element P<sub>F</sub> to the end point P<sub>N</sub>.



#### **Example NC blocks**

23 L Y+20 RR F100	Last contour element: P <sub>E</sub> with radius compensation		
24 DEP LT LEN12.5 F100	Depart contour by LEN=12.5 mm		
25 L Z+100 FMAX M2	Retract in Z, return to block 1, end program		

## Departing on a straight line perpendicular to the last contour point: DEP LN

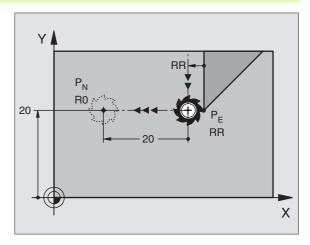
The tool moves on a straight line from the last contour point  $P_E$  to the end point  $P_N$ . The line departs on a perpendicular path from the last contour point  $P_E$ . PN is separated from  $P_E$  by the distance  $_{LEN}$ . plus the tool radius.

- ▶ Program the last contour element with the end point P<sub>E</sub> and radius compensation.
- ▶ Initiate the dialog with the APPR/DEP key and DEP LN soft key:



LEN: Enter the distance from the last contour element  $P_N$ .

Always enterLEN as a positive value!



#### **Example NC blocks**

23 L Y+20 RR F100	Last contour element: P <sub>E</sub> with radius compensation		
24 DEP LN LEN+20 F100	Depart perpendicular to contour by LEN=20 mm		
25 L Z+100 FMAX M2	Retract in Z, return to block 1, end program		

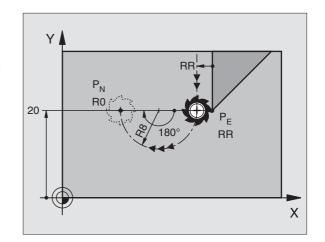
## Departure on a circular path with tangential connection: DEP CT

The tool moves on a circular arc from the last contour point  $P_E$  to the end point  $P_N$ . The arc is tangentially connected to the last contour element.

- Program the last contour element with the end point P<sub>E</sub> and radius compensation.
- ▶ Initiate the dialog with the APPR/DEP key and DEP CT soft key:



- Center angle CCA of the arc
- Radius R of the circular arc
  - If the tool should depart the workpiece in the direction of the radius compensation (i.e. to the right with RR or to the left with RL): Enter R as a positive value.
  - If the tool should depart the workpiece on the direction **opposite** to the radius compensation: Enter R as a negative value.



#### Example NC blocks

23 L Y+20 RR F100	Last contour element: P <sub>E</sub> with radius compensation	
24 DEP CT CCA 180 R+8 F100	Center angle=180°,	
	arc radius=8 mm	
25 L Z+100 FMAX M2	Retract in Z, return to block 1, end program	

# Departing on a circular arc tangentially connecting the contour and a straight line: DEP LCT

The tool moves on a circular arc from the last contour point  $\mathsf{P}_S$  to an auxiliary point  $\mathsf{P}_H$ . It then moves on a straight line to the end point  $\mathsf{P}_N$ . The arc is tangentially connected both to the last contour element and to the line from  $\mathsf{P}_H$  to  $\mathsf{P}_N$ . Once these lines are known, the radius R then suffices to completely define the tool path.

- Program the last contour element with the end point P<sub>E</sub> and radius compensation.
- ▶ Initiate the dialog with the APPR/DEP key and DEP LCT soft key:



- ▶ Enter the coordinates of the end point P<sub>N</sub>.
- ▶ Radius R of the circular arc. Enter R as a positive value.

# P<sub>E</sub> RR RO X

#### **Example NC blocks**

23 L Y+20 RR F100	Last contour element: P <sub>E</sub> with radius compensation		
24 DEP LCT X+10 Y+12 R+8 F100	Coordinates P <sub>N</sub> , arc radius=8 mm		
25 L Z+100 FMAX M2	Retract in Z, return to block 1, end program		

### 6.4 Path Contours — Cartesian **Coordinates**

#### **Overview of path functions**

Function	Path function key	Tool movement	Required input
Line <b>L</b>	LP	Straight line	Coordinates of the end points of the straight line
Chamfer: CHF	CHE o ::Co	Chamfer between two straight lines	Chamfer side length
Circle Center CC	¢ <sup>cc</sup>	No tool movement	Coordinates of the circle center or pole
Circle C	(L)C	Circular arc around a circle center CC to an arc end point	Coordinates of the arc end point, direction of rotation
Circular Arc <b>CR</b>	(CR	Circular arc with a certain radius	Coordinates of the arc end point, arc radius, direction of rotation
Circular Arc CT	СТР	Circular arc with tangential connection to the preceding and subsequent contour elements	Coordinates of the arc end point
Corner Rounding <b>RND</b>	RND <sub>o</sub> o: Lo	Circular arc with tangential connection to the preceding and subsequent contour elements	Rounding-off radius R
<b>FK</b> Free Contour Programming	FK	Straight line or circular path with any connection to the preceding contour element	see "Path Contours—FK Free Contour Programming," page 158

#### Straight line L

The TNC moves the tool in a straight line from its current position to the straight-line end point. The starting point is the end point of the preceding block.



- ▶ Coordinates of the end point of the straight line
- Further entries, if necessary:
- ▶ Radius compensation RL/RR/RO
- Feed rate F
- ► Miscellaneous function M

#### **Example NC blocks**

- 7 L X+10 Y+40 RL F200 M3
- 8 L IX+20 IY-15
- 9 L X+60 IY-10

#### **Actual position capture**

You can also generate a straight-line block (L block) by using the ACTUAL-POSITION-CAPTURE key:

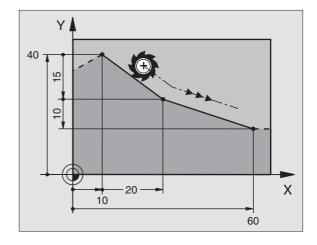
- In the Manual Operation mode, move the tool to the position you wish to capture.
- ▶ Switch the screen display to Programming and Editing.
- Select the program block after which you want to insert the L block.



Press the ACTUAL-POSITION-CAPTURE key: The TNC generates an L block with the actual position coordinates.



In the MOD function, you define the number of axes that the TNC saves in an L block (see "MOD functions," page 418).



## Inserting a chamfer CHF between two straight lines

The chamfer enables you to cut off corners at the intersection of two straight lines.

- The blocks before and after the CHF block must be in the same working plane.
- The radius compensation before and after the chamfer block must be the same.
- An inside chamfer must be large enough to accommodate the current tool.



► Chamfer side length: Length of the chamfer Further entries, if necessary:

▶ Feed rate F (only effective in CHF block)

#### **Example NC blocks**

7 L X+0 Y+30 RL F300 M3

8 L X+40 IY+5

9 CHF 12 F250

10 L IX+5 Y+0

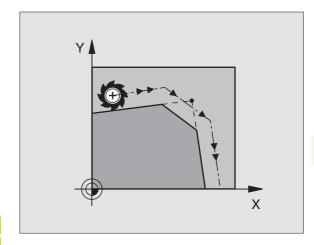


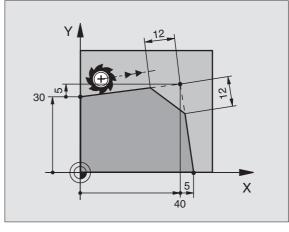
You cannot start a contour with a CHF block.

A chamfer is possible only in the working plane.

The corner point is cut off by the chamfer and is not part of the contour.

A feed rate programmed in the CHF block is effective only in that block. After the CHF block, the previous feed rate becomes effective again.





#### **Corner rounding RND**

The RND function is used for rounding off corners.

The tool moves on an arc that is tangentially connected to both the preceding and subsequent contour elements.

The rounding arc must be large enough to accommodate the tool.



▶ Rounding-off radius: Enter the radius

Further entries, if necessary:

▶ Feed rate F (only effective in RND block)

#### **Example NC blocks**

5 L X+10 Y+40 RL F300 M3

6 L X+40 Y+25

7 RND R5 F100

8 L X+10 Y+5

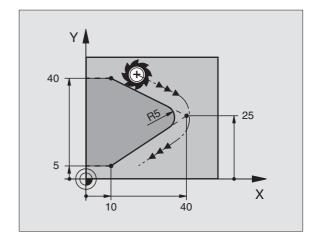


In the preceding and subsequent contour elements, both coordinates must lie in the plane of the rounding arc. If you machine the contour without tool-radius compensation, you must program both coordinates in the working plane.

The corner point is cut off by the rounding arc and is not part of the contour.

A feed rate programmed in the RND block is effective only in that block. After the RND block, the previous feed rate becomes effective again.

You can also use an RND block for a tangential contour approach if you do not want to use an APPR function.



#### Circle center CC

You can define a circle center CC for circles that are programmed with the C key (circular path C). This is done in the following ways:

- Entering the Cartesian coordinates of the circle center, or
- Using the circle center defined in an earlier block, or
- Capturing the coordinates with the ACTUAL-POSITION-CAPTURE key.



▶ Coordinates CC: Enter the circle center coordinates, or

If you want to use the last programmed position, do not enter any coordinates.

#### **Example NC blocks**

5 CC X+25 Y+25

or

10 L X+25 Y+25

11 CC

The program blocks 10 and 11 do not refer to the illustration.

#### **Duration of effect**

The circle center definition remains in effect until a new circle center is programmed. You can also define a circle center for the secondary axes U, V and W.

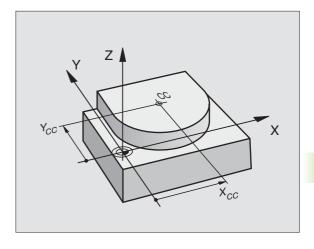
#### Entering the circle center CC incrementally.

If you enter the circle center with incremental coordinates, you have programmed it relative to the last programmed position of the tool.



The only effect of CC is to define a position as circle center: The tool does not move to this position.

The circle center is also the pole for polar coordinates.



#### Circular path C around circle center CC

Before programming a circular path C, you must first enter the circle center CC. The last programmed tool position before the C block is used as the circle starting point.

Move the tool to the circle starting point.



- ▶ Coordinates of the circle center
- Coordinates of the arc end point
- ▶ Direction of rotation DR

Further entries, if necessary:

- ▶ Feed rate F
- ▶ Miscellaneous function M

#### **Example NC blocks**

5 CC X+25 Y+25

6 L X+45 Y+25 RR F200 M3

7 C X+45 Y+25 DR+

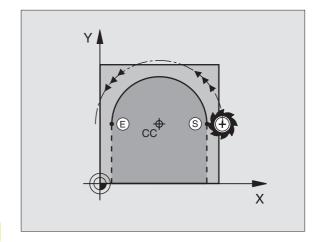
#### **Full circle**

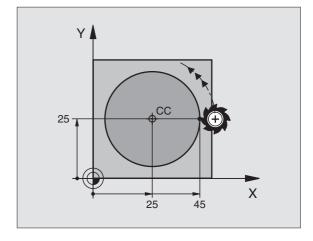
Enter the same point you used as the starting point for the end point in a C block.



The starting and end points of the arc must lie on the circle.

Input tolerance: up to 0.016 mm (selected with MP7431).





#### Circular path CR with defined radius

The tool moves on a circular path with the radius R.



- Coordinates of the arc end point
- Radius R

Note: The algebraic sign determines the size of the arc!

#### Direction of rotation DR

Note: The algebraic sign determines whether the arc is concave or convex!

Further entries, if necessary:

- ▶ Miscellaneous function M
- Feed rate F

#### **Full circle**

For a full circle, program two CR blocks in succession:

The end point of the first semicircle is the starting point of the second. The end point of the second semicircle is the starting point of the first.

#### Central angle CCA and arc radius R

The starting and end points on the contour can be connected with four arcs of the same radius:

Smaller arc: CCA<180°

Enter the radius with a positive sign R>0

Larger arc: CCA>180°

Enter the radius with a negative sign R<0

The direction of rotation determines whether the arc is curving outward (convey) or our ing inward (convey):

outward (convex) or curving inward (concave):

Convex: Direction of rotation DR- (with radius compensation RL)

Concave: Direction of rotation DR+ (with radius compensation RL)

Example NC blocks



11 CR X+70 Y+40 R+20 DR- (arc 1)

or

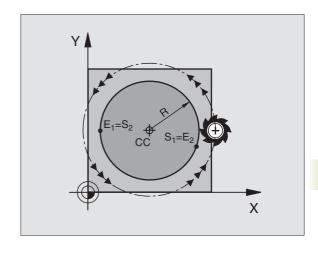
11 CR X+70 Y+40 R+20 DR+ (arc 2)

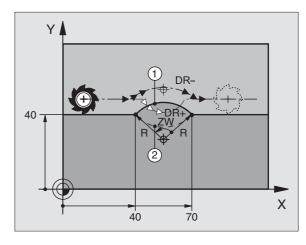
or

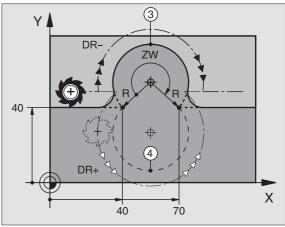
11 CR X+70 Y+40 R-20 DR- (arc 3)

or

11 CR X+70 Y+40 R-20 DR+ (arc 4)









The distance from the starting and end points of the arc diameter cannot be greater than the diameter of the arc.

The maximum radius is 99.9999 m.

You can also enter rotary axes A, B and C.

#### Circular path CT with tangential connection

The tool moves on an arc that starts at a tangent with the previously programmed contour element.

A transition between two contour elements is called tangential when there is no kink or corner at the intersection between the two contours—the transition is smooth.

The contour element to which the tangential arc connects must be programmed immediately before the CT block. This requires at least two positioning blocks.



Coordinates of the arc end point

Further entries, if necessary:

- Feed rate F
- ▶ Miscellaneous function M

#### **Example NC blocks**

7 L X+0 Y+25 RL F300 M3

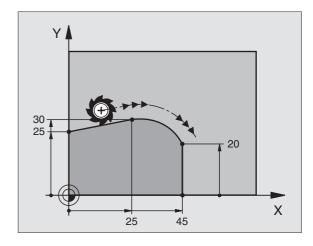
8 L X+25 Y+30

9 CT X+45 Y+20

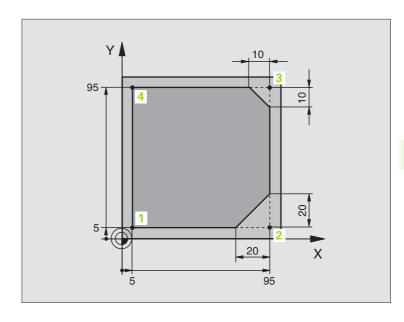
10 L Y+0



A tangential arc is a two-dimensional operation: the coordinates in the CT block and in the contour element preceding it must be in the same plane of the arc.

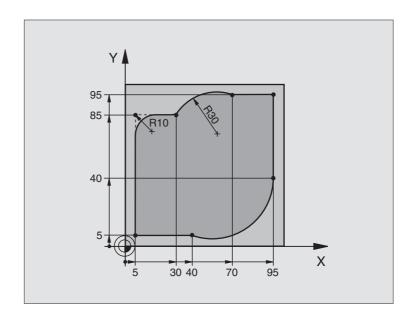


## **Example: Linear movements and chamfers with Cartesian coordinates**



O BEGIN PGM LINEAR MM		
1 BLK FORM 0.1 Z X+0 Y+0 Z-20	Define blank form for graphic workpiece simulation	
2 BLK FORM 0.2 X+100 Y+100 Z+0		
3 TOOL DEF 1 L+0 R+10	Define tool in the program	
4 TOOL CALL 1 Z S4000	Call tool in the spindle axis and with the spindle speed S	
5 L Z+250 RO F MAX	Retract tool in the spindle axis at rapid traverse FMAX	
6 L X-10 Y-10 RO F MAX	Pre-position the tool	
7 L Z-5 RO F1000 M3	Move to working depth at feed rate F = 1000 mm/min	
8 APPR LT X+5 Y+5 LEN10 RL F300	Approach the contour at point 1 on a straight line with	
	tangential connection	
9 L Y+95	Move to point 2	
10 L X+95	Point 3: first straight line for corner 3	
11 CHF 10	Program chamfer with length 10 mm	
12 L Y+5	Point 4: 2nd straight line for corner 3, 1st straight line for corner 4	
13 CHF 20	Program chamfer with length 20 mm	
14 L X+5	Move to last contour point 1, second straight line for corner 4	
15 DEP LT LEN10 F1000	Depart the contour on a straight line with tangential connection	
16 L Z+250 RO F MAX M2	Retract in the tool axis, end program	
17 END PGM LINEAR MM		

## **Example: Circular movements with Cartesian coordinates**

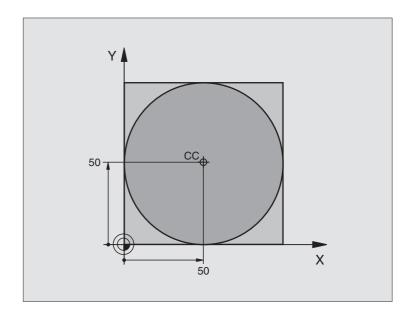


O BEGIN PGM CIRCULAR MM		
1 BLK FORM 0.1 Z X+0 Y+0 Z-20	Define blank form for graphic workpiece simulation	
2 BLK FORM 0.2 X+100 Y+100 Z+0		
3 TOOL DEF 1 L+0 R+10	Define tool in the program	
4 TOOL CALL 1 Z S4000	Call tool in the spindle axis and with the spindle speed S	
5 L Z+250 RO F MAX	Retract tool in the spindle axis at rapid traverse FMAX	
6 L X-10 Y-10 RO F MAX	Pre-position the tool	
7 L Z-5 R0 F1000 M3	Move to working depth at feed rate F = 1000 mm/min	
8 APPR LCT X+5 Y+5 R5 RL F300	Approach the contour at point 1 on a circular arc with	
	tangential connection	
9 L X+5 Y+85	Point 2: first straight line for corner 2	
10 RND R10 F150	Insert radius with R = 10 mm, feed rate: 150 mm/min	
11 L X+30 Y+85	Move to point 3: Starting point of the arc with CR	
12 CR X+70 Y+95 R+30 DR-	Move to point 4: End point of the arc with CR, radius 30 mm	
13 L X+95	Move to point 5	
14 L X+95 Y+40	Move to point 6	
15 CT X+40 Y+5	Move to point 7: End point of the arc, radius with tangential	
	connection to point 6, TNC automatically calculates the radius	

16 L X+5	Move to last contour point 1	
17 DEP LCT X-20 Y-20 R5 F1000	Depart the contour on a circular arc with tangential connection	
18 L Z+250 RO F MAX M2	Retract in the tool axis, end program	
19 END PGM CIRCULAR MM		

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## **Example: Full circle with Cartesian coordinates**



O BEGIN PGM C-CC MM		
1 BLK FORM 0.1 Z X+0 Y+0 Z-20	Define the workpiece blank	
2 BLK FORM 0.2 X+100 Y+100 Z+0		
3 TOOL DEF 1 L+0 R+12.5	Define the tool	
4 TOOL CALL 1 Z S3150	Tool call	
5 CC X+50 Y+50	Define the circle center	
6 L Z+250 RO F MAX	Retract the tool	
7 L X-40 Y+50 RO F MAX	Pre-position the tool	
8 L Z-5 RO F1000 M3	Move to working depth	
9 APPR LCT X+0 Y+50 R5 RL F300	Approach the starting point of the circle on a circular arc with	
	connection	
10 C X+0 DR-	Move to the circle end point (= circle starting point)	
11 DEP LCT X-40 Y+50 R5 F1000	Depart the contour on a circular arc with tangential	
	connection	
12 L Z+250 RO F MAX M2	Retract in the tool axis, end program	
13 END PGM CCC MM		

# 6.5 Path Contours — Polar Coordinates

#### Overview

With polar coordinates you can define a position in terms of its angle PA and its distance PR relative to a previously defined pole CC (see "Fundamentals," page 158).

Polar coordinates are useful with:

- Positions on circular arcs
- Workpiece drawing dimensions in degrees, e.g. bolt hole circles

#### Overview of path functions with polar coordinates

Function	Path function key	Tool movement	Required input
Line <b>LP</b>	* P	Straight line	Polar radius, polar angle of the straight-line end point
Circular arc CP	\( \gamma^c \) + \( \bar{P} \)	Circular path around circle center/ pole CC to arc end point	Polar angle of the arc end point, direction of rotation
Circular arc CTP	ст <i>у</i> + Р	Circular arc with tangential connection to the preceding contour element	Polar radius, polar angle of the arc end point
Helical interpolation	(3c) + (P)	Combination of a circular and a linear movement	Polar radius, polar angle of the arc end point, coordinate of the end point in the tool axis

#### Polar coordinate origin: Pole CC

You can define the pole CC anywhere in the part program before blocks containing polar coordinates. Enter the pole in Cartesian coordinates as a circle center in a CC block.

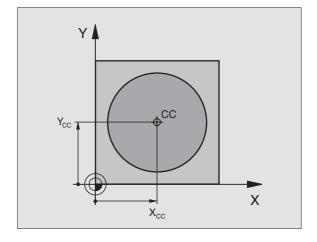


▶ Coordinates CC: Enter Cartesian coordinates for the pole, or

If you want to use the last programmed position, do not enter any coordinates. Before programming polar coordinates, define the pole CC. You can only define the pole CC in Cartesian coordinates. The pole CC remains in effect until you define a new pole CC.

#### **Example NC blocks**

12 CC X+45 Y+25



#### Straight line LP

The tool moves in a straight line from its current position to the straight-line end point. The starting point is the end point of the preceding block.



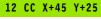


- ▶ Polar coordinates radius PR: Enter the distance from the pole CC to the straight-line end point.
- ▶ Polar coordinates angle PA: Angular position of the straight-line end point between -360° and +360°.

The sign of PA depends on the angle reference axis:

- Angle from angle reference axis to PR is counterclockwise: PA>0
- Angle from angle reference axis to PR is clockwise: PA<0

#### **Example NC blocks**

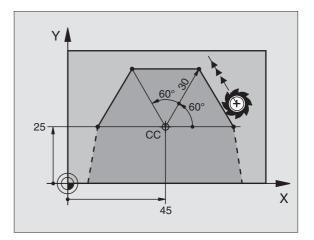


13 LP PR+30 PA+0 RR F300 M3

14 LP PA+60

15 LP IPA+60

16 LP PA+180



#### Circular path CP around pole CC

The polar coordinate radius PR is also the radius of the arc. It is defined by the distance from the starting point to the pole CC. The last programmed tool position before the CP block is the starting point of the arc.





- ▶ Polar-coordinates angle PA: Angular position of the arc end point between −5400° and +5400°
- Direction of rotation DR

#### **Example NC blocks**

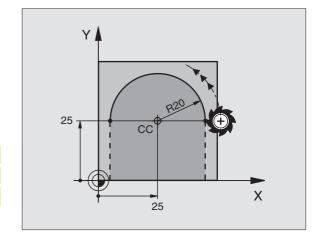
18 CC X+25 Y+25

19 LP PR+20 PA+0 RR F250 M3

20 CP PA+180 DR+



For incremental coordinates, enter the same sign for DR and PA.



#### **Circular path CTP with tangential connection**

The tool moves on a circular path, starting tangentially from a preceding contour element.





- ▶ Polar coordinates radius PR: Distance from the arc end point to the pole CC
- ▶ Polar coordinates angle PA: Angular position of the arc end point

#### **Example NC blocks**

12 CC X+40 Y+35
13 L X+0 Y+35 RL F250 M3
14 LP PR+25 PA+120
15 CTP PR+30 PA+30
16 L Y+0



The pole CC is **not** the center of the contour arc!

#### **Helical interpolation**

A helix is a combination of a circular movement in a main plane and a liner movement perpendicular to this plane.

A helix is programmed only in polar coordinates.

#### **Application**

angle IPA

- Large-diameter internal and external threads
- Lubrication grooves

#### Calculating the helix

To program a helix, you must enter the total angle through which the tool is to move on the helix in incremental dimensions, and the total height of the helix.

For calculating a helix that is to be cut in a upward direction, you need the following data:

Thread revolutions n Thread revolutions + thread overrun at

the start and end of the thread

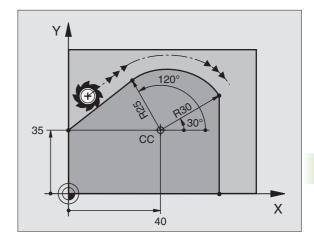
Total height h Thread pitch P times thread revolutions n Incremental total Number of revolutions times 360° + angle for

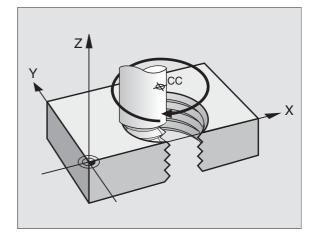
beginning of thread + angle for thread

overrun

Starting coordinate Z Pitch P times (thread revolutions + thread

overrun at start of thread)





#### Shape of the helix

The table below illustrates in which way the shape of the helix is determined by the work direction, direction of rotation and radius compensation.

Internal thread	Work direction	Direction	Radius comp.
Right-handed	Z+	DR+	RL
Left-handed	Z+	DR-	RR
Right-handed	Z–	DR	RR
Left-handed	Z–	DR+	RL

External thread			
Right-handed	Z+	DR+	RR
Left-handed	Z+	DR-	RL
Right-handed	Z–	DR	RL
Left-handed	Z–	DR+	RR

#### Programming a helix



Always enter the same algebraic sign for the direction of rotation DR and the incremental total angle IPA. The tool may otherwise move in a wrong path and damage the contour.

For the total angle IPA, you can enter a value from -5400° to +5400°. If the thread has more than 15 revolutions, program the helix in a program section repeat (see "Program Section Repeats," page 344)

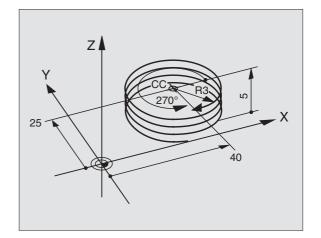




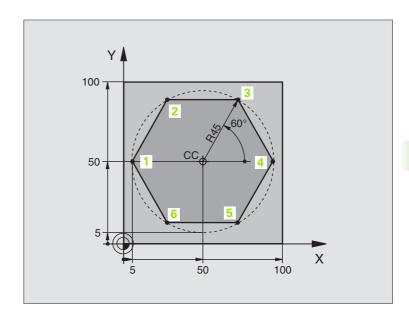
- ▶ Polar coordinates angle: Enter the total angle of tool traverse along the helix in incremental dimensions. After entering the angle, identify the tool axis with an axis selection key.
- ▶ Coordinate: Enter the coordinate for the height of the helix in incremental dimensions.
- Direction of rotation DR Clockwise helix: DR-Counterclockwise helix: DR+
- ▶ Radius compensation RL/RR/RO Enter the radius compensation according to the table above.

Example NC blocks: Thread M6 x 1 mm with 5 revolutions

- 12 CC X+40 Y+25 13 L Z+0 F100 M3
- 14 LP PR+3 PA+270 RL F50
- 15 CP IPA-1800 IZ+5 DR-



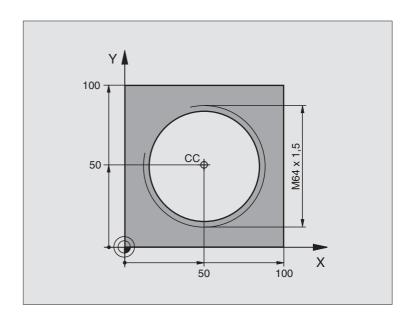
# **Example: Linear movement with polar coordinates**



O BEGIN PGM LINEARPO MM	
1 BLK FORM 0.1 Z X+0 Y+0 Z-20	Define the workpiece blank
2 BLK FORM 0.2 X+100 Y+100 Z+0	
3 TOOL DEF 1 L+0 R+7.5	Define the tool
4 T00L CALL 1 Z S4000	Tool call
5 CC X+50 Y+50	Define the datum for polar coordinates
6 L Z+250 RO F MAX	Retract the tool
7 LP PR+60 PA+180 RO F MAX	Pre-position the tool
8 L Z-5 RO F1000 M3	Move to working depth
9 APPR PLCT PR+45 PA+180 R5 RL F250	Approach the contour at point 1 on a circular arc with
	tangential connection
10 LP PA+120	Move to point 2
11 LP PA+60	Move to point 3
12 LP PA+0	Move to point 4
13 LP PA-60	Move to point 5
14 LP PA-120	Move to point 6
15 LP PA+180	Move to point 1
16 DEP PLCT PR+60 PA+180 R5 F1000	Depart the contour on a circular arc with tangential connection
17 L Z+250 RO F MAX M2	Retract in the tool axis, end program
18 END PGM LINEARPO MM	

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# **Example: Helix**



O BEGIN PGM HELIX MM	
1 BLK FORM 0.1 Z X+0 Y+0 Z-20	Define the workpiece blank
2 BLK FORM 0.2 X+100 Y+100 Z+0	
3 TOOL DEF 1 L+0 R+5	Define the tool
4 TOOL CALL 1 Z S1400	Tool call
5 L Z+250 R0 F MAX	Retract the tool
6 L X+50 Y+50 RO F MAX	Pre-position the tool
7 CC	Transfer the last programmed position as the pole
8 L Z-12.75 RO F1000 M3	Move to working depth
9 APPR PCT PR+32 PA-180 CCA180 R+2	Approach the contour on a circular arc with tangential
RL F100	connection
10 CP IPA+3240 IZ+13.5 DR+ F200	Helical interpolation
11 DEP CT CCA180 R+2	Depart the contour on a circular arc with tangential connection
12 L Z+250 RO F MAX M2	Retract in the tool axis, end program
13 END PGM HELIX MM	

To cut a thread with more than 16 revolutions

L Z-12.75 RO F1000

9 APPR PCT PR+32 PA-180 CCA180 R+2 RL F100

10 LBL 1	Identify beginning of program section repeat
11 CP IPA+360 IZ+1.5 DR+ F200	Enter the thread pitch as an incremental IZ dimension
12 CALL LBL 1 REP 24	Program the number of repeats (thread revolutions)
13 DEP CT CCA180 R+2	

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# 6.6 Path Contours—FK Free Contour Programming

# **Fundamentals**

Workpiece drawings that are not dimensioned for NC often contain unconventional coordinate data that cannot be entered with the gray path function keys. You may, for example, have only the following data on a specific contour element:

- Known coordinates on the contour element or in its proximity
- Coordinate data that are referenced to another contour element
- Directional data and data regarding the course of the contour

You can enter such dimensional data directly by using the FK free contour programming function. The TNC derives the contour from the known coordinate data and supports the programming dialog with the interactive programming graphics. The figure to the upper right shows a workpiece drawing for which FK programming is the most convenient programming method.

If you wish to run FK programs on old TNC models, use the conversion function (see "Converting an FK program into HEIDENHAIN conversational format," page 47).



# The following prerequisites for FK programming FK programming

The FK free contour programming feature can only be used for programming contour elements that lie in the working plane. The working plane is defined in the first BLK FORM block of the part program.

You must enter all available data for every contour element. Even the data that does not change must be entered in every block - otherwise it will not be recognized.

Q parameters are permissible in all FK elements, except in elements with relative references (e.g. RX or RAN), or in elements that are referenced to other NC blocks.

If both FK blocks and conventional blocks are entered in a program, the FK contour must be fully defined before you can return to conventional programming.

The TNC needs a fixed point from which it can calculate the contour elements. Use the gray path function keys to program a position that contains both coordinates of the working plane immediately before programming the FK contour. Do not enter any Q parameters in this block.

If the first block of an FK contour is an FCT or FLT block, you must program at least two NC block with the gray path function keys to fully define the direction of contour approach.

Do not program an FK contour immediately after an LBL label.

# **Graphics during FK programming**



If you wish to use graphic support during FK programming, select the PGM + GRAPHICS screen layout (see "Program Run, Full Sequence and Program Run, Single Block," page 8).

Incomplete coordinate data often are not sufficient to fully define a workpiece contour. In this case, the TNC indicates the possible solutions in the FK graphic. You can then select the contour that matches the drawing. The FK graphic displays the elements of the workpiece contour in different colors:

**White** The contour element is fully defined.

**Green** The entered data describe a limited number of possible

solutions: select the correct one.

**Red** The entered data are not sufficient to determine the

contour element: enter further data.

If the entered data permit a limited number of possible solutions and the contour element is displayed in green, select the correct contour element as follows:

SHOW SOLUTION Press the SHOW soft key repeatedly until the correct contour element is displayed.



▶ If the displayed contour element matches the drawing, select the contour element with FSELECT.

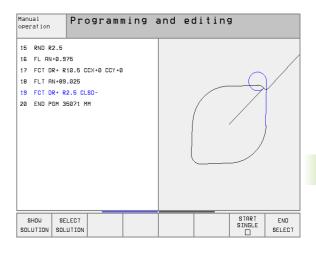
Select the green contour elements as soon as possible with the FSELECT soft key. In this way, you can reduce the ambiguity of subsequent elements.

If you do not yet wish to select a green contour element, press the EDIT soft key to continue the FK dialog.



The machine tool builder may use other colors for the FK graphics.

NC blocks from a program that you called with PGM CALL are displayed in another color.



# Initiating the FK dialog

If you press the gray FK button, the TNC displays the soft keys you can use to initiate an FK dialog: See the following table. Press the FK button a second time to deselect the soft keys.

If you initiate the FK dialog with one of these soft keys, the TNC shows additional soft-key rows that you can use for entering known coordinates, directional data and data regarding the course of the contour.

Contour element	Soft key
Straight line with tangential connection	FLT
Straight line without tangential connection	FL
Circular arc with tangential connection	FCT
Circular arc without tangential connection	FC
Pole for FK programming	FPOL

# Free programming of straight lines

# Straight line without tangential connection



➤ To display the soft keys for free contour programming, press the FK key.



- ➤ To initiate the dialog for free programming of straight lines, press the FL soft key. The TNC displays additional soft keys.
- ▶ Enter all known data in the block by using these soft keys. The FK graphic displays the programmed contour element in red until sufficient data are entered. If the entered data describe several solutions, the graphic will display the contour element in green (see "Graphics during FK programming," page 159).

# Straight line with tangential connection

If the straight line connects tangentially to another contour element, initiate the dialog with the FLT soft key:



➤ To display the soft keys for free contour programming, press the FK key.



- To initiate the dialog, press the FLT soft key.
- ▶ Enter all known data in the block by using the soft keys.

# Free programming of circular arcs

# Circular arc without tangential connection



▶ To display the soft keys for free contour programming, press the FK key.



- ▶ To initiate the dialog for free programming of circular arcs, press the FC soft key. The TNC displays soft keys with which you can enter direct data on the circular arc or data on the circle center.
- ▶ Enter all known data in the block by using these soft keys. The FK graphic displays the programmed contour element in red until sufficient data are entered. If the entered data describe several solutions, the graphic will display the contour element in green (see "Graphics during FK programming," page 159).

# Circular arc with tangential connection

If the circular arc connects tangentially to another contour element, initiate the dialog with the FCT soft key:



To display the soft keys for free contour programming, press the FK key.



- ▶ To initiate the dialog, press the FCT soft key.
- Enter all known data in the block by using the soft keys.



# Input possibilities

# **End point coordinates**

Known data	Soft keys	
Cartesian coordinates X and Y	X	† Y
Polar coordinates referenced to FPOL	PR	PA

# **Example NC blocks**

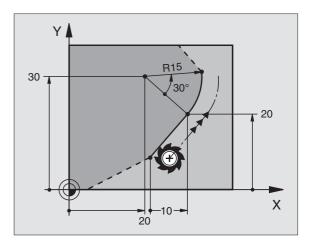
7 FPOL X+20 Y+30

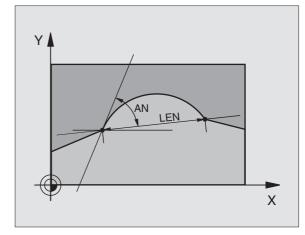
8 FL IX+10 Y+20 RR F100

9 FCT PR+15 IPA+30 DR+ R15

# Direction and length of contour elements

Known data	Soft keys
Length of a straight line	LEN
Gradient angle of a straight line	AN
Chord length LEN of the arc	LEN
Gradient angle AN of the entry tangent	AN
Angle of the leading axis to the arc end point	₹CCA



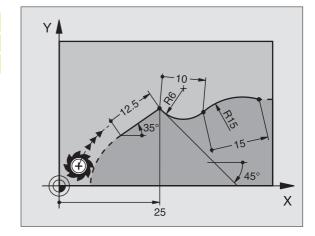


# **Example NC blocks**

27 FLT X+25 LEN 12.5 AN+35 RL F200

28 FC DR+ R6 LEN 10 A-45

29 FCT DR- R15 LEN 15



# Circle center CC, radius and direction of rotation in the FC/FCT block

The TNC calculates a circle center for free-programmed arcs from the data you enter. This makes it possible to program full circles in an FK program block.

If you wish to define the circle center in polar coordinates you must use FPOL, not CC, to define the pole. FPOL is entered in Cartesian coordinates and remains in effect until the TNC encounters a block in which another FPOL is defined.

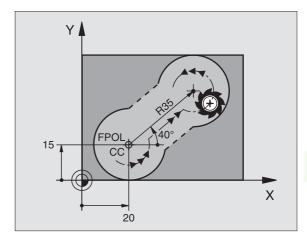


A circle center that was calculated or programmed conventionally is then no longer valid as a pole or circle center for the new FK contour: If you enter conventional polar coordinates that refer to a pole from a CC block you have defined previously, then you must enter the pole again in a CC block after the FK contour.

Known data	Soft keys
Circle center in Cartesian coordinates	ССХ
Circle center in polar coordinates	CC PR PR
Rotational direction of the arc	CC AP
Radius of the arc	CC #

Example NC blocks

10 FC CCX+20 CCY+15 DR+ R15
11 FPOL X+20 Y+15
12 FL AN+40
13 FC DR+ R15 CCPR+35 CCPA+40



### **Closed contours**

You can identify the beginning and end of a closed contour with the CLSD soft key. This reduces the number of possible solutions for the last contour element.

Enter CLSD as an addition to another contour data entry in the first and last blocks of an FK section.

+ CLSD

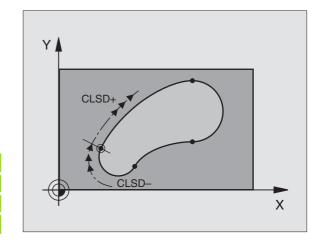
Beginning of contour: CLSD+ End of contour: CLSD-

Example NC blocks

12 L X+5 Y+35 RL F500 M3

13 FC DR- R15 CLSD CCX+20 CCY+35
...

17 FCT DR- R+15 CLSD-



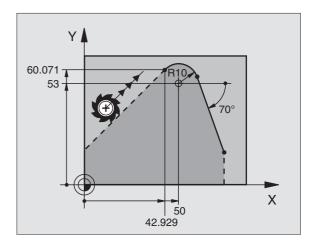
# **Auxiliary points**

You can enter the coordinates of auxiliary points that are located on the contour or in its proximity for both free-programmed straight lines and free-programmed circular arcs.

# Auxiliary points on a contour

The auxiliary points are located on a straight line or on the extension of a straight line, or on a circular arc.

Known data	Soft keys		
X coordinate of an auxiliary point P1 or P2 of a straight line	P1X	P2X	
Y coordinate of an auxiliary point P1 or P2 of a straight line	P1Y	P2Y	
X coordinate of an auxiliary point P1, P2 or P3 of a circular arc	P1X	PZX	РЗХ
Y coordinate of an auxiliary point P1, P2 or P3 of a circular arc	P1Y	PZY	РЗҮ



# Auxiliary points near a contour

Known data	Soft keys	
X and Y coordinates of an auxiliary point near a straight line	PDX	PDY
Distance auxiliary point/straight line	D	

# Known data Soft keys X and Y coordinates of an auxiliary pointnear a circular arc PDX Distance auxiliary point/circular arc Distance auxiliary point/circular arc

# Example NC blocks

13 FC DR- R10 P1X+42.929 P1Y+60.071
14 FLT AN-70 PDX+50 PDY+53 D10

# Relative data

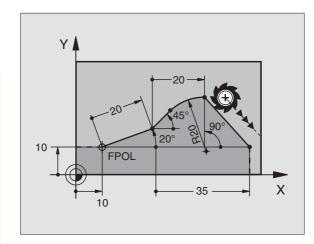
Data whose values are based on another contour element are called relative data. The soft keys and program words for entries begin with the letter "R" for Relative. The figure at right shows the entries that should be programmed as relative data.



The coordinates and angles for relative data are always programmed in incremental dimensions. You must also enter the block number of the contour element on which the data are based.

The block number of the contour element on which the relative data are based can only be located up to 64 positioning blocks before the block in which you program the reference.

If you delete a block on which relative data are based, the TNC will display an error message. Change the program first before you delete the block.



# Data relative to block N: End point coordinates

Known data	Soft keys
Cartesian coordinates relative to block N	RX N
Polar coordinates relative to block N	RPRN

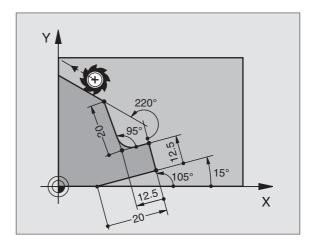
# **Example NC blocks**

12 FPOL X+10 Y+10
13 FL PR+20 PA+20
14 FL AN+45
15 FCT IX+20 DR- R20 CCA+90 RX 13
16 FL IPR+35 PA+0 RPR 13



# Data relative to block N: Direction and distance of the contour element

Known data	Soft key		
Angle between a straight line and another element or between the entry tangent of the arc and another element	RANN		
Straight line parallel to another contour element	PARN		
Distance from a straight line to a parallel contour element	\frac{□P}{}		
Example NC blocks			
17 FL LEN 20 AN+15			
18 FL AN+105 LEN 12.5			
19 FL PAR 17 DP 12.5			
20 FSELECT 2			



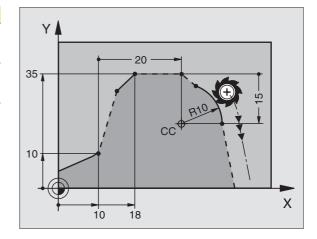
# Data relative to block N: Circle center CC

Known data	Soft key	
Cartesian coordinates of the circle center relative to block N	RCCXN	RCCY N
Polar coordinates of the circle center relative to block N	RCCPRN	RCCPAN

Example NC blocks

21 FL LEN 20 IAN+95
22 FL IAN+220 RAN 18

12 FL X+10 Y+10 RL
13 FL
14 FL X+18 Y+35
15 FL
16 FL
17 FC DR- R10 CCA+0 ICCX+20 ICCY-15 RCCX12 RCCY14



# **Converting FK programs**

You can convert an FK program into HEIDENHAIN conversational format by using the file manager:

- ► Call the file manager and display the files.
- Move the highlight to the file you wish to convert.



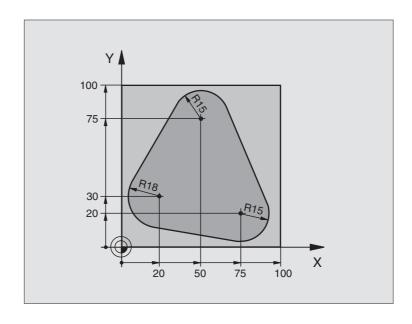
▶ Press the soft keys MORE FUNCTIONS and then CONVERT FK->H. The TNC converts all FK blocks into HEIDENHAIN dialog blocks.



Circle centers that you have entered before programming an FK contour may need to be redefined in the converted program. We recommend that you test the converted part program before executing it.

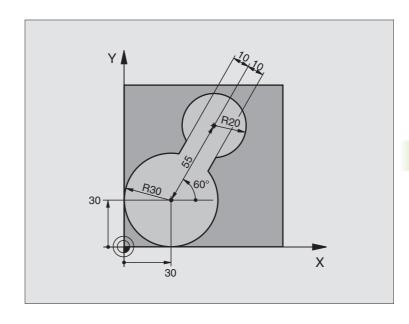
FK programs with Q parameters cannot be converted.

# **Example: FK programming 1**



1 BLK FORM 0.1 Z X+0 Y+0 Z-20 Define the workpiece blank 2 BLK FORM 0.2 X+100 Y+100 Z+0
2 RIK FORM 0 2 Y±100 V±100 7±0
Z DER TORM 0.2 X-100 1-100 Z-0
3 TOOL DEF 1 L+0 R+10 Define the tool
4 TOOL CALL 1 Z S500 Tool call
5 L Z+250 RO F MAX Retract the tool
6 L X-20 Y+30 R0 F MAX Pre-position the tool
7 L Z-10 R0 F1000 M3 Move to working depth
8 APPR CT X+2 Y+30 CCA90 R+5 RL F250 Approach the contour on a circular arc with tangential connecti
9 FC DR- R18 CLSD+ CCX+20 CCY+30 FK contour:
10 FLT Program all known data for each contour element
11 FCT DR- R15 CCX+50 CCY+75
12 FLT
13 FCT DR- R15 CCX+75 CCY+20
14 FLT
15 FCT DR- R18 CLSD- CCX+20 CCY+30
16 DEP CT CCA90 R+5 F1000 Depart the contour on a circular arc with tangential connection
17 L X-30 Y+0 R0 F MAX
18 L Z+250 RO F MAX M2 Retract in the tool axis, end program
19 END PGM FK1 MM

# **Example: FK programming 2**

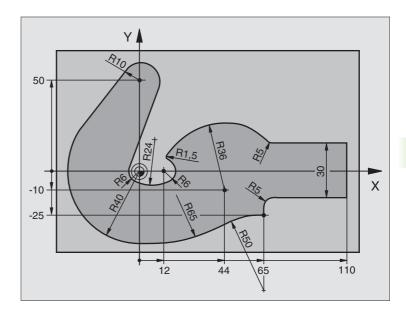


O BEGIN PGM FK2 MM	
1 BLK FORM 0.1 Z X+0 Y+0 Z-20	Define the workpiece blank
2 BLK FORM 0.2 X+100 Y+100 Z+0	
3 TOOL DEF 1 L+0 R+2	Define the tool
4 TOOL CALL 1 Z S4000	Tool call
5 L Z+250 RO F MAX	Retract the tool
6 L X+30 Y+30 RO F MAX	Pre-position the tool
7 L Z+5 RO F MAX M3	Pre-position the tool in the tool axis
8 L Z-5 R0 F100	Move to working depth

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9 APPR LCT X+0	Y+30 R5 RR F350	Approach the contour on a circular arc with tangential connection
10 FPOL X+30 Y+	30	FK contour:
11 FC DR- R30 C	CX+30 CCY+30	Program all known data for each contour element
12 FL AN+60 PDX	+30 PDY+30 D10	
13 FSELECT 3		
14 FC DR- R20 C	CPR+55 CCPA+60	
15 FSELECT 2		
16 FL AN-120 PD	X+30 PDY+30 D10	
17 FSELECT 3		
18 FC X+0 DR- R	30 CCX+30 CCY+30	
19 FSELECT 2		
20 DEP LCT X+30	Y+30 R5	Depart the contour on a circular arc with tangential connection
21 L Z+250 R0 F	MAX M2	Retract in the tool axis, end program
22 END PGM FK2	MM	

# **Example: FK programming 3**



O BEGIN PGM FK3 MM	
1 BLK FORM 0.1 Z X-45 Y-45 Z-20	Define the workpiece blank
2 BLK FORM 0.2 X+120 Y+70 Z+0	
3 TOOL DEF 1 L+0 R+3	Define the tool
4 TOOL CALL 1 Z S4500	Tool call
5 L Z+250 RO F MAX	Retract the tool
6 L X-70 Y+0 R0 F MAX	Pre-position the tool
7 L Z-5 RO F1000 M3	Move to working depth

8 APPR CT X-40 Y+0 CCA90 R+5 RL F250	Approach the contour on a circular arc with tangential connection		
9 FC DR- R40 CCX+0 CCY+0	FK contour:		
10 FLT	Program all known data for each contour element		
11 FCT DR- R10 CCX+0 CCY+50			
12 FLT			
13 FCT DR+ R6 CCX+0 CCY+0			
14 FCT DR+ R24			
15 FCT DR+ R6 CCX+12 CCY+0			
16 FSELECT 2			
17 FCT DR- R1.5			
18 FCT DR- R36 CCX+44 CCY-10			
19 FSELECT 2			
20 FCT DR+ R5			
21 FLT X+110 Y+15 AN+0			
22 FL AN-90			
23 FL X+65 AN+180 PAR21 DP30			
24 RND R5			
25 FL X+65 Y-25 AN-90			
26 FC DR+ R50 CCX+65 CCY-75			
27 FCT DR- R65			
28 FSELECT			
29 FCT Y+0 DR- R40 CCX+0 CCY+0			
30 FSELECT 4			
31 DEP CT CCA90 R+5 F1000	Depart the contour on a circular arc with tangential connection		
32 L X-70 RO F MAX			
33 L Z+250 RO F MAX M2	Retract in the tool axis, end program		
34 END PGM FK3 MM			

# 6.7 Path Contours — Spline Interpolation

# **Function**

If you wish to machine contours that are described in a CAD system as splines, you can transfer them directly to the TNC and execute them. The TNC features a spline interpolator for executing third-degree polynomials in two, three, four, or five axes.



You cannot edit spline blocks in the TNC. Exception: Feed rate **F** and miscellaneous function **M** in the spline block.

# **Example: Block format for two axes**

7 L X+33.909 Z+75.107 F MAX	Spline starting point
8 SPL X+39.824 Z+77.425	Spline end point
K3X+0.0983 K2X-0.441 K1X-5.5724	Spline parameters for X axis
K3Z+0.0015 K2Z-0.9549 K1Z+3.0875 F10000	Spline parameters for Z axis
9 SPL X+44.862 Z+73.44	Spline end point
K3X+0.0934 K2X-0.7211 K1X-4.4102	Spline parameters for X axis
K3Z-0.0576 K2Z-0.7822 K1Z+4.8246	Spline parameters for Z axis
10	

The TNC executes the spline block according to the following third-degree polynomials:

$$X(t) = K3X \cdot t^3 + K2X \cdot t^2 + K1X \cdot t + X$$

$$Z(t) = K3Z \cdot t^3 + K2Z \cdot t^2 + K1Z \cdot t + Z$$

whereby the variable t runs from 1 to 0. The incrementation of t depends on the feed rate and the length of the spline.

# **Example: Block format for five axes**

7 L X+33.909 Y-25.838 Z+75.107 A+17 B-10.103 F MAX	Spline starting point
8 SPL X+39.824 Y-28.378 Z+77.425 A+17.32 B-12.75	Spline end point
K3X+0.0983 K2X-0.441 K1X-5.5724	Spline parameters for X axis
K3Y-0.0422 K2Y+0.1893 K1Y+2.3929	Spline parameters for Y axis
K3Z+0.0015 K2Z-0.9549 K1Z+3.0875	Spline parameters for Z axis
K3A+0.1283 K2A-0.141 K1A-0.5724	Spline parameters for A axis
K3B+0.0083 K2B-0.413 E+2 K1B-1.5724 E+1 F10000	Spline parameters for B axis with
	exponential notation
9	

The TNC executes the spline block according to the following thirddegree polynomials:

$$X(t) = K3X \cdot t^3 + K2X \cdot t^2 + K1X \cdot t + X$$

$$Y(t) = K3Y \cdot t^3 + K2Y \cdot t^2 + K1Y \cdot t + Y$$

$$Z(t) = K3Z \cdot t^3 + K2Z \cdot t^2 + K1Z \cdot t + Z$$

$$A(t) = K3A \cdot t^3 + K2A \cdot t^2 + K1A \cdot t + A$$

$$B(t) = K3B \cdot t^3 + K2B \cdot t^2 + K1B \cdot t + B$$

whereby the variable t runs from 1 to 0. The incrementation of t depends on the feed rate and the length of the spline.



For every end-point coordinate in the spline block, the spline parameters K3 to K1 must be programmed. The end-point coordinates can be programmed any sequence within the spline block.

The TNC always expects the spline parameters K for each axis in the sequence K3, K2, K1.

Besides the principal axes X, Y and Z the TNC can also process the secondary axes U, V and W, and the rotary axes A, B and C. The respective corresponding axis must then be programmed in the spline parameter K (e.g. K3A+0.0953 K2A-0.441 K1A+0.5724).

If the absolute value of a spline parameter K becomes greater than 9.999 999, then the post processor must output K in exponential notation (e.g. K3X+1.2750 E2).

The TNC can execute a program with spline blocks even when the working plane is tilted.

Ensure that the transitions from one spline to the next are as tangential as possible (directional changes of less than 0.1°). The TNC otherwise performs an exact stop if the filter functions are disabled, resulting in a jolting of the machine tool. If the filter functions are active, the TNC decreases the feed rate accordingly at these positions.

# Input ranges

- Spline end point: -99 999.9999 to +99 999.9999
- Spline parameter K: -9.999 999 99 to +9.999 999 99
- Exponent for spline parameter K: -255 to +255 (whole number).





Programming: Miscellaneous functions

# 7.1 Entering Miscellaneous Functions M and STOP

# **Fundamentals**

With the TNC's miscellaneous functions – also called M functions – you can affect:

- Program run, e.g., a program interruption
- Machine functions, such as switching spindle rotation and coolant supply on and off
- Contouring behavior of the tool



The machine tool builder may add some M functions that are not described in this User's Manual. Refer to your machine manual.

You can enter up to two M functions at the end of a positioning block. The TNC then displays the following dialog question:

#### Miscellaneous function M ?

You usually enter only the number of the M function in the programming dialog. Some M functions can be programmed with additional parameters. In this case, the dialog is continued for the parameter input.

In the Manual Operation and Electronic Handwheel modes of operation, the M functions are entered with the M soft key.

Please note that some F functions become effective at the start of a positioning block, and others at the end.

M functions come into effect in the block in which they are called. Unless the M function is only effective blockwise, it is canceled in a subsequent block or at the end of the program. Some M functions are effective only in the block in which they are called.

# Entering an M function in a STOP block

If you program a STOP block, the program run or test run is interrupted at the block, for example for tool inspection. You can also enter an M function in a STOP block:



- To program an interruption of program run, press the STOP key
- ▶ Enter miscellaneous function M

Example NC blocks

87 STOP M6



# 7.2 Miscellaneous Functions for Program Run Control, Spindle and Coolant

# Overview

M	Effect	Effective at block -	start	end
M00	Stop program r Spindle STOP Coolant OFF	run		
M01	Optional progra	am STOP		-
M02	Stop program r Spindle STOP Coolant OFF Go to block 1 Clear the statu on machine pa	s display (dependent		
M03	Spindle ON clo	ckwise		
M04	Spindle ON co	unterclockwise		
M05	Spindle STOP			-
M06	Tool change Spindle STOP Program run st machine param	op (dependent on neter 7440)		
M08	Coolant ON			
M09	Coolant OFF			-
M13	Spindle ON clo Coolant ON	ckwise	-	
M14	Spindle ON coo Coolant ON	unterclockwise		
M30	Same as M02			



# 7.3 Miscellaneous Functions for Coordinate Data

# Programming machine-referenced coordinates: M91/M92

# Scale reference point

On the scale, a reference mark indicates the position of the scale reference point.

### Machine datum

The machine datum is required for the following tasks:

- Defining the limits of traverse (software limit switches)
- Moving to machine-referenced positions (such as tool change positions)
- Setting the workpiece datum

The distance in each axis from the scale reference point to the machine datum is defined by the machine tool builder in a machine parameter.

# Standard behavior

The TNC references coordinates to the workpiece datum, see "Datum Setting(Without a 3-D Touch Probe)," page 22.

#### Behavior with M91 - Machine datum

If you want the coordinates in a positioning block to be referenced to the machine datum, end the block with M91.

The coordinate values on the TNC screen are referenced to the machine datum. Switch the display of coordinates in the status display to REF, see "Status Displays," page 9.

### Behavior with M92 - Additional machine datum



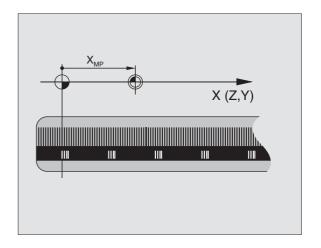
In addition to the machine datum, the machine tool builder can also define an additional machine-based position as a reference point.

For each axis, the machine tool builder defines the distance between the machine datum and this additional machine datum. Refer to the machine manual for more information.

If you want the coordinates in a positioning block to be based on the additional machine datum, end the block with M92.



Radius compensation remains the same in blocks that are programmed with M91 or M92. The tool length, however, is **not** compensated.



### **Effect**

M91 and M92 are effective only in the blocks in which they are programmed.

M91 and M92 take effect at the start of block.

# Workpiece datum

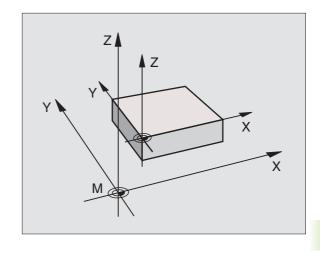
If you want the coordinates to always be referenced to the machine datum, you can inhibit datum setting for one or more axes.

If datum setting is inhibited for all axes, the TNC no longer displays the soft key DATUM SET in the Manual Operation mode.

The figure at right shows coordinate systems with the machine datum and workpiece datum.

### M91/M92 in the test run mode

In order to be able to graphically simulate M91/M92 movements, you need to activate working space monitoring and display the workpiece blank referenced to the set datum see "Showing the workpiece in the working space," page 435.



# Activating the most recently entered datum: M104

# **Function**

When processing pallet tables, the TNC may overwrite your most recently entered datum with values from the pallet table. With M104 you can reactivate the original datum.

# **Effect**

M104 is effective only in the blocks in which it is programmed.

M104 becomes effective at the end of block.

# Moving to position in an non-tilted coordinate system with a tilted working plane: M130

# Standard behavior with a tilted working plane

The TNC places the coordinates in the positioning blocks in the tilted coordinate system.

#### Behavior with M130

The TNC places coordinates in straight line blocks in the untilted coordinate system.

The TNC then positions the (tilted) tool to the programmed coordinates of the untilted system.



Following positioning blocks or fixed cycles are carried out in a tilted coordinate system. This can lead to problems in fixed cycles with absolute pre-positioning.

# Effect

M130 functions blockwise in straight-line blocks without tool radius compensation.



# 7.4 Miscellaneous Functions for Contouring Behavior

**Smoothing corners: M90** 

### Standard behavior

The TNC stops the tool briefly in positioning blocks without tool radius compensation. This is called an accurate stop.

In program blocks with radius compensation (RR/RL), the TNC automatically inserts a transition arc at outside corners.

# **Behavior with M90**

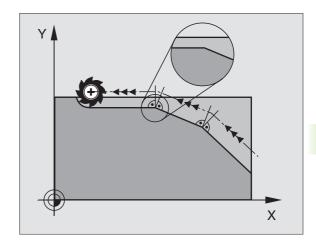
The tool moves at corners with constant speed: This provides a smoother, more continuous surface. Machining time is also reduced. See figure at center right.

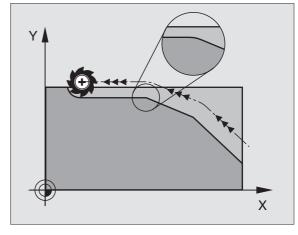
Example application: Surface consisting of a series of straight line segments.

# **Effect**

M90 is effective only in the blocks in which it is programmed with M90.

M90 becomes effective at the start of block. Operation with servo lag must be active.





# Insert rounding arc between straight lines: M112

# Compatibility

For reasons of compatibility, the M112 function is still available. However, to define the tolerance for fast contour milling, HEIDENHAIN recommends the use of the TOLERANCE cycle, see "Special Cycles," page 337.

# Machining small contour steps: M97

# Standard behavior

The TNC inserts a transition arc at outside corners. If the contour steps are very small, however, the tool would damage the contour.

In such cases the TNC interrupts program run and generates the error message "Tool radius too large."

# **Behavior with M97**

The TNC calculates the intersection of the contour elements—as at inside corners—and moves the tool over this point.

Program M97 in the same block as the outside corner.

# **Effect**

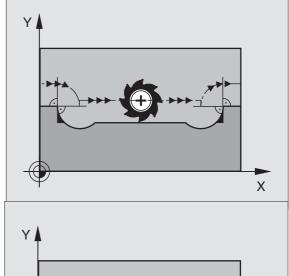
M97 is effective only in the blocks in which it is programmed.

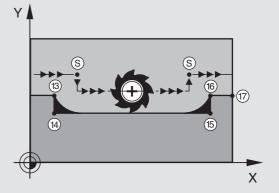


A corner machined with M97 will not be completely finished. You may wish to rework the contour with a smaller tool.

# **Example NC blocks**

5 TOOL DEF L R+20	Large tool radius
•••	
13 L X Y R F M97	Move to contour point 13
14 L IY-0.5 R F	Machine small contour step 13 to 14
15 L IX+100	Move to contour point 15
16 L IY+0.5 R F M97	Machine small contour step 15 to 16
17 L X Y	Move to contour point 17





# Machining open contours: M98

#### Standard behavior

The TNC calculates the intersections of the cutter paths at inside corners and moves the tool in the new direction at those points.

If the contour is open at the corners, however, this will result in incomplete machining.

# **Behavior with M98**

With the miscellaneous function M98, the TNC temporarily suspends radius compensation to ensure that both corners are completely machined.

# **Effect**

M98 is effective only in the blocks in which it is programmed.

M98 takes effect at the end of block.

# **Example NC blocks**

Move to the contour points 10, 11 and 12 in succession:

10 L X ... Y... RL F 11 L X... IY... M98 12 L IX+ ...

# Feed rate factor for plunging movements: M103

# Standard behavior

The TNC moves the tool at the last programmed feed rate, regardless of the direction of traverse.

# **Behavior with M103**

The TNC reduces the feed rate when the tool moves in the negative direction of the tool axis. The feed rate for plunging FZMAX is calculated from the last programmed feed rate FPROG and a factor F%:

FZMAX = FPROG x F%

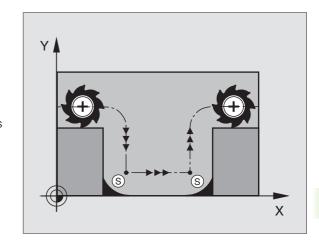
# **Programming M103**

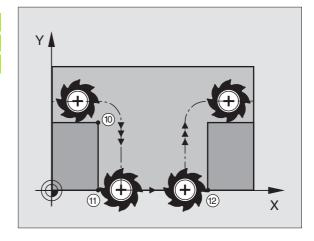
If you enter M103 in a positioning block, the TNC continues the dialog by asking you the factor  ${\sf F}.$ 

# **Effect**

M103 becomes effective at the start of block.

To cancel M103, program M103 once again without a factor.





# **Example NC blocks**

The feed rate for plunging is to be 20% of the feed rate in the plane.

	Actual contouring feed rate (mm/min):
17 L X+20 Y+20 RL F500 M103 F20	500
18 L Y+50	500
19 L IZ-2.5	100
20 L IY+5 IZ-5	141
21 L IX+50	500
22 L Z+5	500

# Feed rate in millimeters per spindle revolution: M136

# Standard behavior

The TNC moves the tool at the programmed feed rate F in mm/min.

# **Behavior with M136**

With M136, the TNC does not move the tool in mm/min, but rather at the programmed feed rate F in millimeters per spindle revolution. If you change the spindle speed by using the spindle override, the TNC changes the feed rate accordingly.



With the introduction of software 280 476-xx, the unit of measure used for miscellaneous function M136 has changed from µm/rev. to mm/rev. If you are using programs in which you have programmed M136 and which you have written on a previous TNC software, you need to reduce the value entered for the feed rate by the factor 1000.

### **Effect**

M136 becomes effective at the start of block.

You can cancel M136 by programming M137.

# Feed rate at circular arcs: M109/M110/M111

#### Standard behavior

The TNC applies the programmed feed rate to the path of the tool center.

#### Behavior at circular arcs with M109

The TNC adjusts the feed rate for circular arcs at inside and outside contours such that the feed rate at the tool cutting edge remains constant.

#### Behavior at circular arcs with M110

The TNC keeps the feed rate constant for circular arcs at inside contours only. At outside contours, the feed rate is not adjusted.



M110 is also effective for the inside machining of circular arcs using contour cycles. If you define M109 or M110 before calling a machining cycle, the adjusted feed rate is also effective for circular arcs within machining cycles. The initial state is restored after finishing or aborting a machining cycle.

#### **Effect**

M109 and M110 become effective at the start of block. To cancel M109 and M110, enter M111.

# Calculating the radius-compensated path in advance (LOOK AHEAD): M120

### Standard behavior

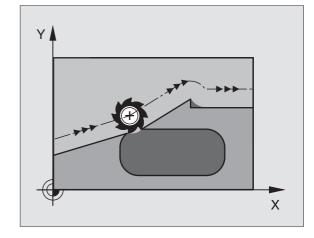
If the tool radius is larger than the contour step that is to be machined with radius compensation, the TNC interrupts program run and generates an error message. M97(see "Machining small contour steps: M97" on page 182): Although you can use M97 to inhibit the error message, this will result in dwell marks and will also move the corner.

If the programmed contour contains undercut features, the tool may damage the contour.

# Behavior with M120

The TNC checks radius-compensated paths for contour undercuts and tool path intersections, and calculates the tool path in advance from the current block. Areas of the contour that might be damaged by the tool, are not machined (dark areas in figure at right). You can also use M120 to calculate the radius compensation for digitized data or data created on an external programming system. This means that deviations from the theoretical tool radius can be compensated.

Use LA (**L**ook **A**head) behind M120 to define the number of blocks (maximum: 99) that you want the TNC to calculate in advance. Note that the larger the number of blocks you choose, the higher the block processing time will be.



# Input

If you enter M120 in a positioning block, the TNC continues the dialog for this block by asking you the number of blocks LA that are to be calculated in advance.

# **Effect**

M120 must be located in an NC block that also contains radius compensation RL or RR. M120 is then effective from this block until

- radius compensation is canceled, or
- M120 LA0 is programmed, or
- M120 is programmed without LA.
- another program is called with PGM CALL

M120 becomes effective at the start of block.

#### Limitations

- After an external or internal stop, you can only re-enter the contour with the function RESTORE POS. AT N.
- If you are using the path functions RND and CHF, the blocks before and after RND or CHF must contain only coordinates of the working plane.
- If you want to approach the contour on a tangential path, you must use the function APPR LCT. The block with APPR LCT must contain only coordinates of the working plane.
- If you want to approach the contour on a tangential path, use the function DEP LCT. The block with DEP LCT must contain only coordinates of the working plane.

# Superimposing handwheel positioning during program run: M118

# Standard behavior

In the program run modes, the TNC moves the tool as defined in the part program.

#### **Behavior with M118**

M118 permits manual corrections by handwheel during program run. You can use this miscellaneous function by entering axis-specific values X, Y and Z (in mm) behind M118.

# Input

If you enter M118 in a positioning block, the TNC continues the dialog for this block by asking you the axis-specific values. The coordinates are entered with the orange axis direction buttons or the ASCII keyboard.

# **Effect**

Cancel handwheel positioning by programming M118 once again without  $X,\,Y$  and Z.

M118 becomes effective at the start of block.

# **Example NC blocks**

You wish to be able to use the handwheel during program run to move the tool in the working plane X/Y by  $\pm 1$  mm of the programmed value:

# L X+0 Y+38.5 RL F125 M118 X1 Y1



M118 is always effective in the original coordinate system, even if the working plane is tilted!

M118 also functions in the Positioning with MDI mode of operation!

If M118 is active, the MANUAL OPERATION function is not available after a program interruption!

# Retraction from the contour in the tool-axis direction: M140

# Standard behavior

In the program run modes, the TNC moves the tool as defined in the part program.

#### Behavior with M104

With M140 MB (move back) you can enter a path in the direction of the tool axis for departure from the contour.

# Input

If you enter M140 in a positioning block, the TNC continues the dialog and asks for the desired path of tool departure from the contour. Enter the requested path that the tool should follow when departing the contour, or press the MAX soft key to move to the limit of the traverse range.

# **Effect**

M140 is effective only in the block in which it is programmed.

M140 becomes effective at the start of the block.

# **Example NC blocks**

Block 250: Retract the tool 50 mm from the contour.

Block 251: Move the tool to the limit of the traverse range.

250 L X+0 Y+38.5 F125 M140 MB 50

251 L X+0 Y+38.5 F125 M140 MB MAX



M140 is also effective if the tilted-working-plane function, M114 or M128 is active. On machines with tilting heads, the TNC then moves the tool in the tilted coordinate system.

With the **FN18: SYSREAD ID230 NR6** function you can find the distance from the current position to the limit of the traverse range in the positive tool axis.

With M140 MB MAX you can only retract in positive direction.

# Suppressing touch probe monitoring: M141

#### Standard behavior

When the stylus is deflected, the TNC outputs an error message as soon as you attempt to move a machine axis.

# **Behavior with M141**

The TNC moves the machine axes even if the touch probe is deflected. This function is required if you wish to write your own measuring cycle in connection with measuring cycle 3 in order to retract the stylus by means of a positioning block after it has been deflected.



If you use M141, make sure that you retract the touch probe in the correct direction.

M141 functions only for movements with straight-line blocks.

# **Effect**

M141 is effective only in the block in which it is programmed.

M141 becomes effective at the start of the block.

# **Delete modal program information: M142**

#### Standard behavior

The TNC resets modal program information in the following situations:

- Select a new program
- Execute a miscellaneous function M02, M30, or an END PGM block (depending on machine parameter 7300)
- Defining cycles for basic behavior with a new value

# **Behavior with M142**

All modal program information except for basic rotation, 3-D rotation and  $\Omega$  parameters are reset.

# **Effect**

M142 is effective only in the block in which it is programmed.

M142 becomes effective at the start of the block.

# **Delete basic rotation: M143**

### Standard behavior

The basic rotation remains in effect until it is reset or is overwritten with a new value.

# **Behavior with M143**

The TNC erases a programmed basic rotation from the NC program.

# **Effect**

M143 is effective only in the block in which it is programmed.

M143 becomes effective at the start of the block.

# 7.5 Miscellaneous Functions for Rotary Axes

# Feed rate in mm/min on rotary axes A, B, C: M116

#### Standard behavior

The TNC interprets the programmed feed rate in a rotary axis in degrees per minute. The contouring feed rate therefore depends on the distance from the tool center to the center of the rotary axis.

The larger this distance becomes, the greater the contouring feed rate.

#### Feed rate in mm/min on rotary axes with M116



The machine geometry must be entered in machine parameters 7510 ff. by the machine tool builder.

The TNC interprets the programmed feed rate in a rotary axis in mm/min. With this miscellaneous function, the TNC calculates the feed rate for each block at the start of the individual block. With a rotary axis, the feed rate is not changed during execution of the block even if the tool moves toward the center of the rotary axis.

#### **Effect**

M116 is effective in the working plane. With M117 you can reset M116. M116 is also canceled at the end of the program.

M116 becomes effective at the start of block.

# Shorter-path traverse of rotary axes: M126

#### Standard behavior

The standard behavior of the TNC while positioning rotary axes whose display has been reduced to values less than 360° is dependent on machine parameter 7682. In machine parameter 7682 is set whether the TNC should consider the difference between nominal and actual position, or whether the TNC should always (even without M126) choose the shortest path traverse to the programmed position. Examples:

Actual position	Nominal position	Traverse
350°	10°	-340°
10°	340°	+330°

#### **Behavior with M126**

With M126, the TNC will move the axis on the shorter path of traverse if you reduce display of a rotary axis to a value less than 360°. Examples:

Actual position	Nominal position	Traverse
350°	10°	+20°
10°	340°	-30°

#### **Effect**

M126 becomes effective at the start of block. To cancel M126, enter M127. At the end of program, M126 is automatically canceled.

# Reducing display of a rotary axis to a value less than 360°: M94

#### Standard behavior

The TNC moves the tool from the current angular value to the programmed angular value.

Example:

Current angular value: 538°
Programmed angular value: 180°
Actual distance of traverse: -358°

#### **Behavior with M94**

At the start of block, the TNC first reduces the current angular value to a value less than 360° and then moves the tool to the programmed value. If several rotary axes are active, M94 will reduce the display of all rotary axes. As an alternative you can enter a rotary axis after M94. The TNC then reduces the display only of this axis.

Example NC blocks

To reduce display of all active rotary axes:

#### L M94

To reduce display of the C axis only

#### L M94 C

To reduce display of all active rotary axes and then move the tool in the C axis to the programmed value:

#### L C+180 FMAX M94

#### **Effect**

M94 is effective only in the block in which it is programmed.

M94 becomes effective at the start of block

# Automatic compensation of machine geometry when working with tilted axes: M114

#### Standard behavior

The TNC moves the tool to the positions given in the part program. If the position of a tilted axis changes in the program, the resulting offset in the linear axes must be calculated by a postprocessor and traversed in a positioning block. As the machine geometry is also relevant, the NC program must be calculated separately for each machine tool.

#### **Behavior with M114**

If the position of a controlled tilted axis changes in the program, the TNC automatically compensates the tool offset by a 3-D length compensation. As the geometry of the individual machine tools is set in machine parameters, the TNC also compensates machine-specific offsets automatically. Programs only need to be calculated by the postprocessor once, even if they are being run on different machines with TNC control.

If your machine tool does not have controlled tilted axes (head tilted manually or positioned by the PLC), you can enter the current valid swivel head position after M114 (e.g. M114 B+45, Q parameters permitted).

The radius compensation must be calculated by a CAD system or by a postprocessor. A programmed radius compensation RL/RR will result in an error message.

If the tool length compensation is calculated by the TNC, the programmed feed rate refers to the point of the tool. Otherwise it refers to the tool datum.



If you machine tool is equipped with a swivel head that can be tilted under program control, you can interrupt program run and change the position of the tilted axis, for example with the handwheel.

With the RESTORE POS. AT N function, you can then resume program run at the block at which the part program was interrupted. If M114 is active, the TNC automatically calculates the new position of the tilted axis.

If you wish to use the handwheel to change the position of the tilted axis during program run, use M118 in conjunction with M128.

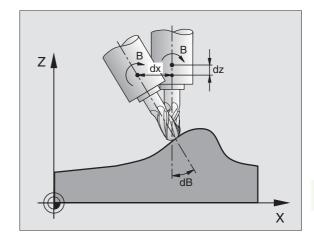
#### **Effect**

M114 becomes effective at the start of block, M115 at the end of block. M114 is not effective when tool radius compensation is active.

To cancel M114, enter M115. At the end of program, M114 is automatically canceled.



The machine geometry must be entered in machine parameters 7510 ff. by the machine tool builder.



# Maintaining the position of the tool tip when positioning with tilted axes (TCPM\*): M128

#### Standard behavior

The TNC moves the tool to the positions given in the part program. If the position of a tilted axis changes in the program, the resulting offset in the linear axes must be calculated and traversed in a positioning block (see figure with M114).

#### **Behavior with M128**

If the position of a controlled tilted axis changes in the program, the position of the tool tip to the workpiece remains the same.

If you wish to use the handwheel to change the position of the tilted axis during program run, use M118 in conjunction with M128. Handwheel positioning in a machine-based coordinate is possible when M128 is active.



For tilted axes with Hirth coupling: Do not change the position of the tilted axis after retracting the tool. Otherwise you might damage the contour.

After M128 you can program another feed rate, at which the TNC will carry out the compensation movements in the linear axes. If you program no feed rate here, or if you program a larger feed rate than is defined in machine parameters 7471, the feed rate from machine parameter 7471 will be effective.



Reset M128 before positioning with M91 or M92 and before a TOOL CALL.

To avoid contour gouging you must use only spherical cutters with M128.

The tool length must refer to the spherical center of the tool tip.

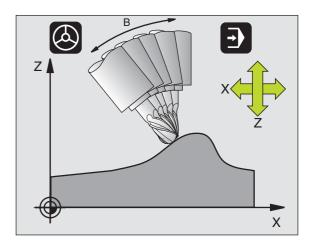
The TNC does not adjust the active radius compensation in accordance with the new position of the tilted axis. The result is an error which is dependent on the angular position of the rotary axis.

If M128 is active, the TNC shows in the status display the following symbol:  $\hfill \hfill \hfill$  .

#### M128 on tilting tables

If you program a tilting table movement while M128 is active, the TNC rotates the coordinate system accordingly. If for example you rotate the C axis by 90° (through a positioning command or datum shift) and then program a movement in the X axis, the TNC executes the movement in the machine axis Y.

The TNC also transforms the defined datum, which has been shifted by the movement of the rotary table.



#### M128 with 3-D tool compensation

If you carry out a 3-D tool compensation with active M128 and active radius compensation RL/RR, the TNC will automatically position the rotary axes for certain machine geometrical configurations (Peripheral milling, see "Three-Dimensional Tool Compensation," page 114).

#### **Effect**

M128 becomes effective at the start of block, M129 at the end of block. M128 is also effective in the manual operating modes and remains active even after a change of mode. The feed rate for the compensation movement will be effective until you program a new feed rate or until you reset M128 with M129.

To cancel M128, enter M129. The TNC also resets M128 if you select a new program in a program run operating mode.



The machine geometry must be entered in machine parameters 7510 ff. by the machine tool builder.

Example NC blocks

Moving at 1000 mm/min to compensate a radius.

L X+0 Y+38.5 RL F125 M128 F1000

# Exact stop at corners with nontangential transitions: M134

#### Standard behavior

The standard behavior of the TNC during positioning with rotary axes is to insert a transitional element in nontangential contour transitions. The contour of the transitional element depends on the acceleration, the rate of acceleration (jerk), and the defined tolerance for contour deviation.



With the machine parameters 7440 you can change the standard behavior of the TNC so that M134 becomes active automatically whenever a program is selected, see "General User Parameters," page 448.

#### **Behavior with M134**

The moves the tool during positioning with rotary axes so as to perform an exact stop at nontangential contour transitions.

#### **Effect**

M134 becomes effective at the start of block, M135 at the end of block.

You can reset M134 with M135. The TNC also resets M134 if you select a new program in a program run operating mode.

# Selecting tilting axes: M138

#### Standard behavior

The TNC performs M114 and M128, and tilts the working plane, only in those axes for which the machine tool builder has set the appropriate machine parameters.

#### **Behavior with M138**

The TNC performs the above functions only in those tilting axes that you have defined using M138.

#### **Effect**

M138 becomes effective at the start of block.

You can reset M138 by reprogramming it without entering any axes.

Example NC blocks

Perform the above-mentioned functions only in the tilting axis C:

L Z+100 RO FMAX M138 C



# Compensating the machine's kinematic configuration for ACTUAL/NOMINAL positions at end of block: M144

#### Standard behavior

The TNC moves the tool to the positions given in the part program. If the position of a tilted axis changes in the program, the resulting offset in the linear axes must be calculated, and traversed in a positioning block.

#### **Behavior with M144**

The TNC calculates into the position value any changes in the machine's kinematic configuration which result, for example, from adding a spindle attachment. If the position of a controlled tilted axis changes, the position of the tool tip to the workpiece is also changed. The resulting offset is calculated in the position display.



Positioning blocks with M91/M92 are permitted if M144 is active

The position display in the operating modes FULL SEQUENCE and SINGLE BLOCK does not change until the tilting axes have reached their final position.

#### **Effect**

M144 becomes effective at the start of the block. M144 does not function in connection with M114, M128 or a tilted working plane.

You can cancel M144 by programming M145.



The machine geometry must be entered in machine parameters 7502 and following by the machine tool builder. The machine tool builder determines the behavior in the automatic and manual operating modes. Refer to your machine manual.

# 7.6 Miscellaneous Functions for Laser Cutting Machines

# **Principle**

The TNC can control the cutting efficiency of a laser by transferring voltage values through the S-analog output. You can influence laser efficiency during program run through the miscellaneous functions M200 to M204.

#### Entering miscellaneous functions for laser cutting machines

If you enter an M function for laser cutting machines in a positioning block, the TNC continues the dialog by asking you the required parameters for the programmed function.

All miscellaneous functions for laser cutting machines become effective at the start of the block.

# Output the programmed voltage directly: M200

#### **Behavior with M200**

The TNC outputs the value programmed after M200 as the voltage V.

Input range: 0 to 9 999 V

#### **Effect**

M200 remains in effect until a new voltage is output through M200, M201, M202, M203 or M204.

# Output voltage as a function of distance: M201

#### Behavior with M201

M201 outputs the voltage in dependence on the distance to be covered. The TNC increases or decreases the current voltage linearly to the value programmed for V.

Input range: 0 to 9 999 V

#### **Effect**

M201 remains in effect until a new voltage is output through M200, M201, M202, M203 or M204.



## Output voltage as a function of speed: M202

#### **Behavior with M202**

The TNC outputs the voltage as a function of speed. In the machine parameters, the machine tool builder defines up to three characteristic curves FNR in which specific feed rates are assigned to specific voltages. Use miscellaneous function M202 to select the curve FNR from which the TNC is to determine the output voltage.

Input range: 1 to 3

#### **Effect**

M202 remains in effect until a new voltage is output through M200, M201, M202, M203 or M204.

# Output voltage as a function of time (time-dependent ramp): M203

#### **Behavior with M203**

The TNC outputs the voltage V as a function of the time TIME. The TNC increases or decreases the current voltage linearly to the value programmed for V within the time programmed for TIME.

#### Input range

Voltage V: 0 to 9.999 Volt TIME: 0 to 1.999 seconds

#### **Effect**

M203 remains in effect until a new voltage is output through M200, M201. M202. M203 or M204.

# Output voltage as a function of time (time-dependent pulse): M204

#### **Behavior with M204**

The TNC outputs a programmed voltage as a pulse with a programmed duration TIME.

#### Input range

Voltage V: 0 to 9.999 Volt TIME: 0 to 1.999 seconds

#### **Effect**

M204 remains in effect until a new voltage is output through M200, M201, M202, M203 or M204.







8

**Programming: Cycles** 

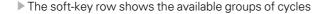
# 8.1 Working with Cycles

Frequently recurring machining cycles that comprise several working steps are stored in the TNC memory as standard cycles. Coordinate transformations and other special cycles are also provided as standard cycles (see table on next page).

Fixed cycles with numbers 200 and over use Q parameters as transfer parameters. Parameters with specific functions that are required in several cycles always have the same number: For example, Q200 is always assigned the set-up clearance, Q202 the plunging depth, etc.

## Defining a cycle using soft keys







Press the soft key for the desired group of cycles, for example DRILLING for the drilling cycles



- Select the desired cycle, for example THREAD MILLING. The TNC initiates the programming dialog and asks all required input values. At the same time a graphic of the input parameters is displayed in the right screen window. The parameter that is asked for in the dialog prompt is highlighted
- Enter all parameters asked by the TNC and conclude each entry with the ENT key
- The TNC terminates the dialog when all required data have been entered

#### Program run Programming and editing Pitch? 14 FLT 15 FCT DR- R18 CLSD- CCX+20 CCY+30 16 DEP CT CCA90 R+5 F1000 17 | X-30 Y+0 R0 F MOX CYCL DEF 262 THREAD MILLING Q335=10 \$NOMINAL DIAMETER Q239=+1.5 \$THREAD PITCH Q201=-18 \$DEPTH OF THREAD #F PRE-POSITIONING CLIMB OR UP-CUT 0203=+0 \$SURFACE COORDINATE \$2ND SET-UP CLEARANCE 0204=50 FEED RATE FOR MILLING

# Defining a cycle using the GOTO function



The soft-key row shows the available groups of cycles



▶ The TNC shows an overview of cycles in a window. Use the arrow keys to select the desired cycle, or enter the cycle number. Confirm with ENT. The TNC then initiates the cycle dialog as described above.

#### **Example NC blocks**

7 CYCL DEF 200	DRILLING
Q200=2	;SET-UP CLEARANCE
Q201=-20	;DEPTH
Q206=150	;FEED RATE FOR PLUNGING
Q202=5	;PLUNGING DEPTH
Q210=0	;DWELL TIME AT TOP
Q203=+0	;SURFACE COORDINATE
Q204=50	;2ND SET-UP CLEARANCE
Q211=0.25	;DWELL TIME AT BOTTOM

Group of cycles	Soft key
Cycles for pecking, reaming, boring, counterboring, tapping and thread cutting	DRILLING
Cycles for milling pockets, studs and slots	POCKETS/ STUDS/ SLOTS
Cycles for producing hole patterns, such as circular or linear patterns	PATTERN
SL (Subcontour List) cycles which allow the contour- parallel machining of relatively complex contours consisting of several overlapping subcontours, cylinder surface interpolation	SLII
Cycles for face milling of flat or twisted surfaces	MULTIPASS MILLING
Coordinate transformation cycles which enable datum shift, rotation mirror image, enlarging and reducing for various contours	COORD. TRANSF.
Special cycles such as dwell time, program call, oriented spindle stop and tolerance	SPECIAL CYCLES



If you use indirect parameter assignments in fixed cycles with numbers greater than 200 (e.g. Q210 = Q1), any change in the assigned parameter (e.g. Q1) will have no effect after the cycle definition. Define the cycle parameter (e.g. Q210) directly in such cases.

In order to be able to run cycles 1 to 17 on older TNC models, you must program an additional negative sign before the values for safety clearance and plunging depth.

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# Calling a cycle



#### **Prerequisites**

The following data must always be programmed before a cycle call

- BLK FORM for graphic display (needed only for test graphics)
- Tool call
- Direction of spindle rotation (M functions M3/M4)
- Cycle definition (CYCL DEF).

For some cycles, additional prerequisites must be observed. They are described with the individual cycle.

The following cycles become effective automatically as soon as they are defined in the part program. These cycles cannot and must not be called:

- Cycle 220 for circular and Cycle 221 for linear hole patterns
- SL Cycle 14 CONTOUR GEOMETRY
- SL Cycle 20 CONTOUR DATA
- Cycle 32 TOLERANCE
- Coordinate transformation cycles
- Cycle 9 DWELL TIME

All other cycles are called as described below:

1 If the TNC is to execute the cycle once after the last programmed block, program the cycle call with the miscellaneous function M99 or with CYCL CALL:



- To program the cycle call, press the CYCL CALL key.
- ▶ Press the CYCL CALL M soft key to enter a cycle call.
- Enter a miscellaneous function M or press END to end the dialoα.
- 2 If the TNC is to execute the cycle automatically after every positioning block, program the cycle call with M89 (depending on machine parameter 7440).
- 3 If the TNC is to execute the cycle at every position that is defined in a point table, use the function CYCL CALL. (see "Point Tables" on page 206)

To cancel M89, enter

■ **M99** or

204

- CYCL CALL or
- CYCL DEF

# Working with the secondary axes U/V/W

The TNC performs infeed movements in the axis that was defined in the TOOL CALL block as the spindle axis. It performs movements in the working plane only in the principle axes X, Y or Z. Exceptions:

- You program secondary axes for the side lengths in cycles 3 SLOT MILLING and 4 POCKET MILLING.
- You program secondary axes in the contour geometry subprogram of an SL cycle.

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# 8.2 Point Tables

## **Function**

You should create a point table whenever you want to run a cycle, or several cycles in sequence, on an irregular point pattern.

If you are using drilling cycles, the coordinates of the working plane in the point table represent the hole centers. If you are using milling cycles, the coordinates of the working plane in the point table represent the starting-point coordinates of the respective cycle (e.g. center-point coordinates of a circular pocket). Coordinates in the spindle axis correspond to the coordinate of the workpiece surface.

# Creating a point table

Select the **Programming and Editing** mode of operation.



To call the file manager, press the PGM MGT key.

#### File name ?

#### **NEW.PNT**

Enter the name and file type of the point table and confirm your entry with the ENT key.





To select the unit of measure, press the MM or INCH soft key. The TNC changes to the program blocks window and displays an empty point table.



With the soft key INSERT LINE, insert new lines and enter the coordinates of the desired machining position.

Repeat the process until all desired coordinates have been entered.



With the soft keys X OFF/ON, Y OFF/ON, Z OFF/ON (second soft-key row), you can specify which coordinates you want to enter in the point table.

i

# Selecting a point table in the program.

In the Programming and Editing mode of operation, select the program for which you want to activate the point table:



Press the PGM CALL key to call the function for selecting the point table.



Press the POINT TABLE soft key.

Enter the name of the point table and confirm your entry with the ENT key. If the point table is not stored in the same directory as the NC program, you must enter the complete path.

#### **Example NC block**

7 SEL PATTERN "TNC:\DIRKT5\MUST35.PNT"

## Calling a cycle in connection with point tables



With **CYCL CALL PAT** the TNC runs the points table that you last defined (even if you have defined the point table in a program that was nested with **CALL PGM**.

The TNC uses the coordinate in the spindle axis as the clearance height, where the tool is located during cycle call. A clearance height or 2nd setup clearance that is defined separately in a cycle must not be greater than the clearance height defined in the global pattern.

If you want the TNC to call the last defined fixed cycle at the points defined in a point table, then program the cycle call with **CYCLE CALL PAT**:



- To program the cycle call, press the CYCL CALL key.
- Press the CYCL CALL PAT soft key to call a point table
- ▶ Enter the feed rate at which the TNC is to move from point to point (if you make no entry the TNC will move at the last programmed feed rate, FMAX not valid).
- If required, enter miscellaneous function M, then confirm with the END key.

The TNC moves the tool back to the safe height over each successive starting point (safe height = the spindle axis coordinate for cycle call). To use this procedure also for the cycles number 200 and greater, you must define the 2nd set-up clearance ( $\Omega$ 204) as 0.

If you want to move at reduced feed rate when pre-positioning in the spindle axis, use the miscellaneous function M103 (see "Feed rate factor for plunging movements: M103" on page 183).

#### Effect of the point tables with Cycles 1 to 5, 17 and 18

The TNC interprets the points of the working plane as coordinates of the hole centers. The coordinate of the spindle axis defines the upper surface of the workpiece, so the TNC can pre-position automatically (first in the working plane, then in the spindle axis).

#### Effect of the point tables with SL cycles and Cycle 12

The TNC interprets the points as an additional datum shift.

#### Effect of the point tables with Cycles 200 to 208 and 262 to 267

The TNC interprets the points of the working plane as coordinates of the hole centers. If you want to use the coordinate defined in the point table for the spindle axis as the starting point coordinate, you must define the workpiece surface coordinate (Q203) as 0.

#### Effect of the point tables with Cycles 210 to 215

The TNC interprets the points as an additional datum shift. If you want to use the points defined in the point table as starting-point coordinates, you must define the starting points and the workpiece surface coordinate (Q203) in the respective milling cycle as 0.

cles

# 8.3 Cycles for Drilling, Tapping and **Thread Milling**

# **Overview**

The TNC offers 19 cycles for all types of drilling operations:

Cycle	Soft key
1 PECKING Without automatic pre-positioning	1 🔯
200 DRILLING With automatic pre-positioning, 2nd set-up clearance	200 🛭
201 REAMING With automatic pre-positioning, 2nd set-up clearance	201
202 BORING With automatic pre-positioning, 2nd set-up clearance	202
203 UNIVERSAL DRILLING With automatic pre-positioning, 2nd set-up clearance, chip breaking, and decrement	203
204 BACK BORING With automatic pre-positioning, 2nd set-up clearance	204
205 UNIVERSAL PECKING With automatic pre-positioning, 2nd set-up clearance, chip breaking, and advanced stop distance	205 🕡
208 BORE MILLING With automatic pre-positioning, 2nd set-up clearance	208

Cycle	Soft key
2 TAPPING With a floating tap holder	2
17 RIGID TAPPING Without a floating tap holder	17 RT
18 THREAD CUTTING	18 []
206 TAPPING NEW With a floating tap holder, with automatic pre- positioning, 2nd set-up clearance	206 ()
207 RIGID TAPPING NEW Without a floating tap holder, with automatic pre- positioning, 2nd set-up clearance	207 (S RT
209 TAPPING W/ CHIP BRKG Without a floating tap holder, with automatic pre- positioning, 2nd set-up clearance, chip breaking	209 3 RT
262 THREAD MILLING Cycle for milling a thread in pre-drilled material	262
263 THREAD MLLNG/CNTSNKG Cycle for milling a thread in pre-drilled material and machining a countersunk chamfer	263
264 THREAD DRILLING/MLLNG Cycle for drilling into the solid material with subsequent milling of the thread with a tool	264
265 HEL.THREAD DRLG/MLG Cycle for milling the thread into the solid material	265
267 OUTSIDE THREAD MLLNG Cycle for milling an external thread and machining a countersunk chamfer	267

## **PECKING (Cycle 1)**

- **1** The tool drills from the current position to the first plunging depth at the programmed feed rate F.
- 2 When it reaches the first plunging depth, the tool retracts in rapid traverse FMAX to the starting position and advances again to the first plunging depth minus the advanced stop distance t.
- 3 The advanced stop distance is automatically calculated by the control:
  - At a total hole depth of up to 30 mm: t = 0.6 mm
  - At a total hole depth exceeding 30 mm: t = hole depth / 50
  - Maximum advanced stop distance: 7 mm
- **4** The tool then advances with another infeed at the programmed feed rate F.
- **5** The TNC repeats this process (1 to 4) until the programmed depth is reached.
- **6** After a dwell time at the hole bottom, the tool is returned to the starting position in rapid traverse FMAX for chip breaking.



#### Before programming, note the following:

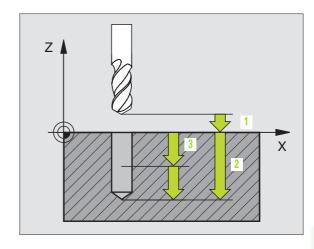
Program a positioning block for the starting point (hole center) in the working plane with radius compensation R0.

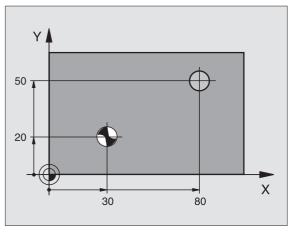
Program a positioning block for the starting point in the tool axis (set-up clearance above the workpiece surface).

The algebraic sign for the cycle parameter DEPTH determines the working direction. If you program DEPTH = 0, the cycle will not be executed.



- ▶ Set-up clearance 1 (incremental value): Distance between tool tip (at starting position) and workpiece surface
- Depth 2 (incremental value): Distance between workpiece surface and bottom of hole (tip of drill taper)
- ▶ Plunging depth 3 (incremental value): Infeed per cut The total hole depth does not have to be a multiple of the plunging depth. The tool will drill to the total hole depth in one movement if:
  - the plunging depth is equal to the depth
  - the plunging depth is greater than the total hole depth
- Dwell time in seconds: Amount of time the tool remains at the total hole depth for chip breaking
- ▶ Feed rate F: Traversing speed of the tool during drilling in mm/min





#### **Example: NC blocks**

5 L Z+100 RO FMAX
6 CYCL DEF 1.0 PECKING
7 CYCL DEF 1.1 SET UP 2
8 CYCL DEF 1.2 DEPTH -15
9 CYCL DEF 1.3 PECKG 7.5
10 CYCL DEF 1.4 DWELL 1
11 CYCL DEF 1.5 F80
12 L X+30 Y+20 FMAX M3

14 L X+80 Y+50 FMAX M99

15 L Z+100 FMAX M2

13 L Z+2 FMAX M99

## **DRILLING (Cycle 200)**

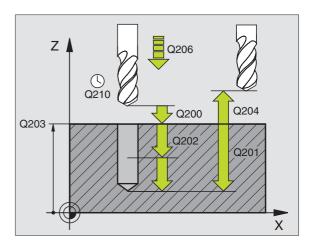
- 1 The TNC positions the tool in the tool axis at rapid traverse FMAX to the set-up clearance above the workpiece surface.
- The tool drills to the first plunging depth at the programmed feed rate F.
- The TNC returns the tool at FMAX to the setup clearance, dwells there (if a dwell time was entered), and then moves at FMAX to the setup clearance above the first plunging depth.
- The tool then advances with another infeed at the programmed feed rate F.
- The TNC repeats this process (2 to 4) until the programmed depth is reached.
- At the hole bottom, the tool path is retraced to setup clearance or — if programmed — to the 2nd setup clearance in rapid traverse FMAX.

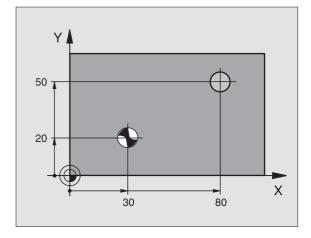


#### Before programming, note the following:

Program a positioning block for the starting point (hole center) in the working plane with radius compensation R0.

The algebraic sign for the cycle parameter DEPTH determines the working direction. If you program DEPTH = 0, the cycle will not be executed.









- ▶ **Set-up clearance** Q200 (incremental value): Distance between tool tip and workpiece surface. Enter a positive value.
- ▶ **Depth** Q201 (incremental value): Distance between workpiece surface and bottom of hole (tip of drill taper)
- ▶ Feed rate for plunging Q206: Traversing speed of the tool during drilling in mm/min
- ▶ Plunging depth Q202 (incremental value): Infeed per cut. The depth does not have to be a multiple of the plunging depth. The TNC will go to depth in one movement if:
  - the plunging depth is equal to the depth
  - the plunging depth is greater than the depth
- ▶ Dwell time at top Q210: Time in seconds that the tool remains at set-up clearance after having been retracted from the hole for chip release.
- ▶ Workpiece surface coordinate Q203 (absolute value): Coordinate of the workpiece surface
- ▶ 2nd set-up clearance Q204 (incremental value): Coordinate in the tool axis at which no collision between tool and workpiece (clamping devices) can occur.
- ▶ Dwell time at depth Q211: Time in seconds that the tool remains at the hole bottom

#### **Example: NC blocks**

10 L Z+100 RO FMAX
11 CYCL DEF 200 DRILLING
Q200 = 2 ;SET-UP CLEARANCE
Q201 = -15 ;DEPTH
Q206 = 250 ;FEED RATE FOR PLUNGING
Q202 = 5 ;PLUNGING DEPTH
Q210 = 0 ;DWELL TIME AT TOP
Q203 = +20 ;SURFACE COORDINATE
Q204 = 100 ;2ND SET-UP CLEARANCE
Q211 = 0.1 ;DWELL TIME AT BOTTOM
12 L X+30 Y+20 FMAX M3
13 CYCL CALL
14 L X+80 Y+50 FMAX M99
15 L Z+100 FMAX M2

# **REAMING (Cycle 201)**

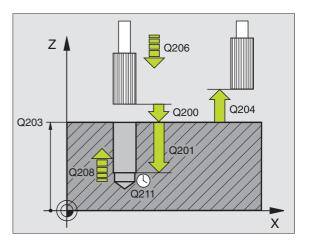
- 1 The TNC positions the tool in the tool axis at rapid traverse FMAX to the programmed setup clearance above the workpiece surface.
- The tool reams to the entered depth at the programmed feed rate F.
- If programmed, the tool remains at the hole bottom for the entered dwell time.
- The tool then retracts to set-up clearance at the feed rate F, and from there — if programmed — to the 2nd set-up clearance in FMAX.

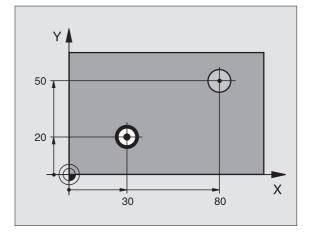


#### Before programming, note the following:

Program a positioning block for the starting point (hole center) in the working plane with radius compensation R0.

The algebraic sign for the cycle parameter DEPTH determines the working direction. If you program DEPTH = 0, the cycle will not be executed.









- ▶ **Set-up clearance** Q200 (incremental value): Distance between tool tip and workpiece surface.
- ▶ Depth Q201 (incremental value): Distance between workpiece surface and bottom of hole
- ▶ Feed rate for plunging Q206: Traversing speed of the tool during reaming in mm/min
- ▶ Dwell time at depth Q211: Time in seconds that the tool remains at the hole bottom
- ▶ **Retraction feed rate** Q208: Traversing speed of the tool in mm/min when retracting from the hole. If you enter Q208 = 0, the tool retracts at the reaming feed rate.
- ▶ Workpiece surface coordinate Q203 (absolute value): Coordinate of the workpiece surface
- ▶ 2nd set-up clearance Q204 (incremental value): Coordinate in the tool axis at which no collision between tool and workpiece (clamping devices) can occur.

#### **Example: NC blocks**

10 L Z+100 RO FMAX
11 CYCL DEF 201 REAMING
Q200 = 2 ;SET-UP CLEARANCE
Q201 = -15 ;DEPTH
Q206 = 100 ;FEED RATE FOR PLUNGING
Q211 = 0.5 ;DWELL TIME AT BOTTOM
Q208 = 250 ;RETRACTION FEED TIME
Q203 = +20 ;SURFACE COORDINATE
Q204 = 100 ;2ND SET-UP CLEARANCE
12 L X+30 Y+20 FMAX M3
13 CYCL CALL
14 L X+80 Y+50 FMAX M9
15 L Z+100 FMAX M2

# **BORING (Cycle 202)**



Machine and control must be specially prepared by the machine tool builder for use of this cycle.

- 1 The TNC positions the tool in the tool axis at rapid traverse FMAX to the set-up clearance above the workpiece surface.
- 2 The tool drills to the programmed depth at the feed rate for plunging.
- **3** If programmed, the tool remains at the hole bottom for the entered dwell time with active spindle rotation for cutting free.
- **4** The TNC then orients the spindle to the 0° position with an oriented spindle stop.
- 5 If retraction is selected, the tool retracts in the programmed direction by 0.2 mm (fixed value).
- 6 The TNC moves the tool at the retraction feed rate to the set-up clearance and then, if entered, to the 2nd set-up clearance with FMAX. If Q214=0 the tool point remains on the wall of the hole.

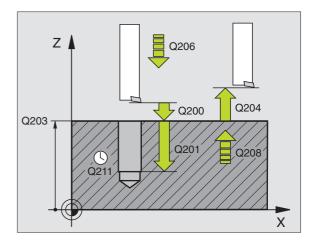


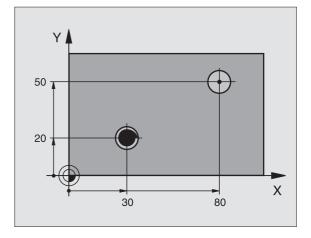
#### Before programming, note the following:

Program a positioning block for the starting point (hole center) in the working plane with radius compensation R0.

The algebraic sign for the cycle parameter DEPTH determines the working direction. If you program DEPTH = 0, the cycle will not be executed.

After the cycle is completed, the TNC restores the coolant and spindle conditions that were active before the cycle call.









- ▶ **Set-up clearance** Q200 (incremental value): Distance between tool tip and workpiece surface.
- ▶ **Depth** Q201 (incremental value): Distance between workpiece surface and bottom of hole
- ▶ Feed rate for plunging Q206: Traversing speed of the tool during boring in mm/min
- ▶ **Dwell time at depth** Q211: Time in seconds that the tool remains at the hole bottom
- Retraction feed rate Q208: Traversing speed of the tool in mm/min when retracting from the hole. If you enter Q208 = 0, the tool retracts at feed rate for plunging.
- ▶ Workpiece surface coordinate Q203 (absolute value): Coordinate of the workpiece surface
- ▶ 2nd set-up clearance Q204 (incremental value): Coordinate in the tool axis at which no collision between tool and workpiece (clamping devices) can occur.
- ▶ **Disengaging direction** (0/1/2/3/4) Q214: Determine the direction in which the TNC retracts the tool at the hole bottom (after spindle orientation).
  - 0 Do not retract tool
  - Retract tool in the negative reference axis direction
  - 2 Retract tool in the negative secondary axis direction
  - **3** Retract tool in the positive reference axis direction
  - 4 Retract tool in the positive secondary axis direction



#### **Danger of collision**

Select a disengaging direction in which the tool moves away from the edge of the hole.

Check the position of the tool tip when you program a spindle orientation to the angle that you enter in Q336 (for example, in the Positioning with Manual Data Input mode of operation). Set the angle so that the tool tip is parallel to a coordinate axis.

▶ Angle for spindle orientation Q336 (absolute value): Angle at which the TNC positions the tool before retracting it.

#### Example:

10 L Z+100 RO FMAX
11 CYCL DEF 202 BORING
Q200 = 2 ;SET-UP CLEARANCE
Q201 = -15 ;DEPTH
Q206 = 100 ;FEED RATE FOR PLUNGING
Q211 = 0.5 ;DWELL TIME AT BOTTOM
Q208 = 250 ;RETRACTION FEED TIME
Q203 = +20 ;SURFACE COORDINATE
Q204 = 100 ;2ND SET-UP CLEARANCE
Q214 = 1 ;DISENGAGING DIRECTN
Q336 = O ;ANGLE OF SPINDLE
12 L X+30 Y+20 FMAX M3
13 CYCL CALL
14 L X+80 Y+50 FMAX M99

## **UNIVERSAL DRILLING (Cycle 203)**

- 1 The TNC positions the tool in the tool axis at rapid traverse FMAX to the programmed setup clearance above the workpiece surface.
- 2 The tool drills to the first plunging depth at the programmed feed rate F.
- 3 If you have programmed chip breaking, the tool then retracts by the entered retraction value. If you are working without chip breaking, the tool retracts at the retraction feed rate to setup clearance, remains there — if programmed — for the entered dwell time, and advances again in FMAX to the setup clearance above the first PLUNGING DEPTH.
- **4** The tool then advances with another infeed at the programmed feed rate. If programmed, the plunging depth is decreased after each infeed by the decrement.
- 5 The TNC repeats this process (2 to 4) until the programmed total hole depth is reached.
- The tool remains at the hole bottom if programmed for the entered dwell time to cut free, and then retracts to set-up clearance at the retraction feed rate. and if programmed to the 2nd set-up clearance with FMAX.



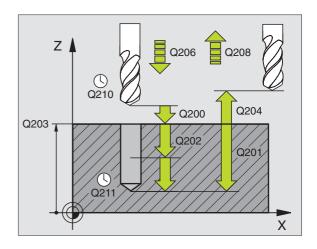
#### Before programming, note the following:

Program a positioning block for the starting point (hole center) in the working plane with radius compensation R0.

The algebraic sign for the cycle parameter DEPTH determines the working direction. If you program DEPTH = 0, the cycle will not be executed.



- ▶ **Set-up clearance** Q200 (incremental value): Distance between tool tip and workpiece surface.
- ▶ Depth Q201 (incremental value): Distance between workpiece surface and bottom of hole (tip of drill taper)
- Feed rate for plunging Q206: Traversing speed of the tool during drilling in mm/min
- ▶ Plunging depth Q202 (incremental value): Infeed per cut. The depth does not have to be a multiple of the plunging depth. The TNC will go to depth in one movement if:
  - the plunging depth is equal to the depth
  - the plunging depth is greater than the depth
- ▶ **Dwell time at top** Q210: Time in seconds that the tool remains at set-up clearance after having been retracted from the hole for chip release.
- ▶ Workpiece surface coordinate Q203 (absolute value): Coordinate of the workpiece surface



#### **Example: NC blocks**

11 CYCL DEF 20	3 UNIVERSAL DRILLING
Q200=2	;SET-UP CLEARANCE
Q201=-20	;DEPTH
Q206=150	;FEED RATE FOR PLUNGING
Q202=5	;PLUNGING DEPTH
Q210=0	; DWELL TIME AT TOP
Q203=+20	;SURFACE COORDINATE
Q204=50	;2ND SET-UP CLEARANCE
Q212=0.2	; DECREMENT
Q213=3	; BREAKS
Q205=3	;MIN. PLUNGING DEPTH
Q211=0.25	;DWELL TIME AT BOTTOM
Q208=500	;RETRACTION FEED RATE
Q256=0.2	;DIST FOR CHIP BRKNG

8 Programming: Cycles

- ▶ 2nd set-up clearance Q204 (incremental value): Coordinate in the tool axis at which no collision between tool and workpiece (clamping devices) can occur.
- ▶ Decrement Q212 (incremental value): Value by which the TNC decreases the plunging depth Q202 after each infeed.
- ▶ No. of breaks before retracting Q213: Number of chip breaks after which the TNC is to withdraw the tool from the hole for chip release. For chip breaking, the TNC retracts the tool each time by the value Q256.
- ▶ Minimum plunging depth Q205 (incremental value): If you have entered a decrement, the TNC limits the plunging depth to the value entered with Q205.
- ▶ Dwell time at depth Q211: Time in seconds that the tool remains at the hole bottom
- ▶ Retraction feed rate Q208: Traversing speed of the tool in mm/min when retracting from the hole. If you enter Q208 = 0, the tool retracts at the feed rate in Q206.
- ▶ Retraction rate for chip breaking Q256 (incremental value): Value by which the TNC retracts the tool during chip breaking



Machine and control must be specially prepared by the machine tool builder for use of this cycle.

Special boring bars for upward cutting are required for this cycle.

This cycle allows holes to be bored from the underside of the workpiece.

- 1 The TNC positions the tool in the tool axis at rapid traverse FMAX to the set-up clearance above the workpiece surface.
- 2 The TNC then orients the spindle to the 0° position with an oriented spindle stop and displaces the tool by the off-center distance.
- **3** The tool is then plunged into the already bored hole at the feed rate for pre-positioning until the tooth has reached setup clearance on the underside of the workpiece.
- 4 The TNC then centers the tool again over the bore hole, switches on the spindle and the coolant and moves at the feed rate for boring to the depth of bore.
- **5** If a dwell time is entered, the tool will pause at the top of the bore hole and will then be retracted from the hole again. The TNC carries out another oriented spindle stop and the tool is once again displaced by the off-center distance.
- 6 The TNC moves the tool at the pre-positioning feed rate to the setup clearance and then, if entered, to the 2nd setup clearance with FMAX.



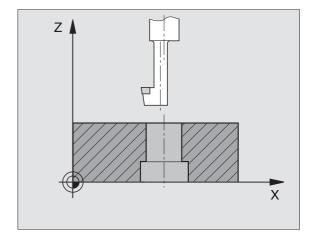
#### Before programming, note the following:

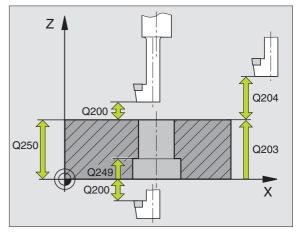
Program a positioning block for the starting point (hole center) in the working plane with radius compensation R0.

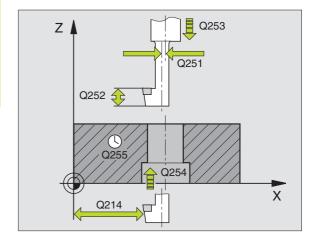
The algebraic sign for the cycle parameter depth determines the working direction. Note: A positive sign bores in the direction of the positive spindle axis.

The entered tool length is the total length to the underside of the boring bar and not just to the tooth.

When calculating the starting point for boring, the TNC considers the tooth length of the boring bar and the thickness of the material.









- ▶ **Set-up clearance** Q200 (incremental value): Distance between tool tip and workpiece surface.
- ▶ **Depth of counterbore** Q249 (incremental value): Distance between underside of workpiece and the top of the hole. A positive sign means the hole will be bored in the positive spindle axis direction.
- ▶ Material thickness Q250 (incremental value): Thickness of the workpiece
- ▶ Off-center distance Q251 (incremental value): Offcenter distance for the boring bar; value from tool data sheet
- ▶ Tool edge height Q252 (incremental value): Distance between the underside of the boring bar and the main cutting tooth; value from tool data sheet
- ▶ Feed rate for pre-positioning Q253: Traversing speed of the tool when moving in and out of the workpiece, in mm/min
- ▶ Feed rate for counterboring Q254: Traversing speed of the tool during counterboring in mm/min
- ▶ Dwell time Q255: Dwell time in seconds at the top of the bore hole
- ▶ Workpiece surface coordinate Q203 (absolute value): Coordinate of the workpiece surface
- ▶ 2nd set-up clearance Q204 (incremental value): Coordinate in the tool axis at which no collision between tool and workpiece (clamping devices) can occur.
- ▶ Disengaging direction (0/1/2/3/4) Q214: Determine the direction in which the TNC displaces the tool by the off-center distance (after spindle orientation).
  - Retract tool in the negative reference axis
  - 2 Retract tool in the negative secondary axis direction
  - **3** Retract tool in the positive reference axis direction
  - Retract tool in the positive secondary axis direction



#### Danger of collision

Check the position of the tool tip when you program a spindle orientation to the angle that you enter in Q336 (for example, in the Positioning with Manual Data Input mode of operation). Set the angle so that the tool tip is parallel to a coordinate axis. Select a disengaging direction in which the tool moves away from the edge of the hole.

#### Example: NC blocks

11 CYCL DEF 204	BACK BORING
Q200=2 ;	SET-UP CLEARANCE
Q249=+5 ;	DEPTH OF COUNTERBORE
Q250=20	MATERIAL THICKNESS
Q251=3.5	OFF-CENTER DISTANCE
Q252=15	TOOL EDGE HEIGHT
Q253=750 ;	F PRE-POSITIONING
Q254=200	F COUNTERBORING
Q255=0	;DWELL TIME
Q203=+20 ;	SURFACE COORDINATE
Q204=50	;2ND SET-UP CLEARANCE
Q214=1 ;	DISENGAGING DIRECTN
Q336=0	ANGLE OF SPINDLE

▶ Angle for spindle orientation Q336 (absolute value): Angle at which the TNC positions the tool before it is plunged into or retracted from the bore hole

# **UNIVERSAL PECKING (Cycle 205)**

- The TNC positions the tool in the tool axis at rapid traverse FMAX to the programmed setup clearance above the workpiece surface.
- 2 The tool drills to the first plunging depth at the programmed feed rate F.
- If you have programmed chip breaking, the tool then retracts by the entered retraction value. If you are working without chip breaking, the tool is moved at rapid traverse to setup clearance and then at FMAX to the entered starting position above the first plunging depth.
- The tool then advances with another infeed at the programmed feed rate. If programmed, the plunging depth is decreased after each infeed by the decrement.
- The TNC repeats this process (2 to 4) until the programmed total hole depth is reached.
- The tool remains at the hole bottom if programmed for the entered dwell time to cut free, and then retracts to set-up clearance at the retraction feed rate, and — if programmed — to the 2nd set-up clearance with FMAX.



### Before programming, note the following:

Program a positioning block for the starting point (hole center) in the working plane with radius compensation R0.

The algebraic sign for the cycle parameter DEPTH determines the working direction. If you program DEPTH = 0, the cycle will not be executed.

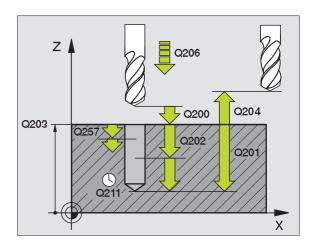


- ▶ **Set-up clearance** Q200 (incremental value): Distance between tool tip and workpiece surface.
- ▶ Depth Q201 (incremental value): Distance between workpiece surface and bottom of hole (tip of drill taper)
- ► Feed rate for plunging Q206: Traversing speed of the tool during drilling in mm/min
- ▶ Plunging depth Q202 (incremental value): Infeed per cut. The depth does not have to be a multiple of the plunging depth. The TNC will go to depth in one movement if:
  - the plunging depth is equal to the depth
  - the plunging depth is greater than the depth
- ▶ Workpiece surface coordinate Q203 (absolute value): Coordinate of the workpiece surface
- ▶ 2nd set-up clearance Q204 (incremental value): Coordinate in the tool axis at which no collision between tool and workpiece (clamping devices) can occur.
- ▶ **Decrement** Q212 (incremental value): Value by which the TNC decreases the plunging depth Q202.
- ▶ Minimum plunging depth Q205 (incremental value): If you have entered a decrement, the TNC limits the plunging depth to the value entered with Q205.
- ▶ Upper advanced stop distance Q258 (incremental value): Set-up clearance for rapid traverse positioning when the TNC moves the tool again to the current plunging depth after retraction from the hole; value for the first plunging depth
- ▶ Lower advanced stop distance Q259 (incremental value): Set-up clearance for rapid traverse positioning when the TNC moves the tool again to the current plunging depth after retraction from the hole; value for the last plunging depth



If you enter  $\Omega$ 258 not equal to  $\Omega$ 259, the TNC will change the advance stop distances between the first and last plunging depths at the same rate.

- ▶ Infeed depth for chip breaking Q257 (incremental value): Depth at which the TNC carries out chip breaking. There is no chip breaking if 0 is entered.
- ▶ Retraction rate for chip breaking Q256 (incremental value): Value by which the TNC retracts the tool during chip breaking
- ▶ Dwell time at depth Q211: Time in seconds that the tool remains at the hole bottom



#### **Example: NC blocks**

11 CYCL DEF 20	5 UNIVERSAL PECKING
Q200=2	;SET-UP CLEARANCE
Q201=-80	;DEPTH
Q206=150	;FEED RATE FOR PLUNGING
Q202=5	;PLUNGING DEPTH
Q203=+100	;SURFACE COORDINATE
Q204=50	;2ND SET-UP CLEARANCE
Q212=0.5	; DECREMENT
Q205=3	;MIN. PLUNGING DEPTH
Q258=0.5	;UPPER ADV STOP DIST
Q259=1	;LOWER ADV STOP DIST
Q257=5	;DEPTH FOR CHIP BRKNG
Q256=0.2	;DIST FOR CHIP BRKNG
Q211=0.25	; DWELL TIME AT BOTTOM

# **BORE MILLING (Cycle 208)**

- 1 The TNC positions the tool in the tool axis at rapid traverse FMAX to the programmed set-up clearance above the workpiece surface and then moves the tool to the bore hole circumference on a rounded arc (if enough space is available).
- **2** The tool mills in a helix from the current position to the first plunging depth at the programmed feed rate.
- When the drilling depth is reached, the TNC once again traverses a full circle to remove the material remaining after the initial plunge.
- 4 The TNC then positions the tool at the center of the hole again.
- **5** Finally the TNC returns to the setup clearance at FMAX. and if programmed to the 2nd set-up clearance with FMAX.



#### Before programming, note the following:

Program a positioning block for the starting point (hole center) in the working plane with radius compensation R0.

The algebraic sign for the cycle parameter DEPTH determines the working direction. If you program DEPTH = 0, the cycle will not be executed.

If you have entered the bore hole diameter to be the same as the tool diameter, the TNC will bore directly to the entered depth without any helical interpolation.

i



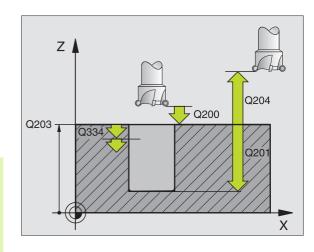
- ▶ Set-up clearance Q200 (incremental value): Distance between tool lower edge and workpiece surface.
- ▶ **Depth** Q201 (incremental value): Distance between workpiece surface and bottom of hole
- ▶ Feed rate for plunging Q206: Traversing speed of the tool during helical drilling in mm/min
- ▶ Infeed per helix Q334 (incremental value): Depth of the tool plunge with each helix (=360°)

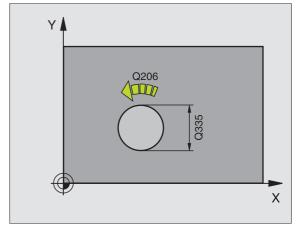


Note that if the infeed distance is too large, the tool or the workpiece may be damaged.

To prevent the infeeds being too large, enter the max. plunge angle of the tool in the tool table, column ANGLE, see "Tool Data," page 99. The TNC then calculates automatically the max. infeed permitted and changes your entered value accordingly.

- ▶ Workpiece surface coordinate Q203 (absolute value): Coordinate of the workpiece surface
- ▶ 2nd set-up clearance Q204 (incremental value): Coordinate in the tool axis at which no collision between tool and workpiece (clamping devices) can occur.
- Nominal diameter Q335 (absolute value): Bore-hole diameter. If you have entered the nominal diameter to be the same as the tool diameter, the TNC will bore directly to the entered depth without any helical interpolation.
- ▶ Roughing diameter Q342 (absolute value): As soon as you enter a value greater than 0 in Q342, the TNC no longer checks the ratio between the nominal diameter and the tool diameter. This allows you to rough-mill holes whose diameter is more than twice as large as the tool diameter.





#### **Example: NC blocks**

12 CYCL DEF 20	8 BORE MILLING
Q200=2	;SET-UP CLEARANCE
Q201=-80	;DEPTH
Q206=150	;FEED RATE FOR PLUNGING
Q334=1.5	;PLUNGING DEPTH
Q203=+100	;SURFACE COORDINATE
Q204=50	;2ND SET-UP CLEARANCE
Q335=25	;NOMINAL DIAMETER
Q342=0	;ROUGHING DIAMETER

# **TAPPING** with a floating tap holder (Cycle 2)

- 1 The tool drills to the total hole depth in one movement.
- 2 Once the tool has reached the total hole depth, the direction of spindle rotation is reversed and the tool is retracted to the starting position at the end of the dwell time.
- **3** At the starting position, the direction of spindle rotation reverses once again.



#### Before programming, note the following:

Program a positioning block for the starting point (hole center) in the working plane with radius compensation R0.

Program a positioning block for the starting point in the tool axis (set-up clearance above the workpiece surface).

The algebraic sign for the cycle parameter DEPTH determines the working direction. If you program DEPTH = 0, the cycle will not be executed.

A floating tap holder is required for tapping. It must compensate the tolerances between feed rate and spindle speed during the tapping process.

When a cycle is being run, the spindle speed override knob is disabled. The feed rate override knob is active only within a limited range, which is defined by the machine tool builder (refer to your machine manual).

For tapping right-hand threads activate the spindle with M3, for left-hand threads use M4.



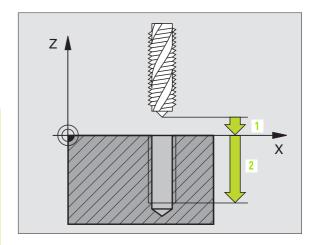
- ▶ Set-up clearance 1 (incremental value): Distance between tool tip (at starting position) and workpiece surface. Standard value: approx. 4 times the thread pitch
- ▶ Total hole depth 2 (thread length, incremental value): Distance between workpiece surface and end of thread
- Dwell time in seconds: Enter a value between 0 and 0.5 seconds to avoid wedging of the tool during retraction.
- ▶ Feed rate F: Traversing speed of the tool during tapping

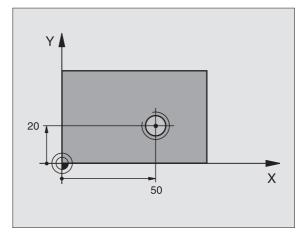
#### The feed rate is calculated as follows: $F = S \times p$

- F Feed rate (mm/min)
- S: Spindle speed (rpm)
- p: Thread pitch (mm)

#### Retracting after a program interruption

If you interrupt program run during tapping with the machine stop button, the TNC will display a soft key with which you can retract the tool.





#### **Example: NC blocks**

24 L Z+100 RO FMAX	
25 CYCL DEF 2.0 TAPPING	
26 CYCL DEF 2.1 SET UP 3	
27 CYCL DEF 2.2 DEPTH -20	
28 CYCL DEF 2.3 DWELL 0.4	
29 CYCL DEF 2.4 F100	
30 L X+50 Y+20 FMAX M3	
31 L Z+3 FMAX M99	

i

# **TAPPING NEW with floating tap holder** (Cycle 206)

- 1 The TNC positions the tool in the tool axis at rapid traverse FMAX to the programmed setup clearance above the workpiece surface.
- **2** The tool drills to the total hole depth in one movement.
- **3** Once the tool has reached the total hole depth, the direction of spindle rotation is reversed and the tool is retracted to the set-up clearance at the end of the dwell time, and — if programmed — to the 2nd set-up clearance with FMAX.
- **4** At the set-up clearance, the direction of spindle rotation reverses once again.



#### Before programming, note the following:

Program a positioning block for the starting point (hole center) in the working plane with radius compensation R0.

The algebraic sign for the cycle parameter DEPTH determines the working direction. If you program DEPTH = 0, the cycle will not be executed.

A floating tap holder is required for tapping. It must compensate the tolerances between feed rate and spindle speed during the tapping process.

When a cycle is being run, the spindle speed override knob is disabled. The feed rate override knob is active only within a limited range, which is defined by the machine tool builder (refer to your machine manual).

For tapping right-hand threads activate the spindle with M3, for left-hand threads use M4.



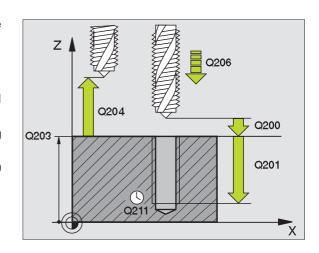
- ▶ Set-up clearance Q200 (incremental value): Distance between tool tip (at starting position) and workpiece surface. Standard value: approx. 4 times the thread pitch
- ► Total hole depth Q201 (thread length, incremental value): Distance between workpiece surface and end of thread
- ▶ Feed rate F Q206: Traversing speed of the tool during tapping
- ▶ Dwell time at bottom Q211: Enter a value between 0 and 0.5 seconds to avoid wedging of the tool during retraction
- ▶ Workpiece surface coordinate Q203 (absolute value): Coordinate of the workpiece surface
- ▶ 2nd set-up clearance Q204 (incremental value): Coordinate in the tool axis at which no collision between tool and workpiece (clamping devices) can occur.

#### The feed rate is calculated as follows: $F = S \times p$

- Feed rate (mm/min)
- S: Spindle speed (rpm)
- p: Thread pitch (mm)

#### Retracting after a program interruption

If you interrupt program run during tapping with the machine stop button, the TNC will display a soft key with which you can retract the tool.



25	CYCL DEF 206	TAPPING NEW
	Q200=2	;SET-UP CLEARANCE
	Q201=-20	;DEPTH
	Q206=150	;FEED RATE FOR PLUNGING
	Q211=0.25	; DWELL TIME AT BOTTOM
	Q203=+25	;SURFACE COORDINATE
	Q204=50	;2ND SET-UP CLEARANCE



Machine and control must be specially prepared by the machine tool builder for use of this cycle.

The TNC cuts the thread without a floating tap holder in one or more passes.

Rigid tapping offers the following advantages over tapping with a floating tap holder

- Higher machining speeds possible
- Repeated tapping of the same thread is possible; repetitions are enabled via spindle orientation to the 0° position during cycle call (depending on machine parameter 7160).
- Increased traverse range of the spindle axis due to absence of a floating tap holder.



#### Before programming, note the following:

Program a positioning block for the starting point (hole center) in the working plane with radius compensation R0.

Program a positioning block for the starting point in the tool axis (set-up clearance above the workpiece surface).

The algebraic sign for the parameter total hole depth determines the working direction.

The TNC calculates the feed rate from the spindle speed. If the spindle speed override is used during tapping, the feed rate is automatically adjusted.

The feed-rate override knob is disabled.

At the end of the cycle the spindle comes to a stop. Before the next operation, restart the spindle with M3 (or M4).



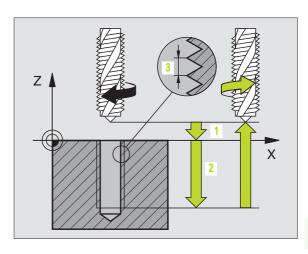
- ▶ Set-up clearance 1 (incremental value): Distance between tool tip (at starting position) and workpiece surface
- ▶ Total hole depth 2 (incremental value): Distance between workpiece surface (beginning of thread) and end of thread
- Pitch 3:

Pitch of the thread. The algebraic sign differentiates between right-hand and left-hand threads:

- += right-hand thread
- -= left-hand thread

#### Retracting after a program interruption

If you interrupt program run during tapping with the machine stop button, the TNC will display the soft key MANUAL OPERATION. If you press the MANUAL OPERATION key, you can retract the tool under program control. Simply press the positive axis direction button of the active tool axis.



#### **Example: NC blocks**

18 CYCL DEF 17.0 RIGID TAPPING GS

CYCL DEF 17.1 SET UP 2

CYCL DEF 17.2 DEPTH -20 20

21 CYCL DEF 17.3 PITCH +1

# RIGID TAPPING without a floating tap holder **TAPPING (Cycle 207)**



Machine and control must be specially prepared by the machine tool builder for use of this cycle.

The TNC cuts the thread without a floating tap holder in one or more

Rigid tapping offers the following advantages over tapping with a floating tap holder:See "RIGID TAPPING (Cycle 17)," page 229.

- The TNC positions the tool in the tool axis at rapid traverse FMAX to the programmed setup clearance above the workpiece surface.
- The tool drills to the total hole depth in one movement.
- Once the tool has reached the total hole depth, the direction of spindle rotation is reversed and the tool is retracted to the set-up clearance at the end of the dwell time. and — if programmed — to the 2nd set-up clearance with FMAX.
- 4 The TNC stops the spindle turning at set-up clearance.



#### Before programming, note the following:

Program a positioning block for the starting point (hole center) in the working plane with radius compensation R0.

The algebraic sign for the parameter total hole depth determines the working direction.

The TNC calculates the feed rate from the spindle speed. If the spindle speed override is used during tapping, the feed rate is automatically adjusted.

The feed-rate override knob is disabled.

At the end of the cycle the spindle comes to a stop. Before the next operation, restart the spindle with M3 (or M4).



- ▶ Set-up clearance Q200 (incremental value): Distance between tool tip (at starting position) and workpiece surface
- ▶ Total hole depth Q201 (incremental value): Distance between workpiece surface and end of thread

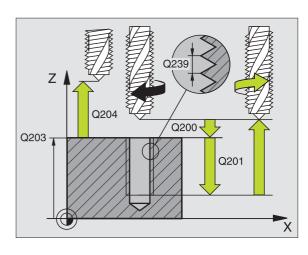
#### ▶ Pitch Q239

Pitch of the thread. The algebraic sign differentiates between right-hand and left-hand threads:

- += right-hand thread
- -= left-hand thread
- ▶ Workpiece surface coordinate Q203 (absolute value): Coordinate of the workpiece surface
- ▶ 2nd set-up clearance Q204 (incremental value): Coordinate in the tool axis at which no collision between tool and workpiece (clamping devices) can occur.

#### Retracting after a program interruption

If you interrupt program run during thread cutting with the machine stop button, the TNC will display the soft key MANUAL OPERATION. If you press the MANUAL OPERATION key, you can retract the tool under program control. Simply press the positive axis direction button of the active tool axis.



26	CYCL DEF 2	07 RIGID TAPPING NEW
	Q200=2	;SET-UP CLEARANCE
	Q201=-20	;DEPTH
	Q239=+1	;THREAD PITCH
	Q203=+25	;SURFACE COORDINATE
	Q204=50	;2ND SET-UP CLEARANCE



# **THREAD CUTTING (Cycle 18)**



Machine and control must be specially prepared by the machine tool builder for use of this cycle.

Cycle 18 THREAD CUTTING is performed by means of spindle control. The tool moves with the active spindle speed from its current position to the entered depth. As soon as it reaches the end of thread, spindle rotation is stopped. Tool approach and departure must be programmed separately. The most convenient way to do this is by using OEM cycles. The machine tool builder can give you further information.



#### Before programming, note the following:

The TNC calculates the feed rate from the spindle speed. If the spindle speed override is used during thread cutting, the feed rate is automatically adjusted.

The feed-rate override knob is disabled.

The TNC automatically activates and deactivates spindle rotation. Do not program M3 or M4 before cycle call.



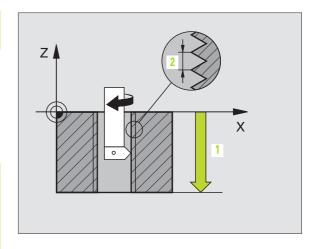
▶ Total hole depth 1: Distance between current tool position and end of thread

The algebraic sign for the total hole depth determines the working direction (a negative value means a negative working direction in the tool axis)

#### ▶ Pitch 2:

Pitch of the thread. The algebraic sign differentiates between right-hand and left-hand threads:

- += right-hand thread (M3 with negative depth)
- = left-hand thread (M4 with negative depth)



#### **Example: NC blocks**

22 CYCL DEF 18.0 THREAD CUTTING

CYCL DEF 18.1 DEPTH -20

24 CYCL DEF 18.2 PITCH +1

# **TAPPING WITH CHIP BREAKING (Cycle 209)**



Machine and control must be specially prepared by the machine tool builder for use of this cycle.

The tool machines the thread in several passes until it reaches the programmed depth. You can define in a parameter whether the tool is to be retracted completely from the hole for chip breaking.

- 1 The TNC positions the tool in the tool axis at rapid traverse FMAX to the programmed setup clearance above the workpiece surface. There it carries out an oriented spindle stop.
- **2** The tool moves to the programmed infeed depth, reverses the direction of spindle rotation and retracts by a specific distance or completely for chip release, depending on the definition.
- **3** It then reverses the direction of spindle rotation again and advances to the next infeed depth.
- **4** The TNC repeats this process (2 to 3) until the programmed thread depth is reached.
- 5 The tool is then retracted to set-up clearance. and if programmed to the 2nd set-up clearance with FMAX.
- **6** The TNC stops the spindle turning at set-up clearance.



#### Before programming, note the following:

Program a positioning block for the starting point (hole center) in the working plane with radius compensation R0.

The algebraic sign for the parameter thread depth determines the working direction.

The TNC calculates the feed rate from the spindle speed. If the spindle speed override is used during tapping, the feed rate is automatically adjusted.

The feed-rate override knob is disabled.

At the end of the cycle the spindle comes to a stop. Before the next operation, restart the spindle with M3 (or M4).



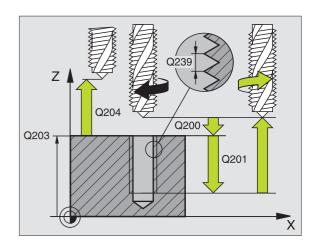
- ▶ Set-up clearance Q200 (incremental value): Distance between tool tip (at starting position) and workpiece surface
- ▶ Thread depth Q201 (incremental value): Distance between workpiece surface and end of thread
- ▶ Pitch Q239

Pitch of the thread. The algebraic sign differentiates between right-hand and left-hand threads:

- += right-hand thread
- -= left-hand thread
- ▶ Workpiece surface coordinate Q203 (absolute value): Coordinate of the workpiece surface
- ▶ 2nd set-up clearance Q204 (incremental value): Coordinate in the tool axis at which no collision between tool and workpiece (clamping devices) can
- ▶ Infeed depth for chip breaking Q257 (incremental value): Depth at which TNC carries out chip breaking
- ▶ Retraction rate for chip breaking Q256: The TNC multiplies the pitch Q239 by the programmed value and retracts the tool by the calculated value during chip breaking. If you enter Q256 = 0, the TNC retracts the tool completely from the hole (to set-up clearance) for chip release.
- ▶ Angle for spindle orientation Q336 (absolute value): Angle at which the TNC positions the tool before machining the thread. This allows you to regroove the thread, if required.

#### Retracting after a program interruption

If you interrupt program run during thread cutting with the machine stop button, the TNC will display the soft key MANUAL OPERATION. If you press the MANUAL OPERATION key, you can retract the tool under program control. Simply press the positive axis direction button of the active tool axis.



26	CYCL DEF 2	09 TAPPING W/ CHIP BRKG
	Q200=2	;SET-UP CLEARANCE
	Q201=-20	;DEPTH
	Q239=+1	;THREAD PITCH
	Q203=+25	;SURFACE COORDINATE
	Q204=50	;2ND SET-UP CLEARANCE
	Q257=5	;DEPTH FOR CHIP BRKNG
	Q256=+25	;DIST FOR CHIP BRKNG
	Q336=50	;ANGLE OF SPINDLE



# **Fundamentals of thread milling**

#### **Prerequisites**

- Your machine tool should feature internal spindle cooling (cooling lubricant min. 30 bar, compressed air supply min. 6 bar).
- Thread milling usually leads to distortions of the thread profile. To correct this effect, you need tool-specific compensation values which are given in the tool catalog or are available from the tool manufacturer. You program the compensation with the delta value for the tool radius DR in the tool call.
- The Cycles 262, 263, 264 and 267 can only be used with rightward rotating tools. For Cycle 265, you can use rightward and leftward rotating tools.
- The working direction is determined by the following input parameters: Algebraic sign Q239 (+ = right-hand thread /- = left-hand thread) and milling method Q351 (+1 = climb /-1 = up-cut). The table below illustrates the interrelation between the individual input parameters for rightward rotating tools.

Internal thread	Pitch	Climb/Up- cut	Work direction
Right-handed	+	+1(RL)	Z+
Left-handed	_	-1(RR)	Z+
Right-handed	+	-1(RR)	Z-
Left-handed	_	+1(RL)	Z–

External thread	Pitch	Climb/Up- cut	Work direction
Right-handed	+	+1(RL)	Z–
Left-handed	-	-1(RR)	Z–
Right-handed	+	-1(RR)	Z+
Left-handed	_	+1(RL)	Z+

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#### **Danger of collision**

Always program the same algebraic sign for the infeeds: Cycles comprise several sequences of operation that are independent of each other. The order of precedence according to which the work direction is determined is described with the individual cycles. If you want to repeat specific machining operation of a cycle, for example with only the countersinking process, enter 0 for the thread depth. The work direction will then be determined from the countersinking depth.

#### Procedure in the case of a tool break!

If a tool break occurs during thread cutting, stop the program run, change to the Positioning with MDI operating mode and move the tool in a linear path to the hole center. You can then retract the tool in the infeed axis and replace it.



The TNC references the programmed feed rate during thread milling to the tool cutting edge. Since the TNC, however, always displays the feed rate relative to the path of the tool tip, the displayed value does not match the programmed value.

The machining direction of the thread changes if you execute a thread milling cycle in connection with Cycle 8 MIRRORING with only one axis.

# **THREAD MILLING (Cycle 262)**

- **1** The TNC positions the tool in the tool axis at rapid traverse FMAX to the programmed setup clearance above the workpiece surface.
- 2 The tool moves at the programmed feed rate for pre-positioning to the starting plane. The starting plane is derived from the algebraic sign of the thread pitch, the milling method (climb or up-cut milling) and the number of threads per step.
- **3** The tool then approaches the thread diameter tangentially in a helical movement. Before the helical approach, a compensating motion of the tool axis is carried out in order to begin at the programmed starting plane for the thread path.
- **4** Depending on the setting of the parameter for the number of threads, the tool mills the thread in one, in several spaced or in one continuous helical movement.
- **5** After this, the tool departs the contour tangentially and returns to the starting point in the working plane.
- **6** At the end of the cycle, the TNC retracts the tool in rapid traverse to set-up clearance or, if programmed, to the 2nd set-up clearance



#### Before programming, note the following:

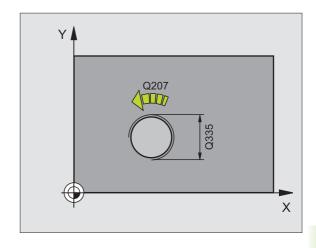
Program a positioning block for the starting point (hole center) in the working plane with radius compensation R0.

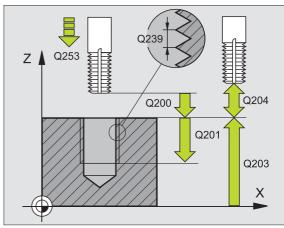
The algebraic sign for the cycle parameter thread depth determines the working direction. If you program the thread depth = 0, the cycle will not be executed.

The thread diameter is approached in a semi-circle from the center. A pre-positioning movement to the side is carried out if the pitch of the tool diameter is four times smaller than the thread diameter.



- Nominal diameter Q335: Nominal thread diameter
- ▶ Thread pitch Q239: Pitch of the thread. The algebraic sign differentiates between right-hand and left-hand threads:
  - += right-hand thread
  - = left-hand thread
- ▶ Thread depth Q201 (incremental value): Distance between workpiece surface and root of thread
- ▶ Threads per step Q355: Number of thread revolutions by which the tool is offset, see figure at lower right
  - **0** = one 360° helical path to the depth of thread
  - 1 = continuous helical path over the entire length of the thread
  - >1 = several helical paths with approach and departure; between them, the TNC offsets the tool by Q355, multiplied by the pitch







- ▶ Feed rate for pre-positioning Q253: Traversing speed of the tool when moving in and out of the workpiece, in mm/min
- ▶ Climb or up-cut Q351: Type of milling operation with
  - +1 = climb milling
  - -1 = up-cut milling
- ▶ Set-up clearance Q200 (incremental value): Distance between tool tip and workpiece surface
- ▶ Workpiece surface coordinate Q203 (absolute value): Coordinate of the workpiece surface
- ▶ 2nd set-up clearance Q204 (incremental value): Coordinate in the tool axis at which no collision between tool and workpiece (clamping devices) can occur.
- ▶ Feed rate for milling Q207: Traversing speed of the tool in mm/min while milling.

25 CYCL DEF 262 THREAD	MILLING
Q335=10 ; NOMINAL	. DIAMETER
Q239=+1.5 ;PITCH	
Q201=-20 ;THREAD	DEPTH
Q355=O ; THREADS	PER STEP
Q253=750 ;F PRE-	POSITIONING
Q351=+1 ;CLIMB (	R UP-CUT
Q200=2 ;SET-UP	CLEARANCE
Q203=+30 ; SURFACI	COORDINATE
Q204=50 ;2ND SET	-UP CLEARANCE
Q207=500 ; FEED RA	TE FOR MILLING



# THREAD MILLING/COUNTERSINKING (Cycle 263)

1 The TNC positions the tool in the tool axis at rapid traverse FMAX to the programmed setup clearance above the workpiece surface.

#### Countersinking

- 2 The tool moves at the feed rate for pre-positioning to the countersinking depth minus the setup clearance, and then at the feed rate for countersinking to the countersinking depth.
- 3 If a safety clearance to the side has been entered, the TNC immediately positions the tool at the feed rate for pre-positioning to the countersinking depth
- 4 Then, depending on the available space, the TNC makes a tangential approach to the core diameter, either tangentially from the center or with a pre-positioning move to the side, and follows a circular path.

#### Countersinking at front

- **5** The tool moves at the feed rate for pre-positioning to the sinking depth at front.
- The TNC positions the tool without compensation from the center on a semicircle to the offset at front, and then follows a circular path at the feed rate for countersinking.
- The tool then moves in a semicircle to the hole center.

#### Thread milling

- 8 The TNC moves the tool at the programmed feed rate for prepositioning to the starting plane for the thread. The starting plane is determined from the thread pitch and the type of milling (climb or up-cut).
- **9** Then the tool moves tangentially on a helical path to the thread diameter and mills the thread with a 360° helical motion.
- **10** After this, the tool departs the contour tangentially and returns to the starting point in the working plane.

11 At the end of the cycle, the TNC retracts the tool in rapid traverse to set-up clearance or, if programmed, to the 2nd set-up clearance



#### Before programming, note the following:

Program a positioning block for the starting point (hole center) in the working plane with radius compensation R0.

The algebraic sign of the cycle parameters depth of thread, countersinking depth or sinking depth at front determines the working direction. The working direction is defined in the following sequence:

1st: Depth of thread

2nd: Countersinking depth

3rd: Depth at front

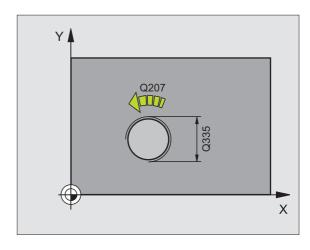
If you program a depth parameter to be 0, the TNC does not execute that step.

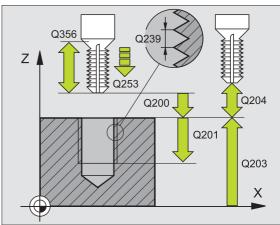
if you wish to countersink with the front of the tool, define the countersinking depth as 0.

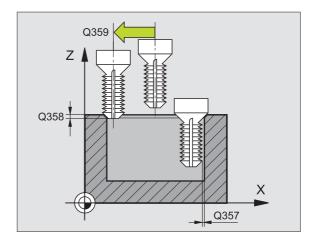
Program the thread depth as a value smaller than the countersinking depth by at least one-third the thread pitch.



- Nominal diameter Q335: Nominal thread diameter
- ▶ Thread pitch Q239: Pitch of the thread. The algebraic sign differentiates between right-hand and left-hand threads:
  - += right-hand thread
  - = left-hand thread
- ▶ Thread depth Q201 (incremental value): Distance between workpiece surface and root of thread
- ➤ Countersinking depth Q356 (incremental value):
  Distance between tool point and the top surface of the workpiece
- ▶ Feed rate for pre-positioning Q253: Traversing speed of the tool when moving in and out of the workpiece, in mm/min
- ▶ Climb or up-cut Q351: Type of milling operation with M03
  - +1 = climb milling
  - -1 = up-cut milling
- ▶ **Set-up clearance** Q200 (incremental value): Distance between tool tip and workpiece surface
- Set-up clearance to the side Q357 (incremental value): Distance between tool tooth and the wall
- ▶ **Depth at front** Q358 (incremental value): Distance between tool point and the top surface of the workpiece for countersinking at the front of the tool
- ▶ Countersinking offset at front Q359 (incremental value): Distance by which the TNC moves the tool center away from the hole center







- ▶ Workpiece surface coordinate Q203 (absolute value): Coordinate of the workpiece surface
- ▶ 2nd set-up clearance Q204 (incremental value): Coordinate in the tool axis at which no collision between tool and workpiece (clamping devices) can occur.
- ▶ Feed rate for counterboring Q254: Traversing speed of the tool during counterboring in mm/min
- ▶ Feed rate for milling Q207: Traversing speed of the tool in mm/min while milling.

25 CYCL DEF 26 COUNTERSINKING	3 THREAD MILLING/
Q335=10	;NOMINAL DIAMETER
Q239=+1.5	; PITCH
Q201=-16	;THREAD DEPTH
Q356=-20	;COUNTERSINKING DEPTH
Q253=750	;F PRE-POSITIONING
0351=+1	;CLIMB OR UP-CUT
Q200=2	;SET-UP CLEARANCE
Q357=0.2	;CLEARANCE TO SIDE
Q358=+0	;DEPTH AT FRONT
Q359=+0	;OFFSET AT FRONT
0203=+30	;SURFACE COORDINATE
Q204=50	;2ND SET-UP CLEARANCE
Q254=150	;F COUNTERSINKING
Q207=500	;FEED RATE FOR MILLING

# **THREAD DRILLING/MILLING (Cycle 264)**

1 The TNC positions the tool in the tool axis at rapid traverse FMAX to the programmed setup clearance above the workpiece surface.

#### **Drilling**

- **2** The tool drills to the first plunging depth at the programmed feed rate for plunging.
- **3** If you have programmed chip breaking, the tool then retracts by the entered retraction value. If you are working without chip breaking, the tool is moved at rapid traverse to setup clearance and then at FMAX to the entered starting position above the first plunging depth.
- **4** The tool then advances with another infeed at the programmed feed rate.
- **5** The TNC repeats this process (2 to 4) until the programmed total hole depth is reached.

#### Countersinking at front

- **6** The tool moves at the feed rate for pre-positioning to the sinking depth at front.
- 7 The TNC positions the tool without compensation from the center on a semicircle to the offset at front, and then follows a circular path at the feed rate for countersinking.
- **8** The tool then moves in a semicircle to the hole center.

#### Thread milling

- **9** The TNC moves the tool at the programmed feed rate for prepositioning to the starting plane for the thread. The starting plane is determined from the thread pitch and the type of milling (climb or up-cut).
- **10** Then the tool moves tangentially on a helical path to the thread diameter and mills the thread with a 360° helical motion.
- **11** After this, the tool departs the contour tangentially and returns to the starting point in the working plane.
- 12 At the end of the cycle, the TNC retracts the tool in rapid traverse to set-up clearance or, if programmed, to the 2nd set-up clearance



#### Before programming, note the following:

Program a positioning block for the starting point (hole center) in the working plane with radius compensation R0.

The algebraic sign of the cycle parameters depth of thread, countersinking depth or sinking depth at front determines the working direction. The working direction is defined in the following sequence:

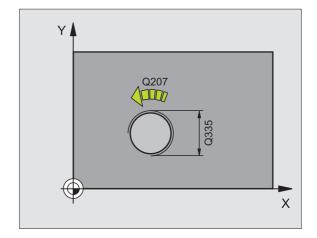
1st: Depth of thread 2nd: Total hole depth 3rd: Depth at front

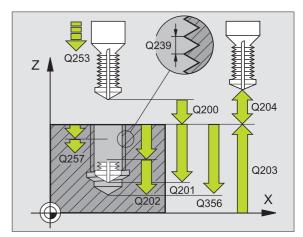
If you program a depth parameter to be 0, the TNC does not execute that step.

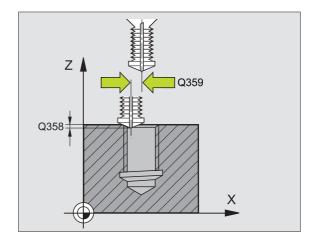
Program the thread depth as a value smaller than the total hole depth by at least one-third the thread pitch.



- Nominal diameter Q335: Nominal thread diameter
- ▶ Thread pitch Q239: Pitch of the thread. The algebraic sign differentiates between right-hand and left-hand threads:
  - += right-hand thread
  - = left-hand thread
- ▶ Thread depth Q201 (incremental value): Distance between workpiece surface and root of thread
- ▶ Total hole depth Q356 (incremental value): Distance between workpiece surface and bottom of hole
- ▶ Feed rate for pre-positioning Q253: Traversing speed of the tool when moving in and out of the workpiece, in mm/min
- ▶ Climb or up-cut Q351: Type of milling operation with M03
  - **+1** = climb milling
  - -1 = up-cut milling
- ▶ Plunging depth Q202 (incremental value): Infeed per cut. The depth does not have to be a multiple of the plunging depth. The TNC will go to depth in one movement if:
  - the plunging depth is equal to the depth
  - the plunging depth is greater than the depth
- ▶ Upper advanced stop distance Q258 (incremental value): Set-up clearance for rapid traverse positioning when the TNC moves the tool again to the current plunging depth after retraction from the hole
- ▶ Infeed depth for chip breaking Q257 (incremental value): Depth at which TNC carries out chip breaking. There is no chip breaking if 0 is entered.
- ▶ Retraction rate for chip breaking Q256 (incremental value): Value by which the TNC retracts the tool during chip breaking
- ▶ Depth at front Q358 (incremental value): Distance between tool point and the top surface of the workpiece for countersinking at the front of the tool
- ▶ Countersinking offset at front Q359 (incremental value): Distance by which the TNC moves the tool center away from the hole center









- ▶ Set-up clearance Q200 (incremental value): Distance between tool tip and workpiece surface
- ▶ Workpiece surface coordinate Q203 (absolute value): Coordinate of the workpiece surface
- ▶ 2nd set-up clearance Q204 (incremental value): Coordinate in the tool axis at which no collision between tool and workpiece (clamping devices) can
- ▶ Feed rate for plunging Q206: Traversing speed of the tool during drilling in mm/min
- ▶ Feed rate for milling Q207: Traversing speed of the tool in mm/min while milling.

	25	CYCL DEF 2	64 THREAD DRILLNG/MLLNG
		Q335=10	;NOMINAL DIAMETER
		Q239=+1.5	; PITCH
		Q201=-16	;THREAD DEPTH
		Q356=-20	;TOTAL HOLE DEPTH
		Q253=750	;F PRE-POSITIONING
		Q351=+1	;CLIMB OR UP-CUT
		Q202=5	;PLUNGING DEPTH
		Q258=0.2	;ADVANCED STOP DISTANCE
		Q257=5	;DEPTH FOR CHIP BRKNG
		Q256=0:2	;DIST FOR CHIP BRKNG
		Q358=+0	;DEPTH AT FRONT
		Q359=+0	;OFFSET AT FRONT
		Q200=2	;SET-UP CLEARANCE
		Q203=+30	;SURFACE COORDINATE
		Q204=50	;2ND SET-UP CLEARANCE
		Q206=150	;FEED RATE FOR PLUNGING
		Q207=500	;FEED RATE FOR MILLING
1			

# HELICAL THREAD DRILLING/MILLING (Cycle 265)

1 The TNC positions the tool in the tool axis at rapid traverse FMAX to the programmed setup clearance above the workpiece surface.

#### Countersinking at front

- 2 If countersinking is before thread milling, the tool moves at the feed rate for countersinking to the sinking depth at front. If countersinking is after thread milling, the tool moves at the feed rate for pre-positioning to the countersinking depth.
- The TNC positions the tool without compensation from the center on a semicircle to the offset at front, and then follows a circular path at the feed rate for countersinking.
- **4** The tool then moves in a semicircle to the hole center.

#### Thread milling

- The tool moves at the programmed feed rate for pre-positioning to the starting plane for the thread.
- The tool then approaches the thread diameter tangentially in a helical movement.
- The tool moves on a continuous helical downward path until it reaches the thread depth.
- After this, the tool departs the contour tangentially and returns to the starting point in the working plane.
- At the end of the cycle, the TNC retracts the tool in rapid traverse to set-up clearance, or — if programmed — to the 2nd set-up clearance.



#### Before programming, note the following:

Program a positioning block for the starting point (hole center) in the working plane with radius compensation R0.

The algebraic sign of the cycle parameters depth of thread or sinking depth at front determines the working direction. The working direction is defined in the following sequence:

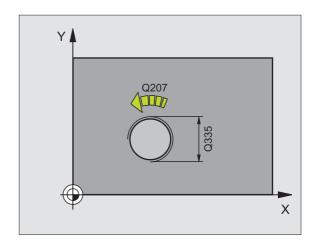
1st: Depth of thread 2nd: Depth at front

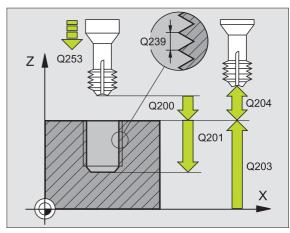
If you program a depth parameter to be 0, the TNC does not execute that step.

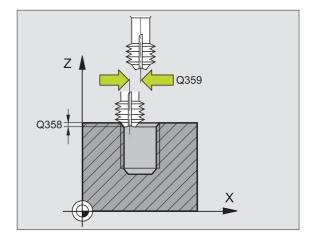
The type of milling (up-cut/climb) is determined by the thread (right-hand/left-hand) and the direction of tool rotation, since it is only possible to work in the direction of the tool.



- Nominal diameter Q335: Nominal thread diameter
- ▶ Thread pitch Q239: Pitch of the thread. The algebraic sign differentiates between right-hand and left-hand threads:
  - += right-hand thread
  - -= left-hand thread
- ▶ Thread depth Q201 (incremental value): Distance between workpiece surface and root of thread
- ▶ Feed rate for pre-positioning Q253: Traversing speed of the tool when moving in and out of the workpiece, in mm/min
- ▶ **Depth at front** Q358 (incremental value): Distance between tool point and the top surface of the workpiece for countersinking at the front of the tool
- ▶ Countersinking offset at front Q359 (incremental value): Distance by which the TNC moves the tool center away from the hole center
- Countersink Q360: Execution of the chamfer0 = before thread machining
  - 1 = after thread machining
- ▶ **Set-up clearance** Q200 (incremental value): Distance between tool tip and workpiece surface







- ▶ 2nd set-up clearance Q204 (incremental value): Coordinate in the tool axis at which no collision between tool and workpiece (clamping devices) can occur.
- ▶ Feed rate for counterboring Q254: Traversing speed of the tool during counterboring in mm/min
- ▶ Feed rate for milling Q207: Traversing speed of the tool in mm/min while milling.

25 CYCL DEF 265 HEL. THREAD DRLG/MLG
Q335=10 ;NOMINAL DIAMETER
Q239=+1.5 ;PITCH
Q201=-16 ;THREAD DEPTH
Q253=750 ;F PRE-POSITIONING
Q351=+1 ;CLIMB OR UP-CUT
Q358=+0 ; DEPTH AT FRONT
Q359=+0 ;OFFSET AT FRONT
Q360=0 ; COUNTERSINKING
Q200=2 ;SET-UP CLEARANCE
Q203=+30 ;SURFACE COORDINATE
Q204=50 ;2ND SET-UP CLEARANCE
Q254=150 ;F COUNTERSINKING
Q207=500 ;FEED RATE FOR MILLING

# **OUTSIDE THREAD MILLING (Cycle 267)**

1 The TNC positions the tool in the tool axis at rapid traverse FMAX to the programmed setup clearance above the workpiece surface.

#### **Countersinking at front**

- 2 The TNC moves on the reference axis of the working plane from the center of the stud to the starting point for countersinking at front. The position of the starting point is determined by the thread radius, tool radius and pitch.
- **3** The tool moves at the feed rate for pre-positioning to the sinking depth at front.
- **4** The TNC positions the tool without compensation from the center on a semicircle to the offset at front, and then follows a circular path at the feed rate for countersinking.
- **5** The tool then moves in a semicircle to the starting point.

#### Thread milling

- **6** The TNC positions the tool to the starting point if there has been no previous countersinking at front. Starting point for thread milling = starting point for countersinking at front.
- 7 The tool moves at the programmed feed rate for pre-positioning to the starting plane. The starting plane is derived from the algebraic sign of the thread pitch, the milling method (climb or up-cut milling) and the number of threads per step.
- **8** The tool then approaches the thread diameter tangentially in a helical movement.
- **9** Depending on the setting of the parameter for the number of threads, the tool mills the thread in one, in several spaced or in one continuous helical movement.
- **10** After this, the tool departs the contour tangentially and returns to the starting point in the working plane.

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11 At the end of the cycle, the TNC retracts the tool in rapid traverse to set-up clearance, or — if programmed — to the 2nd set-up clearance.



#### Before programming, note the following:

Program a positioning block for the starting point (stud center) in the working plane with radius compensation R0.

The offset required before countersinking at the front should be determined ahead of time. You must enter the value from the center of the stud to the center of the tool (uncorrected value).

The algebraic sign of the cycle parameters depth of thread or sinking depth at front determines the working direction. The working direction is defined in the following sequence:

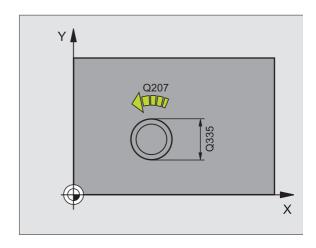
1st: Depth of thread 2nd: Depth at front

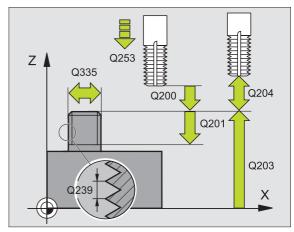
If you program a depth parameter to be 0, the TNC does not execute that step.

The algebraic sign for the cycle parameter thread depth determines the working direction.



- Nominal diameter Q335: Nominal thread diameter
- ▶ Thread pitch Q239: Pitch of the thread. The algebraic sign differentiates between right-hand and left-hand threads:
  - += right-hand thread
  - **–** = left-hand thread
- ▶ Thread depth Q201 (incremental value): Distance between workpiece surface and root of thread
- ▶ Threads per step Q355: Number of thread revolutions by which the tool is offset, see figure at lower right 0 = one 360° helical path to the depth of thread
  - **1** = continuous helical path over the entire length of the thread
  - >1 = several helical paths with approach and departure; between them, the TNC offsets the tool by Q355, multiplied by the pitch
- ▶ Feed rate for pre-positioning Q253: Traversing speed of the tool when moving in and out of the workpiece, in mm/min
- ▶ Climb or up-cut Q351: Type of milling operation with M03
  - +1 = climb milling
  - -1 = up-cut milling







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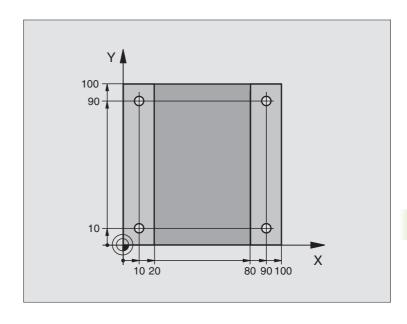
- ▶ Set-up clearance Q200 (incremental value): Distance between tool tip and workpiece surface
- ▶ **Depth at front** Q358 (incremental value): Distance between tool point and the top surface of the workpiece for countersinking at the front of the tool
- ➤ Countersinking offset at front Q359 (incremental value): Distance by which the TNC moves the tool center away from the stud center
- ▶ Workpiece surface coordinate Q203 (absolute value): Coordinate of the workpiece surface
- ▶ 2nd set-up clearance Q204 (incremental value): Coordinate in the tool axis at which no collision between tool and workpiece (clamping devices) can occur.
- ▶ Feed rate for counterboring Q254: Traversing speed of the tool during counterboring in mm/min
- Feed rate for milling Ω207: Traversing speed of the tool in mm/min while milling.

#### **Example: NC blocks**

25	CYCL DEF 2	67 OUTSIDE THREAD MLLNG
	Q335=10	;NOMINAL DIAMETER
	Q239=+1.5	; PITCH
	Q201=-20	;THREAD DEPTH
	Q355=0	;THREADS PER STEP
	Q253=750	;F PRE-POSITIONING
	Q351=+1	;CLIMB OR UP-CUT
	Q200=2	;SET-UP CLEARANCE
	Q358=+O	;DEPTH AT FRONT
	Q359=+0	;OFFSET AT FRONT
	Q203=+30	;SURFACE COORDINATE
	Q204=50	;2ND SET-UP CLEARANCE
	Q254=150	;F COUNTERSINKING
	Q207=500	;FEED RATE FOR MILLING

8 Programming: Cycles

# **Example: Drilling cycles**



O BEGIN PGM C200 MM	
1 BLK FORM 0.1 Z X+0 Y+0 Z-20	Define the workpiece blank
2 BLK FORM 0.2 X+100 Y+100 Z+0	
3 TOOL DEF 1 L+0 R+3	Define the tool
4 TOOL CALL 1 Z S4500	Tool call
5 L Z+250 RO F MAX	Retract the tool
6 CYCL DEF 200 DRILLING	Define cycle
Q200=2 ;SET-UP CLEARANCE	
Q201=-15 ;DEPTH	
Q206=250 ;FEED RATE FOR PLNGNG	
Q202=5 ;PLUNGING DEPTH	
Q210=0 ; DWELL TIME AT TOP	
Q203=-10 ;SURFACE COORDINATE	
Q204=20 ;2ND SET-UP CLEARANCE	
Q211=0.2 ; DWELL TIME AT BOTTOM	

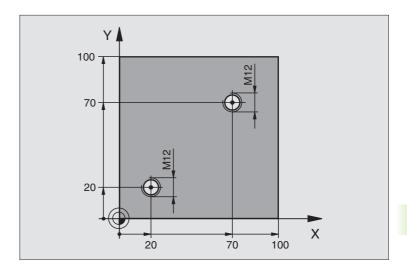
i

7 L X+10 Y+10 R0 F MAX M3	Approach hole 1, spindle ON
8 CYCL CALL	Call the cycle
9 L Y+90 RO F MAX M99	Approach hole 2, call cycle
10 L X+90 RO F MAX M99	Approach hole 3, call cycle
11 L Y+10 RO F MAX M99	Approach hole 4, call cycle
12 L Z+250 RO F MAX M2	Retract in the tool axis, end program
13 END PGM C200 MM	

# **Example: Drilling cycles**

#### **Program sequence**

- Program the drilling cycle in the main program
- Program machining within a subprogram, see "Subprograms," page 343



O BEGIN PGM C18 MM	
1 BLK FORM 0.1 Z X+0 Y+0 Z-20	Define the workpiece blank
2 BLK FORM 0.2 X+100 Y+100 Z+0	
3 TOOL DEF 1 L+0 R+6	Define the tool
4 TOOL CALL 1 Z S100	Tool call
5 L Z+250 RO F MAX	Retract the tool
6 CYCL DEF 18.0 THREAD CUTTING	Define THREAD CUTTING cycle
7 CYCL DEF 18.1 DEPTH +30	
8 CYCL DEF 18.2 PITCH -1.75	
9 L X+20 Y+20 RO F MAX	Approach hole 1
10 CALL LBL 1	Call subprogram 1
11 L X+70 Y+70 RO F MAX	Approach hole 2
12 CALL LBL 1	Call subprogram 1
13 L Z+250 RO F MAX M2	Retract tool, end of main program

i

14 LBL 1	Subprogram 1: Thread cutting
15 CYCL DEF 13.0 ORIENTATION	Define the spindle angle (makes it possible to cut repeatedly)
16 CYCL DEF 13.1 ANGLE 0	
17 L M19	Orient the spindle (machine-specific M function)
18 L IX-2 RO F1000	Tool offset to prevent collision during tool infeed (dependent
	on core diameter and tool)
19 L Z+5 RO F MAX	Pre-position in rapid traverse
20 L Z-30 R0 F1000	Move to starting depth
21 L IX+2	Reset the tool to hole center
22 CYCL CALL	Call Cycle 18
23 L Z+5 RO F MAX	Retract tool
24 LBL 0	End of subprogram 1
25 END PGM C18 MM	

# 8.4 Cycles for milling pockets, studs and slots

# Overview

Cycle	Soft key
4 POCKET MILLING (rectangular) Roughing cycle without automatic pre-positioning	4 💿
212 POCKET FINISHING (rectangular) Finishing cycle with automatic pre-positioning, 2nd set-up clearance	212
213 STUD FINISHING (rectangular) Finishing cycle with automatic pre-positioning, 2nd set-up clearance	213
5 CIRCULAR POCKET Roughing cycle without automatic pre-positioning	5 🔅
214 CIRCULAR POCKET FINISHING Finishing cycle with automatic pre-positioning, 2nd set-up clearance	214
215 CIRCULAR STUD FINISHING Finishing cycle with automatic pre-positioning, 2nd set-up clearance	215
3 SLOT MILLING Roughing/finishing cycle without automatic pre- positioning, vertical depth infeed	3
210 SLOT RECIP. PLNG Roughing/finishing cycle with automaticpre- positioning, with reciprocating plunge infeed	210
211 CIRCULAR SLOT Roughing/finishing cycle with automaticpre- positioning, with reciprocating plunge infeed	211

# **POCKET MILLING (Cycle 4)**

- 1 The tool penetrates the workpiece at the starting position (pocket center) and advances to the first plunging depth.
- 2 The cutter begins milling in the positive axis direction of the longer side (on square pockets, always starting in the positive Y direction) and then roughs out the pocket from the inside out.
- **3** This process (1 to 2) is repeated until the depth is reached.
- 4 At the end of the cycle, the TNC retracts the tool to the starting position.



#### Before programming, note the following:

This cycle requires a center-cut end mill (ISO 1641), or pilot drilling at the pocket center.

Pre-position over the pocket center with radius compensation R0.

Program a positioning block for the starting point in the tool axis (set-up clearance above the workpiece surface).

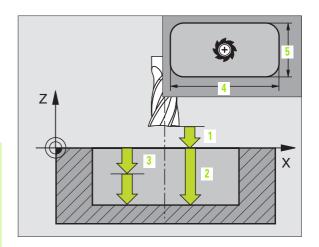
The algebraic sign for the cycle parameter DEPTH determines the working direction. If you program DEPTH = 0, the cycle will not be executed.

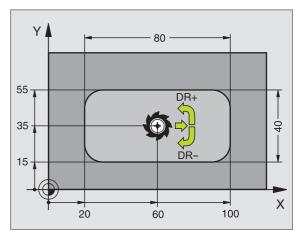
The following prerequisite applies for the 2nd side length: 2nd side length greater than  $[(2 \times \text{rounding radius}) + \text{stepover factor k}].$ 



- Set-up clearance 1 (incremental value): Distance between tool tip (at starting position) and workpiece surface
- ▶ **Depth 2** (incremental value): Distance between workpiece surface and bottom of pocket
- ▶ Plunging depth 3 (incremental value): Infeed per cut The TNC will go to depth in one movement if:
  - the plunging depth is equal to the depth
  - the plunging depth is greater than the depth
- ▶ Feed rate for plunging: Traversing speed of the tool during penetration
- ▶ First side length 4 (incremental value): Pocket length, parallel to the reference axis of the working plane
- ▶ 2nd side length 5: Pocket width
- ► Feed rate F: Traversing speed of the tool in the working plane
- ▶ Clockwise

DR +: Climb milling with M3
DR -: Up-cut milling with M3





#### **Example: NC blocks**

11 L Z+100 R0 FMAX

12	CYCL DEF 4.0 POCKET MILLING
13	CYCL DEF 4.1 SET UP 2
14	CYCL DEF 4.2 DEPTH -10
15	CYCL DEF 4.3 PLNGNG 4 F80
16	CYCL DEF 4.4 X80
17	CYCL DEF 4.5 Y40
18	CYCL DEF 4.6 F100 DR+ RADIUS 10
19	L X+60 Y+35 FMAX M3
20	I 7+2 FMAX M99

i

▶ Rounding off radius: Radius for the pocket corners. If Radius = 0 is entered, the pocket corners will be rounded with the radius of the cutter.

#### **Calculations:**

Stepover factor  $k = K \times R$ 

K: is the overlap factor, preset in machine parameter 7430, and

R is the cutter radius

# **POCKET FINISHING (Cycle 212)**

- 1 The TNC automatically moves the tool in the tool axis to set-up clearance, or if programmed to the 2nd set-up clearance, and subsequently to the center of the pocket.
- 2 From the pocket center, the tool moves in the working plane to the starting point for machining. The TNC takes the allowance and tool radius into account for calculating the starting point. If necessary, the TNC penetrates at the pocket center.
- If the tool is at the 2nd set-up clearance, it moves in rapid traverse FMAX to set-up clearance, and from there advances to the first plunging depth at the feed rate for plunging.
- **4** The tool then moves tangentially to the contour of the finished part and, using climb milling, machines one revolution.
- **5** The tool then departs the contour on a tangential path and returns to the starting point in the working plane.
- **6** This process (3 to 5) is repeated until the programmed depth is reached.
- At the end of the cycle, the TNC retracts the tool in rapid traverse to set-up clearance, or if programmed to the 2nd set-up clearance, and finally to the center of the pocket (end position = starting position).



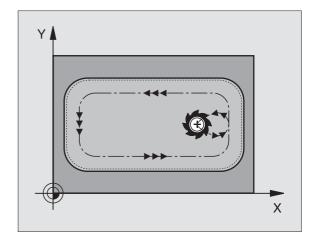
#### Before programming, note the following:

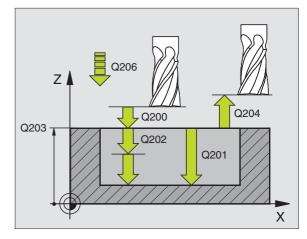
The TNC automatically pre-positions the tool in the tool axis and working plane.

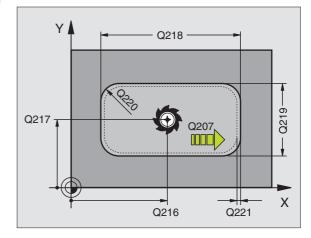
The algebraic sign for the cycle parameter DEPTH determines the working direction. If you program DEPTH = 0, the cycle will not be executed.

If you want to clear and finish the pocket with the same tool, use a center-cut end mill (ISO 1641) and enter a low feed rate for plunging.

Minimum size of the pocket: 3 times the tool radius.











- ▶ **Set-up clearance** Q200 (incremental value): Distance between tool tip and workpiece surface.
- ▶ **Depth** Q201 (incremental value): Distance between workpiece surface and bottom of pocket
- ▶ Feed rate for plunging Q206: Traversing speed of the tool in mm/min when moving to depth. If you are plunge-cutting into the material, enter a value lower than that defined in Q207
- ▶ Plunging depth Q202 (incremental value): Infeed per cut. Enter a value greater than 0.
- Feed rate for milling Ω207: Traversing speed of the tool in mm/min while milling.
- ▶ Workpiece surface coordinate Q203 (absolute value): Coordinate of the workpiece surface
- ▶ 2nd set-up clearance Q204 (incremental value): Coordinate in the tool axis at which no collision between tool and workpiece (clamping devices) can occur.
- ▶ Center in 1st axis O216 (absolute value): Center of the pocket in the reference axis of the working plane
- ▶ Center in 2nd axis Q217 (absolute value): Center of the pocket in the minor axis of the working plane
- ▶ First side length Q218 (incremental value): Pocket length, parallel to the reference axis of the working plane.
- ➤ Second side length Q219 (incremental value): Pocket length, parallel to the minor axis of the working plane
- ▶ Corner radius Q220: Radius of the pocket corner If you make no entry here, the TNC assumes that the corner radius is equal to the tool radius.
- ▶ Allowance in 1st axis O221 (incremental value): Allowance for pre-positioning in the reference axis of the working plane referenced to the length of the pocket.

34 CYCL DEF 212	POCKET FINISHING
Q200=2	;SET-UP CLEARANCE
Q201=-20	; DEPTH
Q206=150	;FEED RATE FOR PLUNGING
Q202=5	;PLUNGING DEPTH
Q207=500	;FEED RATE FOR MILLING
Q203=+30	;SURFACE COORDINATE
Q204=50	; 2ND SET-UP CLEARANCE
Q216=+50	; CENTER IN 1ST AXIS
Q217=+50	; CENTER IN 2ND AXIS
Q218=80	;FIRST SIDE LENGTH
Q219=60	;SECOND SIDE LENGTH
Q220=5	; CORNER RADIUS
Q221=0	; ALLOWANCE

# **STUD FINISHING (Cycle 213)**

- 1 The TNC moves the tool in the tool axis to set-up clearance, or if programmed to the 2nd set-up clearance, and subsequently to the center of the stud.
- **2** From the stud center, the tool moves in the working plane to the starting point for machining. The starting point lies to the right of the stud by a distance approx. 3.5 times the tool radius.
- **3** If the tool is at the 2nd set-up clearance, it moves in rapid traverse FMAX to set-up clearance, and from there advances to the first plunging depth at the feed rate for plunging.
- **4** The tool then moves tangentially to the contour of the finished part and, using climb milling, machines one revolution.
- 5 The tool then departs the contour on a tangential path and returns to the starting point in the working plane.
- This process (3 to 5) is repeated until the programmed depth is reached.
- At the end of the cycle, the TNC retracts the tool in FMAX to setup clearance, or — if programmed — to the 2nd set-up clearance, and finally to the center of the stud (end position = starting position).

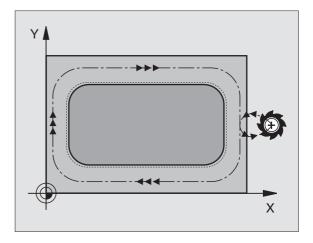


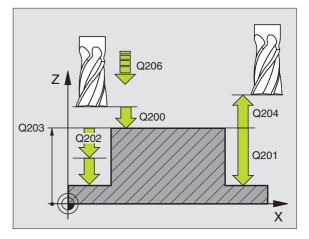
#### Before programming, note the following:

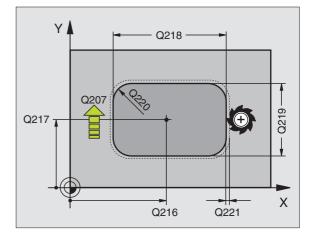
The TNC automatically pre-positions the tool in the tool axis and working plane.

The algebraic sign for the cycle parameter DEPTH determines the working direction. If you program DEPTH = 0, the cycle will not be executed.

If you want to clear and finish the stud with the same tool, use a center-cut end mill (ISO 1641) and enter a low feed rate for plunging.











- ▶ **Set-up clearance** Q200 (incremental value): Distance between tool tip and workpiece surface.
- ▶ Depth Q201 (incremental value): Distance between workpiece surface and bottom of stud
- ▶ Feed rate for plunging Q206: Traversing speed of the tool in mm/min when moving to depth. If you are plunge-cutting into the material, enter a low value; if you have already cleared the stud, enter a higher feed rate.
- ▶ Plunging depth Q202 (incremental value): Infeed per cut. Enter a value greater than 0.
- Feed rate for milling Ω207: Traversing speed of the tool in mm/min while milling.
- ▶ Workpiece surface coordinate Q203 (absolute value): Coordinate of the workpiece surface
- ▶ 2nd set-up clearance Q204 (incremental value): Coordinate in the tool axis at which no collision between tool and workpiece (clamping devices) can occur.
- ▶ Center in 1st axis Q216 (absolute value): Center of the stud in the reference axis of the working plane
- ▶ Center in 2nd axis O217 (absolute value): Center of the stud in the minor axis of the working plane.
- ▶ First side length Q218 (incremental value): Length of stud parallel to the reference axis of the working plane
- Second side length Q219 (incremental value): Length of stud parallel to the secondary axis of the working plane
- ▶ Corner radius Q220: Radius of the stud corner
- ▶ Allowance in 1st axis O221 (incremental value):
  Allowance for pre-positioning in the reference axis of
  the working plane referenced to the length of the stud

35 CYCL DEF 213	S STUD FINISHING
Q200=2	;SET-UP CLEARANCE
Q201=-20	;DEPTH
Q206=150	;FEED RATE FOR PLUNGING
Q202=5	;PLUNGING DEPTH
Q207=500	;FEED RATE FOR MILLING
Q203=+30	;SURFACE COORDINATE
Q204=50	;2ND SET-UP CLEARANCE
Q216=+50	;CENTER IN 1ST AXIS
Q217=+50	;CENTER IN 2ND AXIS
Q218=80	;FIRST SIDE LENGTH
Q219=60	;SECOND SIDE LENGTH
Q220=5	; CORNER RADIUS
Q221=0	; ALLOWANCE

# **CIRCULAR POCKET MILLING (Cycle 5)**

- 1 The tool penetrates the workpiece at the starting position (pocket center) and advances to the first plunging depth.
- The tool subsequently follows a spiral path at the feed rate F see figure at right. For calculating the stepover factor k, see Cycle 4 POCKET MILLING.see "POCKET MILLING (Cycle 4)," page 258
- 3 This process is repeated until the depth is reached.
- **4** At the end of the cycle, the TNC retracts the tool to the starting position.



#### Before programming, note the following:

This cycle requires a center-cut end mill (ISO 1641), or pilot drilling at the pocket center.

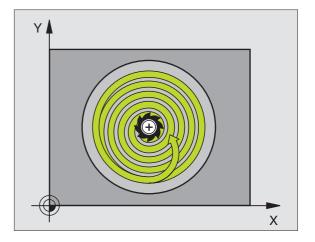
Pre-position over the pocket center with radius compensation R0.

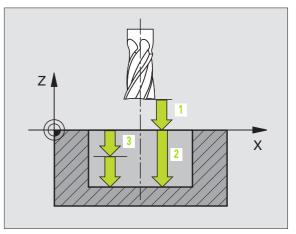
Program a positioning block for the starting point in the tool axis (set-up clearance above the workpiece surface).

The algebraic sign for the cycle parameter DEPTH determines the working direction. If you program DEPTH = 0, the cycle will not be executed.



- ➤ Set-up clearance 1 (incremental value): Distance between tool tip (at starting position) and workpiece surface
- Milling depth 2: Distance between workpiece surface and bottom of pocket
- ▶ Plunging depth 3 (incremental value): Infeed per cut The TNC will go to depth in one movement if:
  - the plunging depth is equal to the depth
  - the plunging depth is greater than the depth

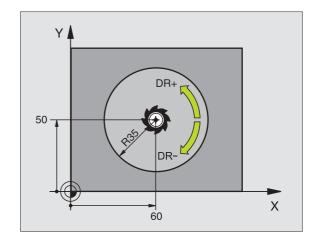






- ▶ Feed rate for plunging: Traversing speed of the tool during penetration
- ▶ Circular radius: Radius of the circular pocket
- ▶ Feed rate F: Traversing speed of the tool in the working plane
- ▶ Clockwise

DR +: Climb milling with M3 DR -: Up-cut milling with M3



### **Example: NC blocks**

16 L Z+100 RO FMAX
17 CYCL DEF 5.0 CIRCULAR POCKET
18 CYCL DEF 5.1 SET UP 2
19 CYCL DEF 5.2 DEPTH -12
20 CYCL DEF 5.3 PLNGNG 6 F80
21 CYCL DEF 5.4 RADIUS 35

22 CYCL DEF 5.5 F100 DR+ 23 L X+60 Y+50 FMAX M3

24 L Z+2 FMAX M99

# **CIRCULAR POCKET FINISHING (Cycle 214)**

- 1 The TNC automatically moves the tool in the tool axis to set-up clearance, or if programmed to the 2nd set-up clearance, and subsequently to the center of the pocket.
- 2 From the pocket center, the tool moves in the working plane to the starting point for machining. The TNC takes the workpiece blank diameter and tool radius into account for calculating the starting point. If you enter a workpiece blank diameter of 0, the TNC plunge-cuts into the pocket center.
- 3 If the tool is at the 2nd set-up clearance, it moves in rapid traverse FMAX to set-up clearance, and from there advances to the first plunging depth at the feed rate for plunging.
- 4 The tool then moves tangentially to the contour of the finished part and, using climb milling, machines one revolution.
- **5** After this, the tool departs the contour tangentially and returns to the starting point in the working plane.
- **6** This process (3 to 5) is repeated until the programmed depth is reached.
- At the end of the cycle, the TNC retracts the tool in rapid traverse to set-up clearance, or, if programmed, to the 2nd set-up clearance and then to the center of the pocket (end position = starting position)

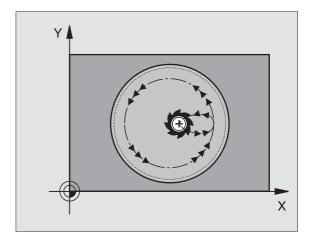


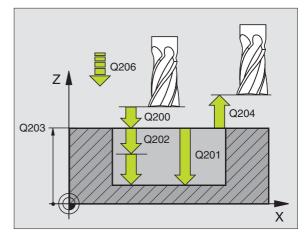
#### Before programming, note the following:

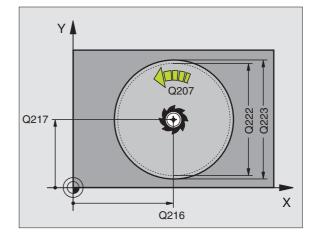
The TNC automatically pre-positions the tool in the tool axis and working plane.

The algebraic sign for the cycle parameter DEPTH determines the working direction. If you program DEPTH = 0, the cycle will not be executed.

If you want to clear and finish the pocket with the same tool, use a center-cut end mill (ISO 1641) and enter a low feed rate for plunging.









- ▶ Set-up clearance Q200 (incremental value): Distance between tool tip and workpiece surface.
- ▶ **Depth** Q201 (incremental value): Distance between workpiece surface and bottom of pocket
- ▶ Feed rate for plunging Q206: Traversing speed of the tool in mm/min when moving to depth. If you are plunge-cutting into the material, enter a value lower than that defined in Q207
- ▶ Plunging depth Q202 (incremental value): Infeed per
- ▶ Feed rate for milling Q207: Traversing speed of the tool in mm/min while milling.
- ▶ Workpiece surface coordinate Q203 (absolute value): Coordinate of the workpiece surface
- ▶ 2nd set-up clearance Q204 (incremental value): Coordinate in the tool axis at which no collision between tool and workpiece (clamping devices) can occur.
- ▶ Center in 1st axis Q216 (absolute value): Center of the pocket in the reference axis of the working plane
- ▶ Center in 2nd axis Q217 (absolute value): Center of the pocket in the minor axis of the working plane
- ▶ Workpiece blank diameter Q222: Diameter of the premachined pocket for calculating the pre-position. Enter the workpiece blank diameter to be less than the diameter of the finished part
- Finished part diameter Q223: Diameter of the finished pocket. Enter the diameter of the finished part to be greater than the workpiece blank diameter.

42 CYCL DEF 21	4 CIRCULAR POCKET FINISHING
Q200=2	;SET-UP CLEARANCE
Q201=-20	;DEPTH
Q206=150	;FEED RATE FOR PLUNGING
Q202=5	;PLUNGING DEPTH
Q207=500	;FEED RATE FOR MILLING
Q203=+30	;SURFACE COORDINATE
Q204=50	;2ND SET-UP CLEARANCE
Q216=+50	; CENTER IN 1ST AXIS
Q217=+50	; CENTER IN 2ND AXIS
Q222=79	;WORKPIECE BLANK DIA.
Q223=80	;FINISHED PART DIA.

# **CIRCULAR STUD FINISHING (Cycle 215)**

- 1 The TNC automatically moves the tool in the tool axis to set-up clearance, or if programmed to the 2nd set-up clearance, and subsequently to the center of the stud.
- **2** From the stud center, the tool moves in the working plane to the starting point for machining. The starting point lies to the right of the stud by a distance approx. 3.5 times the tool radius.
- **3** If the tool is at the 2nd set-up clearance, it moves in rapid traverse FMAX to set-up clearance, and from there advances to the first plunging depth at the feed rate for plunging.
- **4** The tool then moves tangentially to the contour of the finished part and, using climb milling, machines one revolution.
- 5 The tool then departs the contour on a tangential path and returns to the starting point in the working plane.
- This process (3 to 5) is repeated until the programmed depth is reached.
- 7 At the end of the cycle, the TNC retracts the tool in FMAX to setup clearance, or — if programmed — to the 2nd set-up clearance, and finally to the center of the pocket (end position = starting position).

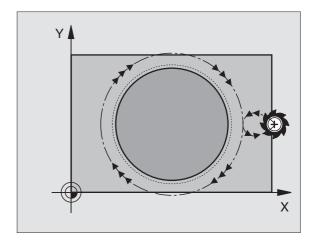


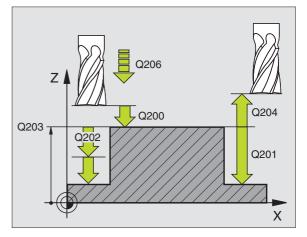
#### Before programming, note the following:

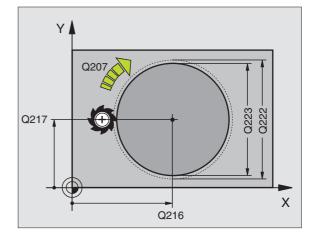
The TNC automatically pre-positions the tool in the tool axis and working plane.

The algebraic sign for the cycle parameter DEPTH determines the working direction. If you program DEPTH = 0, the cycle will not be executed.

If you want to clear and finish the stud with the same tool, use a center-cut end mill (ISO 1641) and enter a low feed rate for plunging.











- ▶ **Set-up clearance** Q200 (incremental value): Distance between tool tip and workpiece surface.
- ▶ **Depth** Q201 (incremental value): Distance between workpiece surface and bottom of stud
- ▶ Feed rate for plunging Q206: Traversing speed of the tool in mm/min when moving to depth. If you are plunge-cutting into the material, enter a low value; if you have already cleared the stud, enter a higher feed rate.
- ▶ Plunging depth Q202 (incremental value): Infeed per cut. Enter a value greater than 0.
- ▶ Feed rate for milling Q207: Traversing speed of the tool in mm/min while milling.
- ▶ Workpiece surface coordinate Q203 (absolute value): Coordinate of the workpiece surface
- ▶ 2nd set-up clearance Q204 (incremental value): Coordinate in the tool axis at which no collision between tool and workpiece (clamping devices) can occur.
- ▶ Center in 1st axis Q216 (absolute value): Center of the stud in the reference axis of the working plane
- ▶ Center in 2nd axis Q217 (absolute value): Center of the stud in the minor axis of the working plane.
- ▶ Workpiece blank diameter Q222: Diameter of the premachined stud for calculating the pre-position. Enter the workpiece blank diameter to be greater than the diameter of the finished part
- ▶ Diameter of finished part Q223: Diameter of the finished stud. Enter the diameter of the finished part to be less than the workpiece blank diameter.

43 CYCL DEF 215	C. STUD FINISHING
Q200=2 ;	SET-UP CLEARANCE
Q201=-20 ;	DEPTH
Q206=150 ;	FEED RATE FOR PLUNGING
Q202=5 ;	PLUNGING DEPTH
Q207=500 ;	FEED RATE FOR MILLING
Q203=+30 ;	SURFACE COORDINATE
Q204=50 ;	2ND SET-UP CLEARANCE
Q216=+50 ;	CENTER IN 1ST AXIS
Q217=+50 ;	CENTER IN 2ND AXIS
Q222=81 ;	WORKPIECE BLANK DIA.
Q223=80 ;	FINISHED PART DIA.

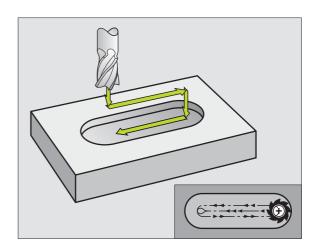
# **SLOT MILLING (Cycle 3)**

#### Roughing process

- 1 The TNC moves the tool inward by the milling allowance (half the difference between the slot width and the tool diameter). From there it plunge-cuts into the workpiece and mills in the longitudinal direction of the slot.
- **2** After downfeed at the end of the slot, milling is performed in the opposite direction. This process is repeated until the programmed milling depth is reached.

#### Finishing process

- **3** The TNC advances the tool at the slot bottom on a tangential arc to the outside contour. The tool subsequently climb mills the contour (with M3).
- **4** At the end of the cycle, the tool is retracted in rapid traverse FMAX to set-up clearance. If the number of infeeds was odd, the tool returns to the starting position at the level of the set-up clearance.





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#### Before programming, note the following:

This cycle requires a center-cut end mill (ISO 1641), or pilot drilling at the starting point.

Pre-position to the center of the slot and offset by the tool radius into the slot with radius compensation R0.

The cutter diameter must be not be larger than the slot width and not smaller than half the slot width.

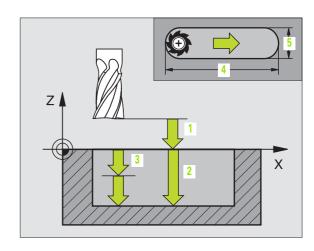
Program a positioning block for the starting point in the tool axis (set-up clearance above the workpiece surface).

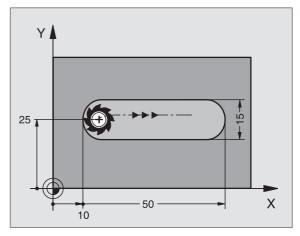
The algebraic sign for the cycle parameter DEPTH determines the working direction. If you program DEPTH = 0, the cycle will not be executed.





- ▶ Set-up clearance 1 (incremental value): Distance between tool tip (at starting position) and workpiece surface
- ▶ Milling depth 2 (incremental value): Distance between workpiece surface and bottom of pocket
- ▶ Plunging depth 3 (incremental value): Infeed per cut. The tool will drill to the depth in one operation if:
  - the plunging depth is equal to the depth
  - the plunging depth is greater than the depth
- ▶ Feed rate for plunging: Traversing speed during penetration
- ▶ 1st side length 4: Slot length; specify the sign to determine the first milling direction
- ▶ 2nd side length 5: Slot width
- ▶ Feed rate F: Traversing speed of the tool in the working plane





9 L Z+100 RO FMAX		
10 TOOL DEF 1 L+0 R+6		
11 TOOL CALL 1 Z S1500		
12 CYCL DEF 3.0 SLOT MILLING		
13 CYCL DEF 3.1 SET UP 2		
14 CYCL DEF 3.2 DEPTH -15		
15 CYCL DEF 3.3 PLNGNG 5 F80		
16 CYCL DEF 3.4 X50		
17 CYCL DEF 3.5 Y15		
18 CYCL DEF 3.6 F120		
19 L X+16 Y+25 RO FMAX M3		
20 L Z+2 M99		

# SLOT (oblong hole) with reciprocating plungecut (Cycle 210)



#### Before programming, note the following:

The TNC automatically pre-positions the tool in the tool axis and working plane.

During roughing the tool plunges into the material with a sideward reciprocating motion from one end of the slot to the other. Pilot drilling is therefore unnecessary.

The algebraic sign for the cycle parameter DEPTH determines the working direction. If you program DEPTH = 0, the cycle will not be executed.

The cutter diameter must not be larger than the slot width and not smaller than a third of the slot width.

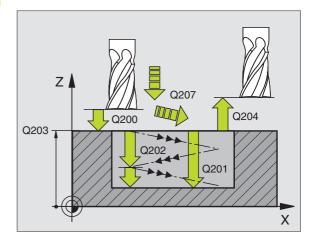
The cutter diameter must be smaller than half the slot length. The TNC otherwise cannot execute this cycle.

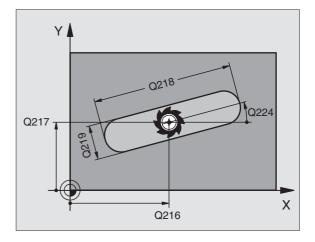
#### **Roughing process**

- 1 At rapid traverse, the TNC positions the tool in the tool axis to the 2nd set-up clearance and subsequently to the center of the left circle. From there, the TNC positions the tool to set-up clearance above the workpiece surface.
- 2 The tool moves at the feed rate for milling to the workpiece surface. From there, the cutter advances in the longitudinal direction of the slot — plunge-cutting obliquely into the material until it reaches the center of the right circle.
- 3 The tool then moves back to the center of the left circle, again with oblique plunge-cutting. This process is repeated until the programmed milling depth is reached.
- 4 At the milling depth, the TNC moves the tool for the purpose of face milling to the other end of the slot and then back to the center of the slot.

#### **Finishing process**

- **5** The TNC advances the tool from the slot center tangentially to the contour of the finished part. The tool subsequently climb mills the contour (with M3), and if so entered, in more than one infeed.
- **6** When the tool reaches the end of the contour, it departs the contour tangentially and returns to the center of the slot.
- 7 At the end of the cycle, the tool is retracted in rapid traverse FMAX to set-up clearance and if programmed to the 2nd set-up clearance.







- ▶ **Set-up clearance** Q200 (incremental value): Distance between tool tip and workpiece surface.
- ▶ **Depth** Q201 (incremental value): Distance between workpiece surface and bottom of slot
- ▶ Feed rate for milling Q207: Traversing speed of the tool in mm/min while milling.
- ▶ Plunging depth Q202 (incremental value): Total extent by which the tool is fed in the tool axis during a reciprocating movement
- ▶ Machining operation (0/1/2) Q215: Define the machining operation:
  - 0: Roughing and finishing
  - 1: Only roughing
  - 2: Only finishing
- ▶ Workpiece surface coordinate Q203 (absolute value): Coordinate of the workpiece surface
- ▶ 2nd setup clearance Q204 (incremental value): Z coordinate at which no collision between tool and workpiece (clamping devices) can occur
- ▶ Center in 1st axis Q216 (absolute value): Center of the slot in the reference axis of the working plane
- ▶ Center in 2nd axis Q217 (absolute value): Center of the slot in the minor axis of the working plane
- ▶ First side length Q218 (value parallel to the reference axis of the working plane): Enter the length of the slot
- ▶ Second side length Q219 (value parallel to the secondary axis of the working plane): Enter the slot width. If you enter a slot width that equals the tool diameter, the TNC will carry out the roughing process only (slot milling).
- ▶ Angle of rotation Q224 (absolute value): Angle by which the entire slot is rotated. The center of rotation lies in the center of the slot.
- ▶ Infeed for finishing Q338 (incremental value): Infeed per cut. Q338=0: Finishing in one infeed.

51 CYCL DEF 21	O SLOT RECIP. PLNG
Q200=2	;SET-UP CLEARANCE
Q201=-20	;DEPTH
Q207=500	;FEED RATE FOR MILLING
Q202=5	;PLUNGING DEPTH
Q215=0	;MACHINING OPERATION
Q203=+30	;SURFACE COORDINATE
Q204=50	;2ND SET-UP CLEARANCE
Q216=+50	; CENTER IN 1ST AXIS
Q217=+50	;CENTER IN 2ND AXIS
Q218=80	;FIRST SIDE LENGTH
Q219=12	;SECOND SIDE LENGTH
Q224=+15	;ANGLE OF ROTATION
Q338=5	;INFEED FOR FINISHING

# CIRCULAR SLOT (oblong hole) with reciprocating plunge-cut (Cycle 211)

#### **Roughing process**

- 1 At rapid traverse, the TNC positions the tool in the tool axis to the 2nd set-up clearance and subsequently to the center of the right circle. From there, the tool is positioned to the programmed set-up clearance above the workpiece surface.
- 2 The tool moves at the milling feed rate to the workpiece surface. From there, the cutter advances plunge-cutting obliquely into the material to the other end of the slot.
- **3** The tool then moves at a downward angle back to the starting point, again with oblique plunge-cutting. This process (2 to 3) is repeated until the programmed milling depth is reached.
- 4 At the milling depth, the TNC moves the tool for the purpose of face milling to the other end of the slot.

#### **Finishing process**

- The TNC advances the tool from the slot center tangentially to the contour of the finished part. The tool subsequently climb mills the contour (with M3), and if so entered, in more than one infeed. The starting point for the finishing process is the center of the right circle.
- **6** When the tool reaches the end of the contour, it departs the contour tangentially.
- 7 At the end of the cycle, the tool is retracted in rapid traverse FMAX to set-up clearance and if programmed to the 2nd set-up clearance.



#### Before programming, note the following:

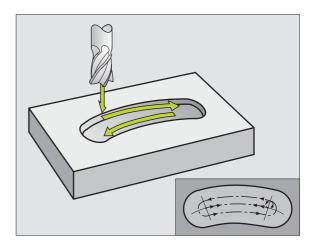
The TNC automatically pre-positions the tool in the tool axis and working plane.

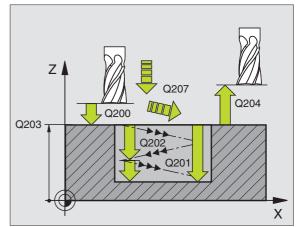
During roughing the tool plunges into the material with a helical sideward reciprocating motion from one end of the slot to the other. Pilot drilling is therefore unnecessary.

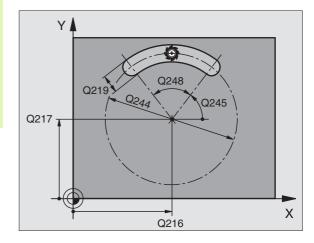
The algebraic sign for the cycle parameter DEPTH determines the working direction. If you program DEPTH = 0, the cycle will not be executed.

The cutter diameter must not be larger than the slot width and not smaller than a third of the slot width.

The cutter diameter must be smaller than half the slot length. The TNC otherwise cannot execute this cycle.





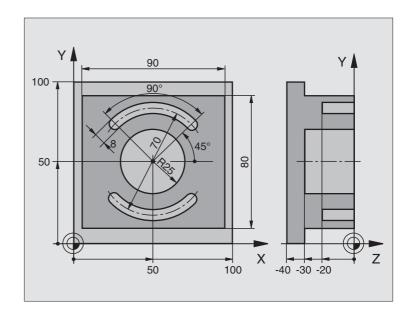




- ▶ **Set-up clearance** Q200 (incremental value): Distance between tool tip and workpiece surface.
- ▶ **Depth** Q201 (incremental value): Distance between workpiece surface and bottom of slot
- Feed rate for milling Q207: Traversing speed of the tool in mm/min while milling.
- ▶ Plunging depth Q202 (incremental value): Total extent by which the tool is fed in the tool axis during a reciprocating movement
- ▶ Machining operation (0/1/2) Q215: Define the machining operation:
  - 0: Roughing and finishing
  - 1: Only roughing
  - 2: Only finishing
- ▶ Workpiece surface coordinate Q203 (absolute value): Coordinate of the workpiece surface
- ▶ 2nd setup clearance Q204 (incremental value): Z coordinate at which no collision between tool and workpiece (clamping devices) can occur
- ▶ Center in 1st axis Q216 (absolute value): Center of the slot in the reference axis of the working plane
- ▶ Center in 2nd axis Q217 (absolute value): Center of the slot in the minor axis of the working plane
- ▶ Pitch circle diameter Q244: Enter the diameter of the pitch circle
- Second side length Q219: Enter the slot width. If you enter a slot width that equals the tool diameter, the TNC will carry out the roughing process only (slot milling).
- ▶ Starting angle Q245 (absolute value): Enter the polar angle of the starting point
- ► Angular length Q248 (incremental value): Enter the angular length of the slot
- ▶ Infeed for finishing Q338 (incremental value): Infeed per cut. Q338=0: Finishing in one infeed.

52 CYCL DEF 211 CIRCULAR SLOT
Q200=2 ;SET-UP CLEARANCE
Q201=-20 ;DEPTH
Q207=500 ;FEED RATE FOR MILLING
Q202=5 ; PLUNGING DEPTH
Q215=O ;MACHINING OPERATION
Q203=+30 ;SURFACE COORDINATE
Q204=50 ;2ND SET-UP CLEARANCE
Q216=+50 ;CENTER IN 1ST AXIS
Q217=+50 ;CENTER IN 2ND AXIS
Q244=80 ;PITCH CIRCLE DIAMETR
Q219=12 ;SECOND SIDE LENGTH
Q245=+45 ;STARTING ANGLE
Q248=90 ;ANGULAR LENGTH
Q338=5 ;INFEED FOR FINISHING

# **Example: Milling pockets, studs and slots**



O BEGIN PGM C210 MM	
1 BLK FORM 0.1 Z X+0 Y+0 Z-40	Define the workpiece blank
2 BLK FORM 0.2 X+100 Y+100 Z+0	
3 TOOL DEF 1 L+0 R+6	Define the tool for roughing/finishing
4 TOOL DEF 2 L+0 R+3	Define slotting mill
5 TOOL CALL 1 Z S3500	Call the tool for roughing/finishing
6 L Z+250 RO F MAX	Retract the tool
7 CYCL DEF 213 STUD FINISHING	Define cycle for machining the contour outside
Q200=2 ;SET-UP CLEARANCE	
Q201=-30 ;DEPTH	
Q206=250 ; FEED RATE FOR PLNGNG	
Q202=5 ; PLUNGING DEPTH	
Q207=250 ; FEED RATE FOR MILLING	
Q203=+0 ;SURFACE COORDINATE	
Q204=20 ;2ND SET-UP CLEARANCE	
Q216=+50 ; CENTER IN 1ST AXIS	
Q217=+50 ; CENTER IN 2ND AXIS	
Q218=90 ;FIRST SIDE LENGTH	
Q219=80 ;SECOND SIDE LENGTH	

Q220=O ; CORNER RADIUS	
Q221=5 ;ALLOWANCE	
8 CYCL CALL M3	Call cycle for machining the contour outside
9 CYCL DEF 5.0 CIRCULAR POCKET	Define CIRCULAR POCKET MILLING cycle
10 CYCL DEF 5.1 SET UP 2	
11 CYCL DEF 5.2 DEPTH -30	
12 CYCL DEF 5.3 PLNGNG 5 F250	
13 CYCL DEF 5.4 RADIUS 25	
14 CYCL DEF 5.5 F400 DR+	
15 L Z+2 RO F MAX M99	Call CIRCULAR POCKET MILLING cycle
16 L Z+250 RO F MAX M6	Tool change
17 TOOL CALL 2 Z S5000	Call slotting mill
18 CYCL DEF 211 CIRCULAR SLOT	Cycle definition for slot 1
Q200=2 ;SET-UP CLEARANCE	
Q201=-20 ;DEPTH	
Q207=250 ;FEED RATE FOR MILLNG	
Q202=5 ;PLUNGING DEPTH	
Q215=O ;MACHINING OPERATION	
Q203=+0 ;SURFACE COORDINATE	
Q204=100 ;2ND SET-UP CLEARANCE	
Q216=+50 ;CENTER IN 1ST AXIS	
Q217=+50 ;CENTER IN 2ND AXIS	
Q244=70 ;PITCH CIRCLE DIA.	
Q219=8 ;SECOND SIDE LENGTH	
Q245=+45 ;STARTING ANGLE	
Q248=90 ;ANGULAR LENGTH	
Q338=5 ;INFEED FOR FINISHING	
19 CYCL CALL M3	Call cycle for slot 1
20 FN 0: Q245 = +225	New starting angle for slot 2
21 CYCL CALL	Call cycle for slot 2
22 L Z+250 RO F MAX M2	Retract in the tool axis, end program
23 END PGM C210 MM	

HEIDENHAIN TNC 426, TNC 430

# 8.5 Cycles for Machining Hole **Patterns**

### **Overview**

The TNC provides two cycles for machining hole patterns directly:

Cycle	Soft key
220 CIRCULAR PATTERN	220
221 LINEAR PATTERN	221 \( \phi \ \phi \phi

You can combine Cycle 220 and Cycle 221 with the following fixed cycles:



If you have to machine irregular hole patterns, use CYCL CALL PAT (see "Point Tables" on page 206) to develop point tables.

- Cycle 1 **PECKING** Cycle 2 TAPPING with a floating tap holder Cycle 3 SLOT MILLING Cycle 4 **POCKET MILLING** Cycle 5 CIRCULAR POCKET MILLING Cycle 17 RIGID TAPPING without a floating tap holder Cycle 18 THREAD CUTTING Cycle 200 DRILLING
- Cycle 201 REAMING Cycle 202 BORING
- Cycle 203 UNIVERSAL DRILLING
- Cycle 204 BACK BORING
- Cycle 205 UNIVERSAL PECKING
- Cycle 206 TAPPING NEW with a floating tap holder
- Cycle 207 RIGID TAPPING NEW without a floating tap holder
- Cycle 208 BORE MILLING
- Cycle 209 TAPPING WITH CHIP BREAKING
- Cycle 212 POCKET FINISHING Cycle 213 STUD FINISHING
- Cycle 214 CIRCULAR POCKET FINISHING Cycle 215 CIRCULAR STUD FINISHING
- Cycle 262 THREAD MILLING
- Cycle 263 THREAD MILLING/COUNTERSINKING
- Cycle 264 THREAD DRILLING/MILLING
- Cycle 265 HELICAL THREAD DRILLING/MILLING
- Cycle 267 OUTSIDE THREAD MILLING

### **CIRCULAR PATTERN (Cycle 220)**

1 At rapid traverse, the TNC moves the tool from its current position to the starting point for the first machining operation.

#### Sequence:

- Move to 2nd set-up clearance (spindle axis)
- Approach the starting point in the spindle axis
- Move to set-up clearance above the workpiece surface (spindle axis)
- **2** From this position, the TNC executes the last defined fixed cycle.
- **3** The tool then approaches the starting point for the next machining operation on a straight line at set-up clearance (or 2nd set-up clearance).
- **4** This process (1 to 3) is repeated until all machining operations have been executed.



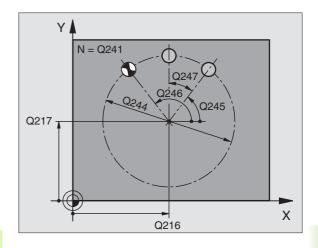
#### Before programming, note the following:

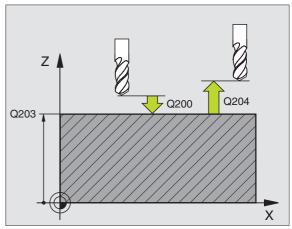
Cycle 220 is DEF active, which means that Cycle 220 automatically calls the last defined fixed cycle.

If you combine Cycle 220 with one of the fixed cycles 200 to 208, 212 to 215, 262 to 265 or 267, the set-up clearance, workpiece surface and 2nd set-up clearance that you defined in Cycle 220 will be effective for the selected fixed cycle.



- ▶ Center in 1st axis Q216 (absolute value): Center of the pitch circle in the reference axis of the working plane
- ▶ Center in 2nd axis Q217 (absolute value): Center of the pitch circle in the minor axis of the working plane
- ▶ Pitch circle diameter Q244: Diameter of the pitch circle
- ▶ Starting angle Q245 (absolute value): Angle between the reference axis of the working plane and the starting point for the first machining operation on the pitch circle
- ▶ Stopping angle Q246 (absolute value): Angle between the reference axis of the working plane and the starting point for the last machining operation on the pitch circle (does not apply to complete circles). Do not enter the same value for the stopping angle and starting angle. If you enter the stopping angle greater than the starting angle, machining will be carried out counterclockwise; otherwise, machining will be clockwise.





#### **Example: NC blocks**

53	CYCL DEF 220 POLAR PATTERN
	Q216=+50 ;CENTER IN 1ST AXIS
	Q217=+50 ;CENTER IN 2ND AXIS
	Q244=80 ;PITCH CIRCLE DIAMETR
	Q245=+0 ;STARTING ANGLE
	Q246=+360 ;STOPPING ANGLE
	Q247=+0 ;STEPPING ANGLE
	Q241=8 ;NR OF REPETITIONS
	Q200=2 ;SET-UP CLEARANCE
	Q203=+30 ;SURFACE COORDINATE
	Q204=50 ;2ND SET-UP CLEARANCE
	Q301=1 ;TRAVERSE TO CLEARANCE HEIGHT

- ▶ Stepping angle Q247 (incremental value): Angle between two machining operations on a pitch circle. If you enter an angle step of 0, the TNC will calculate the angle step from the starting and stopping angles and the number of pattern repetitions. If you enter a value other than 0, the TNC will not take the stopping angle into account. The sign for the angle step determines the working direction (– = clockwise).
- Number of repetitions Q241: Number of machining operations on a pitch circle
- ▶ Set-up clearance Q200 (incremental value): Distance between tool tip and workpiece surface. Enter a positive value.
- ▶ Workpiece surface coordinate Q203 (absolute value): Coordinate of the workpiece surface
- ▶ 2nd set-up clearance Q204 (incremental value): Coordinate in the tool axis at which no collision between tool and workpiece (clamping devices) can occur.
- ▶ Traversing to clearance height Q301: Definition of how the tool is to move between machining processes:
  - **0**: Move between operations to the set-up clearance
  - 1: Move between operations to 2nd set-up clearance.

1

# **LINEAR PATTERN (Cycle 221)**



#### Before programming, note the following:

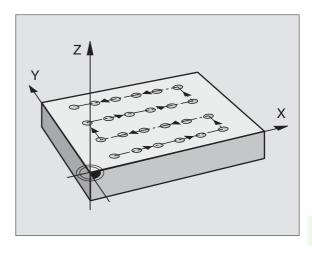
Cycle 221 is DEF active, which means that Cycle 221 calls the last defined fixed cycle automatically.

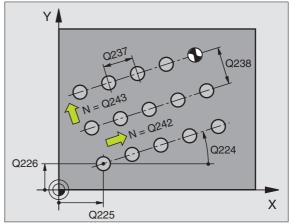
If you combine Cycle 221 with one of the fixed cycles 200 to 208, 212 to 215, 262 to 265 or 267, the set-up clearance, workpiece surface and 2nd set-up clearance that you defined in Cycle 221 will be effective for the selected fixed cycle.

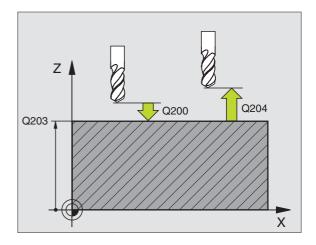
1 The TNC automatically moves the tool from its current position to the starting point for the first machining operation.

#### Sequence:

- 2. Move to 2nd set-up clearance (spindle axis)
- Approach the starting point in the spindle axis
- Move to set-up clearance above the workpiece surface (spindle axis)
- **2** From this position, the TNC executes the last defined fixed cycle.
- **3** The tool then approaches the starting point for the next machining operation in the positive reference axis direction at set-up clearance (or 2nd set-up clearance).
- **4** This process (1 to 3) is repeated until all machining operations on the first line have been executed. The tool is located above the last point on the first line.
- **5** The tool subsequently moves to the last point on the second line where it carries out the machining operation.
- **6** From this position, the tool approaches the starting point for the next machining operation in the negative reference axis direction.
- 7 This process (6) is repeated until all machining operations in the second line have been executed.
- 8 The tool then moves to the starting point of the next line.
- **9** All subsequent lines are processed in a reciprocating movement.









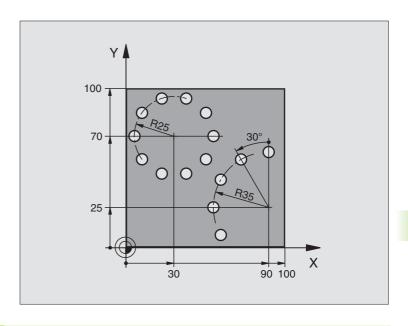


- Starting point 1st axis Q225 (absolute value): Coordinate of the starting point in the reference axis of the working plane
- Starting point 2nd axis Q226 (absolute value): Coordinate of the starting point in the minor axis of the working plane
- Spacing in 1st axis Q237 (incremental value): Spacing between the individual points on a line
- ➤ Spacing in 2nd axis Q238 (incremental value): Spacing between the individual lines
- Number of columns Q242: Number of machining operations on a line
- ▶ Number of lines Q243: Number of passes
- Angle of rotation Q224 (absolute value): Angle by which the entire pattern is rotated. The center of rotation lies in the starting point.
- ▶ Set-up clearance Q200 (incremental value): Distance between tool tip and workpiece surface
- ▶ Workpiece surface coordinate Q203 (absolute value): Coordinate of the workpiece surface
- ▶ 2nd set-up clearance Q204 (incremental value): Coordinate in the tool axis at which no collision between tool and workpiece (clamping devices) can occur.
- ▶ Traversing to clearance height Q301: Definition of how the tool is to move between machining processes:
  - **0:** Move to set-up clearance
  - **1:** Move to 2nd set-up clearance between the measuring points.

54	CYCL DEF 22	1 CARTESIAN PATTRN
	Q225=+15	;STARTNG PNT 1ST AXIS
	Q226=+15	;STARTNG PNT 2ND AXIS
	Q237=+10	;SPACING IN 1ST AXIS
	Q238=+8	;SPACING IN 2ND AXIS
	Q242=6	;NUMBER OF COLUMNS
	Q243=4	;NUMBER OF LINES
	Q224=+15	;ANGLE OF ROTATION
	Q200=2	;SET-UP CLEARANCE
	Q203=+30	;SURFACE COORDINATE
	Q204=50	;2ND SET-UP CLEARANCE
	Q301=1 ;	TRAVERSE TO CLEARANCE HEIGHT

8 Programming: Cycles

# **Example: Circular hole patterns**



O BEGIN PGM HOLEPAT MM	
1 BLK FORM 0.1 Z X+0 Y+0 Z-40	Define the workpiece blank
2 BLK FORM 0.2 X+100 Y+100 Z+0	
3 TOOL DEF 1 L+0 R+3	Define the tool
4 T00L CALL 1 Z S3500	Tool call
5 L Z+250 RO F MAX M3	Retract the tool
6 CYCL DEF 200 DRILLING	Cycle definition: drilling
Q200=2 ;SET-UP CLEARANCE	
Q201=-15 ;DEPTH	
Q206=250 ;FEED RATE FOR PLNGNG	
Q202=4 ;PLUNGING DEPTH	
Q210=O ;DWELL TIME AT TOP	
Q203=+0 ;SURFACE COORDINATE	
Q204=0 ;2ND SET-UP CLEARANCE	
Q211=0.25 ;DWELL TIME AT BOTTOM	

7 CYCL DEF 220 POLAR PATTERN	Define cycle for circular pattern 1, CYCL 200 is called automatically,
Q216=+30 ;CENTER IN 1ST AXIS	Q200, Q203 and Q204 are effective as defined in Cycle 220.
Q217=+70 ;CENTER IN 2ND AXIS	
Q244=50 ; PITCH CIRCLE DIA.	
Q245=+0 ;STARTING ANGLE	
Q246=+360 ;STOPPING ANGLE	
Q247=+0 ;STEPPING ANGLE	
Q241=10 ;NR OF REPETITIONS	
Q200=2 ;SET-UP CLEARANCE	
Q203=+0 ;SURFACE COORDINATE	
Q204=100 ;2ND SET-UP CLEARANCE	
Q301=1 ;TRAVERSE TO CLEARANCE HEIGHT	
8 CYCL DEF 220 POLAR PATTERN	Define cycle for circular pattern 2, CYCL 200 is called automatically,
Q216=+90 ;CENTER IN 1ST AXIS	Q200, Q203 and Q204 are effective as defined in Cycle 220.
Q217=+25 ; CENTER IN 2ND AXIS	
Q244=70 ;PITCH CIRCLE DIA.	
Q245=+90 ;STARTING ANGLE	
Q246=+360 ;STOPPING ANGLE	
Q247=+30 ;STEPPING ANGLE	
Q241=5 ;NR OF REPETITIONS	
Q200=2 ;SET-UP CLEARANCE	
Q203=+0 ;SURFACE COORDINATE	
Q204=100 ;2ND SET-UP CLEARANCE	
Q301=1 ;TRAVERSE TO CLEARANCE HEIGHT	
9 L Z+250 R0 F MAX M2	Retract in the tool axis, end program
10 END PGM HOLEPAT MM	

8 Programming: Cycles

# 8.6 SL cycles

#### **Fundamentals**

SL cycles enable you to form complex contours by combining up to 12 subcontours (pockets or islands). You define the individual subcontours in subprograms. The TNC calculates the total contour from the subcontours (subprogram numbers) that enter in Cycle 14 CONTOUR GEOMETRY.



The memory capacity for programming an SL cycle (all contour subprograms) is limited to 48 kilobytes. The number of possible contour elements depends on the type of contour (inside or outside contour) and the number of subcontours. For example, you can program up to approx. 256 line blocks.

#### Characteristics of the subprograms

- Coordinate transformations are allowed. If they are programmed within the subcontour they are also effective in the following subprograms, but they need not be reset after the cycle call.
- The TNC ignores feed rates F and miscellaneous functions M.
- The TNC recognizes a pocket if the tool path lies inside the contour, for example if you machine the contour clockwise with radius compensation RR.
- The TNC recognizes an island if the tool path lies outside the contour, for example if you machine the contour clockwise with radius compensation RL.
- The subprograms must not contain tool axis coordinates.
- The working plane is defined in the first coordinate block of the subprogram. The secondary axes U,V,W are permitted.

#### Characteristics of the fixed cycles

- The TNC automatically positions the tool to set-up clearance before a cycle.
- Each level of infeed depth is milled without interruptions since the cutter traverses around islands instead of over them.
- The radius of "inside corners" can be programmed—the tool keeps moving to prevent surface blemishes at inside corners (this applies for the outermost pass in the Rough-out and Side-Finishing cycles).
- The contour is approached in a tangential arc for side finishing.
- For floor finishing, the tool again approaches the workpiece in a tangential arc (for tool axis Z, for example, the arc may be in the Z/X plane).
- The contour is machined throughout in either climb or up-cut milling.



With MP7420 you can determine where the tool is positioned at the end of Cycles 21 to 24.

The machining data (such as milling depth, finishing allowance and setup clearance) are entered as CONTOUR DATA in Cycle 20.

# Example: Program structure: Machining with SL cycles

O BEGIN PGM SL2 MM
•••
12 CYCL DEF 14.0 CONTOUR GEOMETRY
13 CYCL DEF 20.0 CONTOUR DATA
•••
16 CYCL DEF 21.0 PILOT DRILLING
17 CYCL CALL
•••
18 CYCL DEF 22.0 ROUGH-OUT
19 CYCL CALL
•••
22 CYCL DEF 23.0 FLOOR FINISHING
23 CYCL CALL
•••
26 CYCL DEF 24.0 SIDE FINISHING
27 CYCL CALL
•••
50 L Z+250 RO FMAX M2
51 LBL 1
•••
55 LBL 0
56 LBL 2
•••
60 LBL 0
•••
99 END PGM SL2 MM

# **Overview of SL cycles**

Сусіе	Soft key
14 CONTOUR GEOMETRY (essential)	14 LBL 1N
20 CONTOUR DATA (essential)	20 CONTOUR DATA
21 PILOT DRILLING (optional)	21 🛛
22 ROUGH-OUT (essential)	22
23 FLOOR FINISHING (optional)	23
24 SIDE FINISHING (optional)	24

# **Enhanced cycles:**

Cycle	Soft key
25 CONTOUR TRAIN	25
27 CYLINDER SURFACE	27
28 CYLINDER SURFACE slot milling	28

# **CONTOUR GEOMETRY (Cycle 14)**

All subprograms that are superimposed to define the contour are listed in Cycle 14 CONTOUR GEOMETRY.



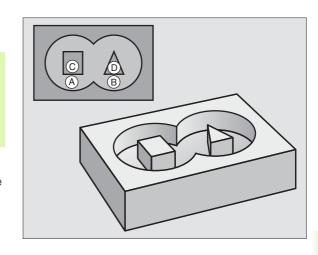
#### Before programming, note the following:

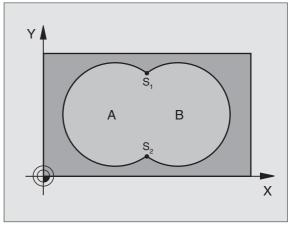
Cycle 14 is DEF active which means that it becomes effective as soon as it is defined in the part program.

You can list up to 12 subprograms (subcontours) in Cycle 14.



Label numbers for the contour: Enter all label numbers for the individual subprograms that are to be superimposed to define the contour. Confirm every label number with the ENT key. When you have entered all numbers, conclude entry with the END key.





**Example: NC blocks** 

12 CYCL DEF 14.0 CONTOUR GEOMETRY

13 CYCL DEF 14.1 CONTOUR LABEL 1 /2 /3 /4

# **Overlapping contours**

Pockets and islands can be overlapped to form a new contour. You can thus enlarge the area of a pocket by another pocket or reduce it by an island

#### **Subprograms: Overlapping pockets**



The subsequent programming examples are contour subprograms that are called by Cycle 14 CONTOUR GEOMETRY in a main program.

Pockets A and B overlap.

The TNC calculates the points of intersection S1 and S2 (they do not have to be programmed).

The pockets are programmed as full circles.

Subprogram 1: Pocket A

	51	LBL	1
--	----	-----	---

52 L X+10 Y+50 RR

53 CC X+35 Y+50

54 C X+10 Y+50 DR-

55 LBL 0

Subprogram 2: Pocket B

#### 56 LBL 2

57 L X+90 Y+50 RR

58 CC X+65 Y+50

59 C X+90 Y+50 DR-

60 LBL 0

#### Area of inclusion

Both surfaces A and B are to be machined, including the mutually overlapped area:

- The surfaces A and B must be pockets.
- The first pocket (in Cycle 14) must start outside the second pocket. Surface A:

#### 51 LBL 1

52 L X+10 Y+50 RR

53 CC X+35 Y+50

54 C X+10 Y+50 DR-

55 LBL 0

#### Surface B:

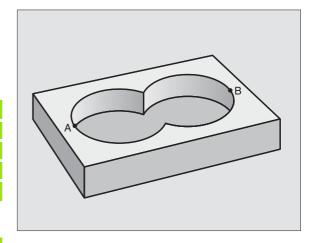
56 LBL 2

57 L X+90 Y+50 RR

58 CC X+65 Y+50

59 C X+90 Y+50 DR-

60 LBL 0



#### Area of exclusion

Surface A is to be machined without the portion overlapped by B

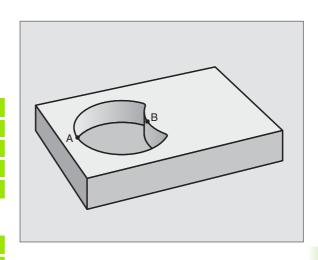
- Surface A must be a pocket and B an island.
- A must start outside of B.

Surface A:

- 51 LBL 1
- 52 L X+10 Y+50 RR
- 53 CC X+35 Y+50
- 54 C X+10 Y+50 DR-
- 55 LBL 0

Surface B:

- 56 LBL 2
- 57 L X+90 Y+50 RL
- 58 CC X+65 Y+50
- 59 C X+90 Y+50 DR-
- 60 LBL 0



#### Area of intersection

Only the area overlapped by both A and B is to be machined. (The areas covered by A or B alone are to be left unmachined.)

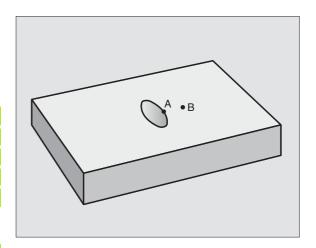
- A and B must be pockets.
- A must start inside of B.

Surface A:

- 51 LBL 1
- 52 L X+60 Y+50 RR
- 53 CC X+35 Y+50
- 54 C X+60 Y+50 DR-
- 55 LBL 0

Surface B:

- 56 LBL 2
- 57 L X+90 Y+50 RR
- 58 CC X+65 Y+50
- 59 C X+90 Y+50 DR-
- 60 LBL 0





# **CONTOUR DATA (Cycle 20)**

Machining data for the subprograms describing the subcontours are entered in Cycle 20.



#### Before programming, note the following:

Cycle 20 is DEF active which means that it becomes effective as soon as it is defined in the part program.

The algebraic sign for the cycle parameter DEPTH determines the working direction. If you program depth = 0, the TNC does not execute that next cycle.

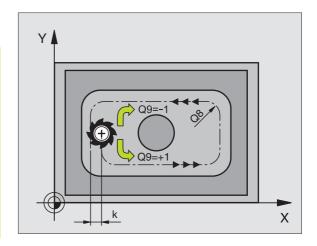
The machining data entered in Cycle 20 are valid for Cycles 21 to 24.

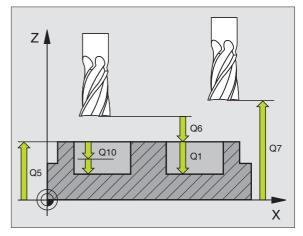
If you are using the SL cycles in Q parameter programs, the cycle parameters Q1 to Q19 cannot be used as program parameters.



- ▶ Milling depth Q1 (incremental value): Distance between workpiece surface and bottom of pocket
- ▶ Path overlap factor Q2: Q2 x tool radius = stepover factor k
- Finishing allowance for side Q3 (incremental value): Finishing allowance in the working plane
- Finishing allowance for floor Q4 (incremental value): Finishing allowance in the tool axis
- ▶ Workpiece surface coordinate Q5 (absolute value): Absolute coordinate of the workpiece surface
- ▶ **Set-up clearance** Q6 (incremental value): Distance between tool tip and workpiece surface
- ▶ Clearance height Q7 (absolute value): Absolute height at which the tool cannot collide with the workpiece (for intermediate positioning and retraction at the end of the cycle)
- ▶ Inside corner radius Q8: Inside "corner" rounding radius; entered value is referenced to the tool midpoint path.
- ▶ Direction of rotation ? Clockwise = -1 Q9: Machining direction for pockets
  - Clockwise (Q9 = -1 up-cut milling for pocket and island)
  - Counterclockwise (Q9 = +1 climb milling for pocket and island)

You can check the machining parameters during a program interruption and overwrite them if required.





#### **Example: NC blocks**

57	CYCL DEF	20.0 CONTOUR DATA
	Q1=-20	;MILLING DEPTH
	Q2=1	;TOOL PATH OVERLAP
	Q3=+0.2	;ALLOWANCE FOR SIDE
	Q4=+0.1	;ALLOWANCE FOR FLOOR
	Q5=+30	;SURFACE COORDINATE
	Q6=2	;SET-UP CLEARANCE
	Q7=+80	;CLEARANCE HEIGHT
	Q8=0.5	;ROUNDING RADIUS
	Q9=+1	;DIRECTION OF ROTATION

# **REAMING (Cycle 21)**



When calculating the infeed points, the TNC does not account for the delta value DR programmed in a TOOL CALL block.

In narrow areas, the TNC may not be able to carry out pilot drilling with a tool that is larger than the rough-out tool.

#### **Process**

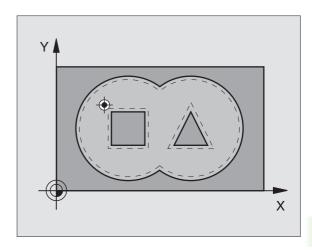
Same as Cycle 1, Pecking; see "Cycles for Drilling, Tapping and Thread Milling," page 209.

#### **Application**

Cycle 21 is for PILOT DRILLING of the cutter infeed points. It accounts for the allowance for side and the allowance for floor as well as the radius of the rough-out tool. The cutter infeed points also serve as starting points for roughing.



- ▶ Plunging depth Q10 (incremental value): Dimension by which the tool drills in each infeed (negative sign for negative working direction)
- ► Feed rate for plunging Q11: Traversing speed in mm/min during drilling
- ▶ Rough-out tool number Q13: Tool number of the roughing mill



58	CYCL DEF	21.0 PILOT DRILLING	
	Q10=+5	;PLUNGING DEPTH	
	Q11=100	;FEED RATE FOR PLUNGING	
	Q13=1	;ROUGH-OUT TOOL	

# **ROUGH-OUT (Cycle 22)**

- 1 The TNC positions the tool over the cutter infeed point, taking the allowance for side into account.
- 2 In the first plunging depth, the tool mills the contour from inside outward at the milling feed rate Q12.
- **3** The island contours (here: C/D) are cleared out with an approach toward the pocket contour (here: A/B).
- **4** Then the TNC rough-mills the pocket contour retracts the tool to the clearance height.

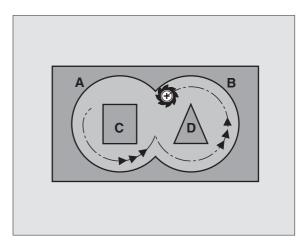


#### Before programming, note the following:

This cycle requires a center-cut end mill (ISO 1641) or pilot drilling with Cycle 21.



- ▶ Plunging depth Q10 (incremental value): Dimension by which the tool plunges in each infeed
- ► Feed rate for plunging Q11: Traversing speed of the tool in mm/min during penetration
- ▶ Feed rate for milling Q12: Traversing speed for milling in mm/min
- ▶ Coarse roughing tool number Q18: Number of the tool with which the TNC has already coarse-roughed the contour. If there was no coarse roughing, enter "0"; if you enter a value other than zero, the TNC will only rough-out the portion that could not be machined with the coarse roughing tool. If the portion that is to be roughed cannot be approached from the side, the TNC will mill in a reciprocating plunge-cut; For this purpose you must enter the tool length LCUTS in the tool table TOOL.T, see "Tool Data," page 99 and define the maximum plunging ANGLE of the tool. The TNC will otherwise generate an error message.
- ▶ Reciprocation feed rate Q19: Traversing speed of the tool in mm/min during reciprocating plunge-cut



59	CYCL DEF	22.0 ROUGH-OUT
	Q10=+5	;PLUNGING DEPTH
	Q11=100	;FEED RATE FOR PLUNGING
	Q12=350	;FEED RATE FOR MILLING
	Q18=1	;COARSE ROUGHING TOOL
	Q19=150	;RECIPROCATION FEED RATE



# **FLOOR FINISHING (Cycle 23)**

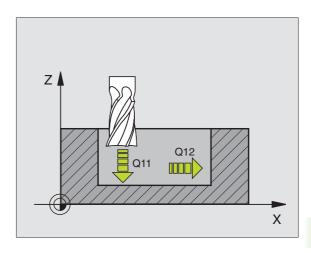


The TNC automatically calculates the starting point for finishing. The starting point depends on the available space in the pocket.

The tool approaches the machining plane smoothly (in a vertically tangential arc). The tool then clears the finishing allowance remaining from rough-out.



- ▶ Feed rate for plunging: Traversing speed of the tool during penetration
- ▶ Feed rate for milling Q12: Traversing speed for milling



**Example: NC blocks** 

60 CYCL DEF 23.0 FLOOR FINISHING

Q11=100 ; FEED RATE FOR PLUNGING

Q12=350 ; FEED RATE FOR MILLING

# **SIDE FINISHING (Cycle 24)**

The subcontours are approached and departed on a tangential arc. Each subcontour is finish-milled separately.



#### Before programming, note the following:

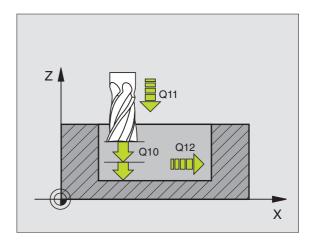
The sum of allowance for side (Q14) and the radius of the finish mill must be smaller than the sum of allowance for side (Q3, Cycle 20) and the radius of the rough mill.

This calculation also holds if you run Cycle 24 without having roughed out with Cycle 22; in this case, enter "0" for the radius of the rough mill.

The TNC automatically calculates the starting point for finishing. The starting point depends on the available space in the pocket.



- ▶ Direction of rotation ? Clockwise = -1 Q9: Machining direction:
  - +1:Counterclockwise
  - -1:Clockwise
- ▶ Plunging depth Q10 (incremental value): Dimension by which the tool plunges in each infeed
- ▶ Feed rate for plunging Q11: Traversing speed of the tool during penetration
- ▶ Feed rate for milling Q12: Traversing speed for milling
- ▶ Finishing allowance for side Q14 (incremental value): Enter the allowed material for several finishmilling operations. If you enter Q14 = 0, the remaining finishing allowance will be cleared.



61	CYCL DEF 2	4.0 SIDE FINISHING
	Q9=+1	;DIRECTION OF ROTATION
	Q10=+5	;PLUNGING DEPTH
	Q11=100	;FEED RATE FOR PLUNGING
	Q12=350	;FEED RATE FOR MILLING
	Q14=+0	;ALLOWANCE FOR SIDE

# **CONTOUR TRAIN (Cycle 25)**

In conjunction with Cycle 14 CONTOUR GEOMETRY, this cycle facilitates the machining of open contours (i.e. where the starting point of the contour is not the same as its end point).

Cycle 25 CONTOUR TRAIN offers considerable advantages over machining an open contour using positioning blocks:

- The TNC monitors the operation to prevent undercuts and surface blemishes. It is recommended that you run a graphic simulation of the contour before execution.
- If the radius of the selected tool is too large, the corners of the contour may have to be reworked.
- The contour can be machined throughout by up-cut or by climb milling. The type of milling even remains effective when the contours are mirrored.
- The tool can traverse back and forth for milling in several infeeds: This results in faster machining.
- Allowance values can be entered in order to perform repeated rough-milling and finish-milling operations.



#### Before programming, note the following:

The algebraic sign for the cycle parameter DEPTH determines the working direction. If you program DEPTH = 0, the cycle will not be executed.

The TNC takes only the first label of Cycle 14 CONTOUR GEOMETRY into account.

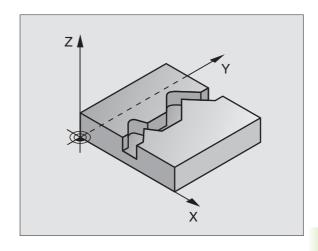
The memory capacity for programming an SL cycle is limited. For example, you can program up to 256 straight-line blocks in one SL cycle.

Cycle 20 CONTOUR DATA is not required.

Positions that are programmed in incremental dimensions immediately after Cycle 25 are referenced to the position of the tool at the end of the cycle.



- ▶ Milling depth Q1 (incremental value): Distance between workpiece surface and contour floor
- Finishing allowance for side Q3 (incremental value): Finishing allowance in the working plane
- ▶ Workpiece surface coordinate Q5 (absolute value): Absolute coordinate of the workpiece surface referenced to the workpiece datum
- ▶ Clearance height Q7 (absolute value): Absolute height at which the tool cannot collide with the workpiece. Position for tool retraction at the end of the cycle.
- ▶ Plunging depth Q10 (incremental value): Dimension by which the tool plunges in each infeed
- ▶ Feed rate for plunging Q11: Traversing speed of the tool in the tool axis



62	CYCL DEF	25.0 CONTOUR TRAIN
	Q1=-20	;MILLING DEPTH
	Q3=+0	;ALLOWANCE FOR SIDE
	Q5=+0	;WORKPIECE SURFACE COORD.
	Q7=+50	;CLEARANCE HEIGHT
	Q10=+5	;PLUNGING DEPTH
	Q11=100	;FEED RATE FOR PLUNGING
	Q12=350	;FEED RATE FOR MILLING
	Q1=-1	;CLIMB OR UP-CUT

- ▶ Feed rate for milling Q12: Traversing speed of the tool in the working plane
- ► Climb or up-cut ? Up-cut = -1 Q15: Climb milling: Input value = +1 Up-cut milling: Input value = -1 To enable climb milling and up-cut milling alternately in several infeeds:Input value = 0



# **CYLINDER SURFACE (Cycle 27)**



Machine and control must be specially prepared by the machine tool builder for use of this cycle.

This cycle enables you to program a contour in two dimensions and then roll it onto a cylindrical surface for 3-D machining. Use Cycle 28 if you wish to mill guide notches onto the cylinder surface.

The contour is described in a subprogram identified in Cycle 14 CONTOUR GEOMETRY.

The subprogram contains coordinates in a rotary axis and in its parallel axis. The rotary axis C, for example, is parallel to the Z axis. The path functions L, CHF, CR, RND APPR (except APPR LCT) and DEP are available.

The dimensions in the rotary axis can be entered as desired either in degrees or in mm (or inches). You can select the desired dimension type in the cycle definition.

- 1 The TNC positions the tool over the cutter infeed point, taking the allowance for side into account.
- **2** At the first plunging depth, the tool mills along the programmed contour at the milling feed rate Q12.
- **3** At the end of the contour, the TNC returns the tool to the setup clearance and returns to the point of penetration;
- **4** Steps 1 to 3 are repeated until the programmed milling depth Q1 is reached.
- **5** Then the tool moves to the setup clearance.



#### Before programming, note the following:

The memory capacity for programming an SL cycle is limited. For example, you can program up to 256 straight-line blocks in one SL cycle.

The algebraic sign for the cycle parameter DEPTH determines the working direction. If you program DEPTH = 0, the cycle will not be executed.

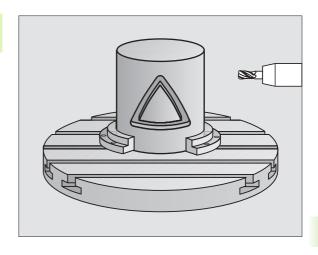
This cycle requires a center-cut end mill (ISO 1641).

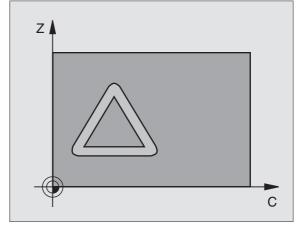
The cylinder must be set up centered on the rotary table.

The tool axis must be perpendicular to the rotary table. If this is not the case, the TNC will generate an error message.

This cycle can also be used in a tilted working plane.

The TNC checks whether the compensated and non-compensated tool paths lie within the display range of the rotary axis, which is defined in Machine Parameter 810.x. If the error message "Contour programming error" is output, set MP 810.x = 0.









- Milling depth Q1 (incremental value): Distance between the cylindrical surface and the floor of the contour
- ▶ Finishing allowance for side Q3 (incremental value): Finishing allowance in the plane of the unrolled cylindrical surface. This allowance is effective in the direction of the radius compensation
- ▶ **Set-up clearance** Q6 (incremental value): Distance between the tool tip and the cylinder surface
- ▶ Plunging depth Q10 (incremental value): Dimension by which the tool plunges in each infeed
- ▶ Feed rate for plunging Q11: Traversing speed of the tool in the tool axis
- ▶ Feed rate for milling Q12: Traversing speed of the tool in the working plane
- ▶ Cylinder radius Q16: Radius of the cylinder on which the contour is to be machined
- ▶ Dimension type? ang./lin. Q17: The dimensions for the rotary axis of the subprogram are given either in degrees (0) or in mm/inches (1)

63 CYCL DEF	27.0 CYLINDER SURFACE
Q1=-8	;MILLING DEPTH
Q3=+0	;ALLOWANCE FOR SIDE
Q6=+0	;SET-UP CLEARANCE
010=+3	;PLUNGING DEPTH
Q11=100	;FEED RATE FOR PLUNGING
Q12=350	;FEED RATE FOR MILLING
Q16=25	; RADIUS
Q17=0	;DIMENSION TYPE (ANG/LIN)



### **CYLINDER SURFACE slot milling (Cycle 28)**



Machine and control must be specially prepared by the machine tool builder for use of this cycle.

This cycle enables you to program a guide notch in two dimensions and then transfer it onto a cylindrical surface. Unlike Cycle 27, with this cycle the TNC adjusts the tool so that, with radius compensation active, the walls of the slot are always parallel. Program the center-line path of the contour.

- 1 The TNC positions the tool over the cutter infeed point.
- 2 At the first plunging depth, the tool mills along the programmed slot wall at the milling feed rate Q12 while respecting the finishing allowance for the side.
- **3** At the end of the contour, the TNC moves the tool to the opposite wall and returns to the infeed point.
- **4** Steps 2 and 3 are repeated until the programmed milling depth Q1 is reached.
- **5** Then the tool moves to the setup clearance.



### Before programming, note the following:

The memory capacity for programming an SL cycle is limited. For example, you can program up to 256 straight-line blocks in one SL cycle.

The algebraic sign for the cycle parameter DEPTH determines the working direction. If you program DEPTH = 0, the cycle will not be executed.

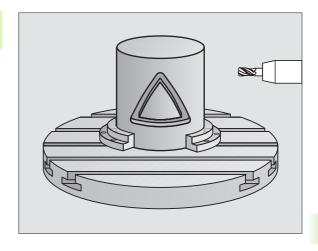
This cycle requires a center-cut end mill (ISO 1641).

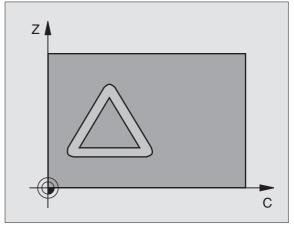
The cylinder must be set up centered on the rotary table.

The tool axis must be perpendicular to the rotary table. If this is not the case, the TNC will generate an error message.

This cycle can also be used in a tilted working plane.

The TNC checks whether the compensated and non-compensated tool paths lie within the display range of the rotary axis, which is defined in Machine Parameter 810.x. If the error message "Contour programming error" is output, set MP 810.x = 0.







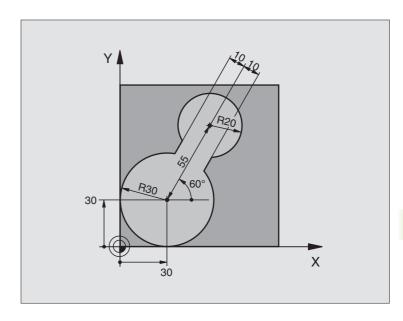
- Milling depth Q1 (incremental value): Distance between the cylindrical surface and the floor of the contour
- ▶ Finishing allowance for side Q3 (incremental value): Finishing allowance in the plane of the unrolled cylindrical surface. This allowance is effective in the direction of the radius compensation
- ▶ **Set-up clearance** Q6 (incremental value): Distance between the tool tip and the cylinder surface
- ▶ Plunging depth Q10 (incremental value): Dimension by which the tool plunges in each infeed
- ▶ Feed rate for plunging Q11: Traversing speed of the tool in the tool axis
- ▶ Feed rate for milling Q12: Traversing speed of the tool in the working plane
- ▶ Cylinder radius Q16: Radius of the cylinder on which the contour is to be machined
- ▶ Dimension type? ang./lin. Q17: The dimensions for the rotary axis of the subprogram are given either in degrees (0) or in mm/inches (1)
- ▶ Slot width Q20: Width of the slot to be machined

### **Example: NC blocks**

63	CYCL DEF 2	8.0 CYLINDER SURFACE
	Q1=-8	;MILLING DEPTH
	Q3=+0	;ALLOWANCE FOR SIDE
	Q6=+0	;SET-UP CLEARANCE
	Q10=+3	;PLUNGING DEPTH
	Q11=100	;FEED RATE FOR PLUNGING
	Q12=350	;FEED RATE FOR MILLING
	Q16=25	; RADIUS
	Q17=0	;DIMENSION TYPE (ANG/LIN)
	Q20=12	;SLOT WIDTH



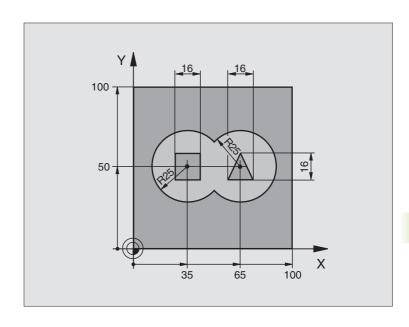
# **Example: Roughing-out and fine-roughing a pocket**



O BEGIN PGM C20 MM	
1 BLK FORM 0.1 Z X-10 Y-10 Z-40	
2 BLK FORM 0.2 X+100 Y+100 Z+0	Define the workpiece blank
3 TOOL DEF 1 L+0 R+15	Tool definition: coarse roughing tool
4 TOOL DEF 2 L+0 R+7.5	Tool definition: fine roughing tool
5 TOOL CALL 1 Z S2500	Tool call: coarse roughing tool
6 L Z+250 RO F MAX	Retract the tool
7 CYCL DEF 14.0 CONTOUR GEOMETRY	Define contour subprogram
8 CYCL DEF 14.1 CONTOUR LABEL 1	
9 CYCL DEF 20.0 CONTOUR DATA	Define general machining parameters
Q1=-20 ;MILLING DEPTH	
Q2=1 ;TOOL PATH OVERLAP	
Q3=+O ;ALLOWANCE FOR SIDE	
Q4=+0 ;ALLOWANCE FOR FLOOR	
Q5=+O ;WORKPIECE SURFACE COORD.	
Q6=2 ;SET-UP CLEARANCE	
Q7=+100 ;CLEARANCE HEIGHT	
Q8=0.1 ; ROUNDING RADIUS	
Q9=-1 ;DIRECTION OF ROTATION	

10 CYCL DEF 22.0 ROUGH-OUT	Cycle definition: Coarse roughing
Q10=5 ;PLUNGING DEPTH	, and a second s
Q11=100 ;FEED RATE FOR PLUNGING	
Q12=350 ;FEED RATE FOR MILLING	
Q18=O ; COARSE ROUGHING TOOL	
Q19=150 ;RECIPROCATION FEED RATE	
11 CYCL CALL M3	Cycle call: Coarse roughing
12 L Z+250 RO F MAX M6	Tool change
13 TOOL CALL 2 Z S3000	Tool call: fine roughing tool
14 CYCL DEF 22.0 ROUGH-OUT	Define the fine roughing cycle
Q10=5 ; PLUNGING DEPTH	
Q11=100 ;FEED RATE FOR PLUNGING	
Q12=350 ;FEED RATE FOR MILLING	
Q18=1 ;COARSE ROUGHING TOOL	
Q19=150 ;RECIPROCATION FEED RATE	
15 CYCL CALL M3	Cycle call: Fine roughing
16 L Z+250 RO F MAX M2	Retract in the tool axis, end program
17 LBL 1	Contour subprogram
18 L X+0 Y+30 RR	see "Example: FK programming 2," page 169
19 FC DR- R30 CCX+30 CCY+30	
20 FL AN+60 PDX+30 PDY+30 D10	
21 FSELECT 3	
22 FPOL X+30 Y+30	
23 FC DR- R20 CCPR+55 CCPA+60 24 FSELECT 2	
24 FSELECT 2 25 FL AN-120 PDX+30 PDY+30 D10	
26 FSELECT 3	
27 FC X+0 DR- R30 CCX+30 CCY+30	
28 FSELECT 2	
29 LBL 0	
30 END PGM C20 MM	
OV END I WIT CEO FILT	

# **Example: Pilot drilling, roughing-out and finishing overlapping contours**



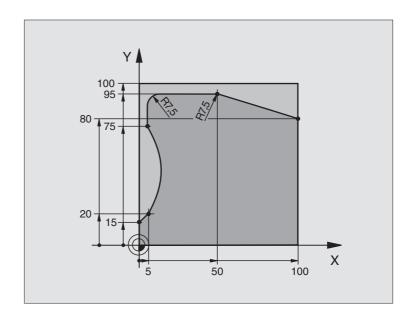
O BEGIN PGM C21 MM	
1 BLK FORM 0.1 Z X+0 Y+0 Z-40	Define the workpiece blank
2 BLK FORM 0.2 X+100 Y+100 Z+0	
3 TOOL DEF 1 L+0 R+6	Define tool: drill
4 TOOL DEF 2 L+0 R+6	Define the tool for roughing/finishing
5 TOOL CALL 1 Z S2500	Call the drilling tool
6 L Z+250 R0 F MAX	Retract the tool
7 CYCL DEF 14.0 CONTOUR GEOMETRY	Define contour subprogram
8 CYCL DEF 14.1 CONTOUR LABEL 1 /2 /3 /4	
9 CYCL DEF 20.0 CONTOUR DATA	Define general machining parameters
Q1=-20 ;MILLING DEPTH	
Q2=1 ;TOOL PATH OVERLAP	
Q3=+0.5 ;ALLOWANCE FOR SIDE	
Q4=+0.5 ;ALLOWANCE FOR FLOOR	
Q5=+0 ;WORKPIECE SURFACE COORD.	
Q6=2 ; SET-UP CLEARANCE	
Q7=+100 ; CLEARANCE HEIGHT	
Q8=0.1 ; ROUNDING RADIUS	
Q9=-1 ; DIRECTION OF ROTATION	

10 CYCL DEF 21.0 PILOT DRILLING	Cycle definition: Pilot drilling
Q10=5 ; PLUNGING DEPTH	
Q11=250 ; FEED RATE FOR PLUNGING	
Q13=2 ; ROUGH-OUT TOOL	
11 CYCL CALL M3	Cycle call: Pilot drilling
12 L Z+250 RO F MAX M6	Tool change
13 TOOL CALL 2 Z S3000	Call the tool for roughing/finishing
14 CYCL DEF 22.0 ROUGH-OUT	Cycle definition: Rough-out
Q10=5 ;PLUNGING DEPTH	
Q11=100 ; FEED RATE FOR PLUNGING	
Q12=350 ;FEED RATE FOR MILLING	
Q18=0 ;COARSE ROUGHING TOOL	
Q19=150 ;RECIPROCATION FEED RATE	
15 CYCL CALL M3	Cycle call: Rough-out
16 CYCL DEF 23.0 FLOOR FINISHING	Cycle definition: Floor finishing
Q11=100 ;FEED RATE FOR PLUNGING	
Q12=200 ;FEED RATE FOR MILLING	
17 CYCL CALL	Cycle call: Floor finishing
18 CYCL DEF 24.0 SIDE FINISHING	Cycle definition: Side finishing
Q9=+1 ;DIRECTION OF ROTATION	
Q10=5 ;PLUNGING DEPTH	
Q10=5 ;PLUNGING DEPTH Q11=100 ;FEED RATE FOR PLUNGING	
Q11=100 ;FEED RATE FOR PLUNGING	
Q11=100 ; FEED RATE FOR PLUNGING Q12=400 ; FEED RATE FOR MILLING	Cycle call: Side finishing

8 Programming: Cycles

21 LBL 1	Contour subprogram 1: left pocket
22 CC X+35 Y+50	
23 L X+10 Y+50 RR	
24 C X+10 DR-	
25 LBL 0	
26 LBL 2	Contour subprogram 2: right pocket
27 CC X+65 Y+50	
28 L X+90 Y+50 RR	
29 C X+90 DR-	
30 LBL 0	
31 LBL 3	Contour subprogram 3: square left island
32 L X+27 Y+50 RL	
33 L Y+58	
34 L X+43	
35 L Y+42	
36 L X+27	
37 LBL 0	
38 LBL 4	Contour subprogram 4: triangular right island
39 L X+65 Y+42 RL	
40 L X+57	
41 L X+65 Y+58	
42 L X+73 Y+42	
43 LBL 0	
44 END PGM C21 MM	

# **Example: Contour train**



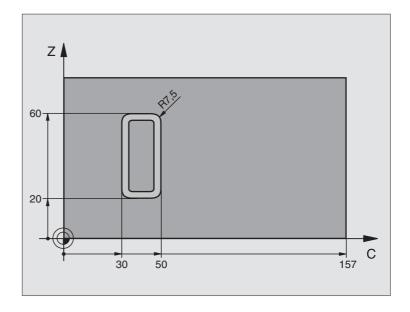
O BEGIN PGM C25 MM	
1 BLK FORM 0.1 Z X+0 Y+0 Z-40	Define the workpiece blank
2 BLK FORM 0.2 X+100 Y+100 Z+0	
3 TOOL DEF 1 L+0 R+10	Define the tool
4 TOOL CALL 1 Z S20004	Tool call
5 L Z+250 RO F MAX	Retract the tool
6 CYCL DEF 14.0 CONTOUR GEOMETRY	Define contour subprogram
7 CYCL DEF 14.1 CONTOUR LABEL 1	
8 CYCL DEF 25.0 CONTOUR TRAIN	Define machining parameters
Q1=-20 ;MILLING DEPTH	
Q3=+O ;ALLOWANCE FOR SIDE	
Q5=+0 ;WORKPIECE SURFACE COORD.	
Q7=+250 ;CLEARANCE HEIGHT	
Q10=5 ; PLUNGING DEPTH	
Q11=100 ; FEED RATE FOR PLUNGING	
Q12=200 ; FEED RATE FOR MILLING	
Q15=+1 ;CLIMB OR UP-CUT	
9 CYCL CALL M3	Call the cycle
10 L Z+250 RO F MAX M2	Retract in the tool axis, end program

11	LBL 1	Contour subprogram
12	L X+0 Y+15 RL	
13	L X+5 Y+20	
14	CT X+5 Y+75	
15	L Y+95	
16	RND R7.5	
17	L X+50	
18	RND R7.5	
19	L X+100 Y+80	
20	LBL 0	
21	END PGM C25 MM	

# **Example: Cylinder surface**

### Note:

- Cylinder centered on rotary table.
- Datum at center of rotary table



O BEGIN PGM C27 MM	
1 TOOL DEF 1 L+0 R+3.5	Define the tool
2 TOOL CALL 1 Y S2000	Call tool, tool axis is Y
3 L Y+250 RO FMAX	Retract the tool
4 L X+O RO FMAX	Position tool on rotary table center
5 CYCL DEF 14.0 CONTOUR GEOMETRY	Define contour subprogram
6 CYCL DEF 14.1 CONTOUR LABEL 1	
7 CYCL DEF 27.0 CYLINDER SURFACE	Define machining parameters
Q1=-7 ;MILLING DEPTH	
Q3=+O ;ALLOWANCE FOR SIDE	
Q6=2 ;SET-UP CLEARANCE	
Q10=4 ; PLUNGING DEPTH	
Q11=100 ; FEED RATE FOR PLUNGING	
Q12=250 ; FEED RATE FOR MILLING	
Q16=25 ; RADIUS	
Q17=1 ;DIMENSION TYPE (ANG/LIN)	
8 L C+O RO F MAX M3	Pre-position rotary table
9 CYCL CALL	Call the cycle
10 L Y+250 RO F MAX M2	Retract in the tool axis, end program

11 LBL 1		Contour subprogram
12 L C+40 Z+20	RL	Data for the rotary axis are entered in mm (Q17=1)
13 L C+50		
14 RND R7.5		
15 L Z+60		
16 RND R7.5		
17 L IC-20		
18 RND R7.5		
19 L Z+20		
20 RND R7.5		
21 L C+40		
22 LBL 0		
23 END PGM C27	ММ	

# 8.7 Cycles for multipass milling

### **Overview**

The TNC offers three cycles for machining the following surface types:

- Created by digitizing or with a CAD/CAM system
- Flat, rectangular surfaces
- Flat, oblique-angled surfaces
- Surfaces that are inclined in any way
- Twisted surfaces

Cycle	Soft key
30 RUN DIGITIZED DATA For multipass milling of digitized surface data in several infeeds	30 MILL PNT-DAT
230 MULTIPASS MILLING For flat rectangular surfaces	230
231 RULED SURFACE For oblique, inclined or twisted surfaces	231



### **RUN DIGITIZED DATA (Cycle 30)**

- 1 From the current position, the TNC positions the tool in rapid traverse FMAX in the tool axis to the set-up clearance above the MAX point that you have programmed in the cycle.
- **2** The tool then moves in FMAX in the working plane to the MIN point you have programmed in the cycle.
- **3** From this point, the tool advances to the first contour point at the feed rate for plunging.
- **4** The TNC subsequently processes all points that are stored in the digitizing data file at the feed rate for milling. If necessary, the TNC retracts the tool between machining operations to set-up clearance if specific areas are to be left unmachined.
- **5** At the end of the cycle, the tool is retracted in FMAX to set-up clearance.



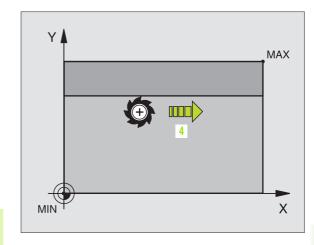
### Before programming, note the following:

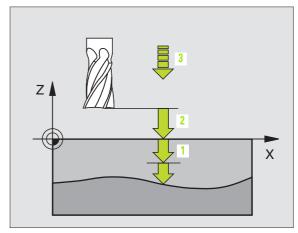
You can use Cycle 30 to run digitizing data and PNT files.

If you want to run PNT files in which no tool axis coordinate is programmed, the milling depth is derived from the programmed MIN point in the tool axis.



- ▶ PGM Name digitizing data: Enter the name of the file in which the digitizing data is stored. If the file is not stored in the current directory, enter the complete path. If you wish to execute a point table, enter also the file type .PNT.
- Min. point of range: Lowest coordinates (X, Y and Z coordinates) in the range to be milled
- Max. point of range: Highest coordinates (X, Y and Z coordinates) in the range to be milled
- Set-up clearance 1 (incremental value): Distance between tool tip and workpiece surface for tool movements in rapid traverse
- ▶ Plunging depth 2 (incremental value): Infeed per cut
- ▶ Feed rate for plunging 3: Traversing speed of the tool in mm/min during penetration
- ► Feed rate for milling 4: Traversing speed of the tool in mm/min while milling.
- ▶ Miscellaneous function M: Optional entry of a miscellaneous function, for example M13





### **Example: NC blocks**

64	CYCL DEF 30.0 RUN DIGITIZED DATA
65	CYCL DEF 30.1 PGM DIGIT.: BSP.H
66	CYCL DEF 30.2 X+0 Y+0 Z-20
67	CYCL DEF 30.3 X+100 Y+100 Z+0
68	CYCL DEF 30.4 SET UP 2
69	CYCL DEF 30.5 PLNGNG +5 F100
70	CYCL DEF 30.6 F350 M8

### **MULTIPASS MILLING (Cycle 230)**

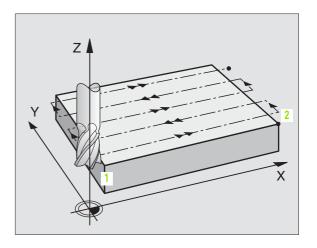
- 1 From the current position in the working plane, the TNC positions the tool in rapid traverse FMAX to the starting point 1; the TNC moves the tool by its radius to the left and upward.
- 2 The tool then moves in FMAX in the tool axis to set-up clearance. From there it approaches the programmed starting position in the tool axis at the feed rate for plunging.
- 3 The tool then moves as the programmed feed rate for milling to the end point 2. The TNC calculates the end point from the programmed starting point, the program length, and the tool radius.
- **4** The TNC offsets the tool to the starting point in the next pass at the stepover feed rate. The offset is calculated from the programmed width and the number of cuts.
- **5** The tool then returns in the negative direction of the first axis.
- 6 Multipass milling is repeated until the programmed surface has been completed.
- 7 At the end of the cycle, the tool is retracted in FMAX to set-up clearance.



### Before programming, note the following:

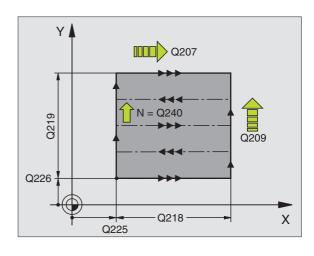
From the current position, the TNC positions the tool at the starting point 1, first in the working plane and then in the tool axis.

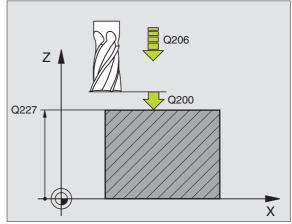
Pre-position the tool in such a way that no collision between tool and clamping devices can occur.





- ▶ Starting point in 1st axis Q225 (absolute value): Minimum point coordinate of the surface to be multipass-milled in the reference axis of the working plane
- ▶ Starting point in 2nd axis Q226 (absolute value): Minimum-point coordinate of the surface to be multipass-milled in the minor axis of the working plane
- ▶ Starting point in 3rd axis Q227 (absolute value): Height in the spindle axis at which multipass-milling is carried out
- ▶ First side length Q218 (incremental value): Length of the surface to be multipass-milled in the reference axis of the working plane, referenced to the starting point in 1st axis
- ▶ Second side length Q219 (incremental value): Length of the surface to be multipass-milled in the minor axis of the working plane, referenced to the starting point in 2nd axis
- Number of cuts Q240: Number of passes to be made over the width
- ▶ Feed rate for plunging 206: Traversing speed of the tool in mm/min when moving from set-up clearance to the milling depth
- ▶ Feed rate for milling Q207: Traversing speed of the tool in mm/min while milling.
- ▶ Stepover feed rate Q209: Traversing speed of the tool in mm/min when moving to the next pass. If you are moving the tool transversely in the material, enter Q209 to be smaller than Q207 If you are moving it transversely in the open, Q209 may be greater than Q207.
- ▶ Set-up clearance Q200 (incremental value): Distance between tool tip and milling depth for positioning at the start and end of the cycle.





### **Example: NC blocks**

71 CYCL DEF 230 MULTIPASS MILLNG
Q225=+10 ;STARTNG PNT 1ST AXIS
Q226=+12 ;STARTNG PNT 2ND AXIS
Q227=+2.5 ;STARTNG PNT 2ND AXIS
Q218=150 ;FIRST SIDE LENGTH
Q219=75 ;SECOND SIDE LENGTH
Q240=25 ;NUMBER OF CUTS
Q206=150 ;FEED RATE FOR PLUNGING
Q207=500 ;FEED RATE FOR MILLING
Q209=200 ;STEPOVER FEED RATE
Q200=2 ;SET-UP CLEARANCE

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### **RULED SURFACE (Cycle 231)**

- 1 From the current position, the TNC positions the tool in a linear 3-D movement to the starting point 1.
- 2 The tool subsequently advances to the stopping point 2 at the feed rate for milling.
- **3** From this point, the tool moves in rapid traverse FMAX by the tool diameter in the positive tool axis direction, and then back to starting point **1**.
- **4** At the starting point **1** the TNC moves the tool back to the last traversed Z value.
- 5 Then the TNC moves the tool in all three axes from point 1 in the direction of point 4 to the next line.
- 6 From this point, the tool moves to the stopping point on this pass. The TNC calculates the end point from point 2 and a movement in the direction of point 3.
- 7 Multipass milling is repeated until the programmed surface has been completed.
- **8** At the end of the cycle, the tool is positioned above the highest programmed point in the tool axis, offset by the tool diameter.



The starting point, and therefore the milling direction, is selectable because the TNC always moves from point 1 to point 2 and in the total movement from point 1 / 2 to point 3 / 4. You can program point 1at any corner of the surface to be machined.

If you are using an end mill for the machining operation, you can optimize the surface finish in the following ways

- A shaping cut (spindle axis coordinate of point 1 greater than spindle-axis coordinate of point 2) for slightly inclined surfaces.
- A drawing cut (spindle axis coordinate of point 1 smaller than spindle-axis coordinate of point 2) for steep surfaces.
- When milling twisted surfaces, program the main cutting direction (from point 1 to point 2) parallel to the direction of the steeper inclination.

If you are using a spherical cutter for the machining operation, you can optimize the surface finish in the following way

■ When milling twisted surfaces, program the main cutting direction (from point 1 to point 2) perpendicular to the direction of the steepest inclination.

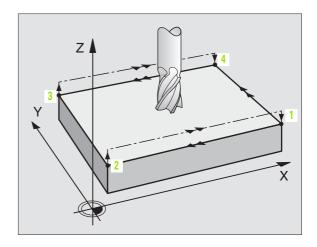


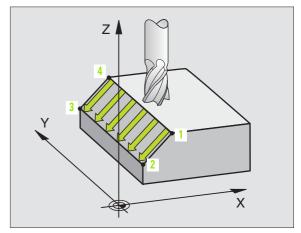
### Before programming, note the following:

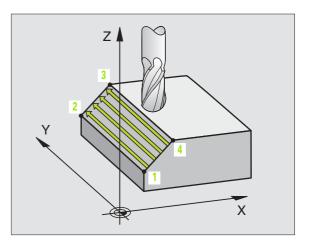
The TNC positions the tool from the current position in a linear 3-D movement to the starting point 1. Preposition the tool in such a way that no collision between tool and clamping devices can occur.

The TNC moves the tool with radius compensation R0 to the programmed positions.

If required, use a center-cut end mill (ISO 1641).



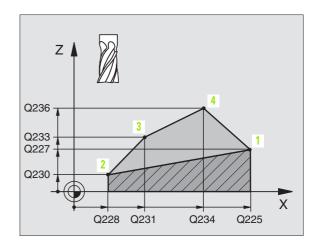


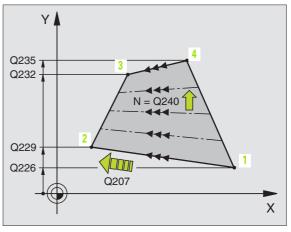






- Starting point in 1st axis Q225 (absolute value): Starting point coordinate of the surface to be multipass-milled in the reference axis of the working plane
- Starting point in 2nd axis Q226 (absolute value): Starting point coordinate of the surface to be multipass-milled in the minor axis of the working plane
- Starting point in 3rd axis Q227 (absolute value): Starting point coordinate of the surface to be multipass-milled in the tool axis
- ▶ 2nd point in 1st axis Q228 (absolute value): Stopping point coordinate of the surface to be multipass milled in the reference axis of the working plane
- ▶ 2nd point in 2nd axis Q229 (absolute value): Stopping point coordinate of the surface to be multipass milled in the minor axis of the working plane
- ▶ 2nd point in 3rd axis Q230 (absolute value): Stopping point coordinate of the surface to be multipass milled in the tool axis
- ▶ 3rd point in 1st axis Q231 (absolute value): Coordinate of point 3 in the reference axis of the working plane
- ▶ 3rd point in 2nd axis Q232 (absolute value): Coordinate of point 3 in the minor axis of the working plane
- ▶ 3rd point in 3rd axis Q233 (absolute value): Coordinate of point 3 in the tool axis





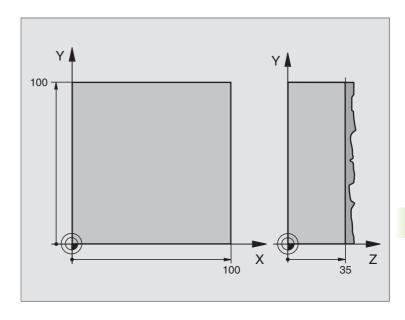
- ▶ 4th point in 1st axis Q234 (absolute value): Coordinate of point 4 in the reference axis of the working plane
- ▶ 4th point in 2nd axis Q235 (absolute value): Coordinate of point 4 in the minor axis of the working plane
- ▶ 4th point in 3rd axis Q236 (absolute value): Coordinate of point 4 in the tool axis
- Number of cuts Q240: Number of passes to be made between points 1 and 4, 2 and 3.
- ▶ Feed rate for milling Q207: Traversing speed of the tool in mm/min while milling. The TNC performs the first step at half the programmed feed rate.

### **Example: NC blocks**

72 CYCL DEF 231 RULED SURFACE
Q225=+0 ;STARTNG PNT 1ST AXIS
Q226=+5 ;STARTNG PNT 2ND AXIS
Q227=-2 ;STARTING PNT 3RD AXIS
Q228=+100 ;2ND POINT 1ST AXIS
Q229=+15 ;2ND POINT 2ND AXIS
Q230=+5 ;2ND POINT 3RD AXIS
Q231=+15 ;3RD POINT 1ST AXIS
Q232=+125 ;3RD POINT 2ND AXIS
Q233=+25 ;3RD POINT 3RD AXIS
Q234=+15 ;4TH POINT 1ST AXIS
Q235=+125 ;4TH POINT 2ND AXIS
Q236=+25 ;4TH POINT 3RD AXIS
Q240=40 ; NUMBER OF CUTS
Q207=500 ;FEED RATE FOR MILLING

8 Programming: Cycles

# **Example: Multipass milling**



O BEGIN PGM C230 MM	
1 BLK FORM 0.1 Z X+0 Y+0 Z+0	Define the workpiece blank
2 BLK FORM 0.2 X+100 Y+100 Z+40	
3 TOOL DEF 1 L+0 R+5	Define the tool
4 TOOL CALL 1 Z S3500	Tool call
5 L Z+250 RO F MAX	Retract the tool
6 CYCL DEF 230 MULTIPASS MILLNG	Cycle definition: MULTIPASS MILLING
Q225=+0 ;STARTNG PNT 1ST AXIS	
Q226=+0 ;STARTNG PNT 2ND AXIS	
Q227=+35 ;STARTNG PNT 3RD AXIS	
Q218=100 ;FIRST SIDE LENGTH	
Q219=100 ;SECOND SIDE LENGTH	
Q240=25 ;NUMBER OF CUTS	
Q206=250 ;FEED RATE FOR PLNGNG	
Q207=400 ;FEED RATE FOR MILLNG	
Q209=150 ;STEPOVER FEED RATE	
Q200=2 ;SET-UP CLEARANCE	

7 L X+-25 Y+0 RO F MAX M3	Pre-position near the starting point	
8 CYCL CALL	Call the cycle	
9 L Z+250 RO F MAX M2	Retract in the tool axis, end program	
10 END PGM C230 MM		

# 8.8 Coordinate Transformation Cycles

### Overview

Once a contour has been programmed, you can position it on the workpiece at various locations and in different sizes through the use of coordinate transformations. The TNC provides the following coordinate transformation cycles:

Cycle	Soft key
7 DATUM SHIFT For shifting contours directly within the program or from datum tables	7
247 DATUM SETTING Datum setting during program run	247
8 MIRROR IMAGE Mirroring contours	8 1
10 ROTATION For rotating contours in the working plane	10
11 SCALING FACTOR For increasing or reducing the size of contours	11
26 AXIS-SPECIFIC SCALING FACTOR For increasing or reducing the size of contours with scaling factors for each axis	26 CC
19 WORKING PLANE For executing machining operations in a tilted coordinate system for machines with tilting heads and/or rotary tables	19

### **Effect of coordinate transformations**

Beginning of effect: A coordinate transformation becomes effective as soon as it is defined — it is not called. It remains in effect until it is changed or canceled.

#### To cancel coordinate transformations:

- Define cycles for basic behavior with a new value, such as scaling factor 1.0
- Execute a miscellaneous function M02, M30, or an END PGM block (depending on machine parameter 7300)
- Select a new program
- Program miscellaneous function M142 Erasing modal program information

### **DATUM SHIFT (Cycle 7)**

A datum shift allows machining operations to be repeated at various locations on the workpiece.

#### **Effect**

When the DATUM SHIFT cycle is defined, all coordinate data is based on the new datum. The TNC displays the datum shift in each axis in the additional status display. Input of rotary axes is also permitted.



▶ **Datum shift**: Enter the coordinates of the new datum. Absolute values are referenced to the manually set workpiece datum. Incremental values are always referenced to the datum which was last valid — this can be a datum which has already been shifted.

### Cancellation

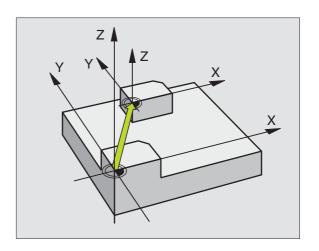
A datum shift is canceled by entering the datum shift coordinates X=0, Y=0 and Z=0.

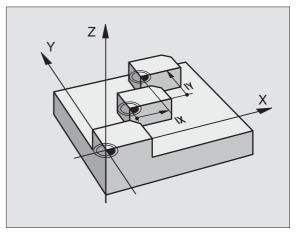
### **Graphics**

If you program a new BLK FORM after a datum shift, you can use machine parameter 7310 to determine whether the BLK FORM is referenced to the current datum or to the original datum. Referencing a new BLK FORM to the current datum enables you to display each part in a program in which several pallets are machined.

### **Status Displays**

- The actual position values are referenced to the active (shifted)
- All of the position values shown in the additional status display are referenced to the manually set datum.





**Example: NC blocks** 

13 CYCL DEF 7.0 DATUM SHIFT

14 CYCL DEF 7.1 X+60

16 CYCL DEF 7.3 Z-5

15 CYCL DEF 7.2 Y+40

### **DATUM SHIFT with datum tables (Cycle 7)**



If you are using datum shifts with datum tables, then use the SEL TABLE function to activate the desired datum table from the NC program.

If you work without SEL-TABLE, then you must activate the desired datum table before the test run or the program run. (This applies also for the programming graphics).

- Use the file management to select the desired table for a test run in the **Test Run** operating mode: The table receives the status S.
- Use the file management in a program run mode to select the desired table for a program run: The table receives the status M.

Datums from a datum table can be referenced either to the current datum or to the machine datum (depending on machine parameter 7475).

The coordinate values from datum tables are only effective with absolute coordinate values.

New lines can only be inserted at the end of the table.

#### **Function**

Datum tables are used for

- frequently recurring machining sequences at various locations on the workpiece
- frequent use of the same datum shift

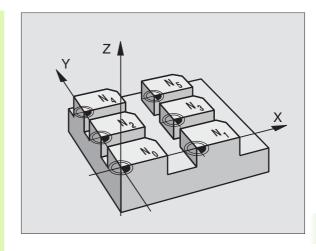
Within a program, you can either program datum points directly in the cycle definition or call them from a datum table.

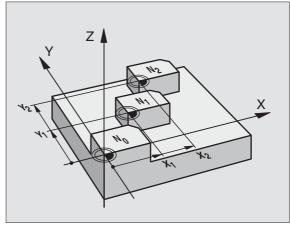


▶ **Datum shift**: Enter the number of the datum from the datum table or a Q parameter. If you enter a Q parameter, the TNC activates the datum number found in the Q parameter.

### Cancellation

- Call a datum shift to the coordinates X=0; Y=0 etc. from a datum table
- Execute a datum shift to the coordinates X=0; Y=0 etc. directly with a cycle definition.





**Example: NC blocks** 

77 CYCL DEF 7.0 DATUM SHIFT

78 CYCL DEF 7.1 #5

### Selecting a datum table in the part program

With the **SEL TABLE** function you select the table from which the TNC takes the datums:



▶ To select the functions for program call, press the PGM CALL key.



- ▶ Press the TOOL TABLE soft key.
- ▶ Enter the complete path name of the datum table and confirm your entry with the END key.



Program a SEL TABLE block before Cycle 7 Datum Shift.

A datum table selected with SEL TABLE remains active until you select another datum table with SEL TABLE or through PGM MGT.

### Editing a datum table

Select the datum table in the **Programming and Editing** mode of operation.



- To call the file manager, press the PGM MGT key, see "File Management: Fundamentals," page 39.
- ▶ Display the datum tables: Press the soft keys SELECT TYPE and SHOW .D.
- ▶ Select the desired table or enter a new file name.
- ▶ Edit the file. The soft-key row comprises the following functions for editing:

Function	Soft key
Select beginning of table	BEGIN T
Select end of table	<u>∏</u>
Go to the next page	PAGE Î
Go to the next page	PAGE
Insert line (only possible at the end of table)	INSERT LINE
Delete line	DELETE LINE
Confirm the entered line and go to the beginning of the next line	NEXT LINE
Add the entered number of lines (reference points) to the end of the table.	APPEND N LINES

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### Edit a pocket table in a Program Run operating mode.

In a program run mode you can select the active datum table. Press the DATUM TABLE soft key. You can then use the same editing functions as in the **Programming and Editing** mode of operation.

#### Configuring the datum table

On the second and third soft-key rows you can define for each datum table the axes for which you wish to set the datums. In the standard setting all of the axes are active. If you wish to exclude an axis, set the corresponding soft key to OFF. The TNC then deletes that column from the datum table.

If you do not wish to define a datum table for an active axis, press the NO ENT key. The TNC then enters a dash in the corresponding column.

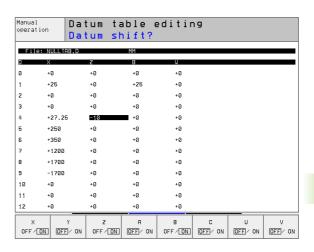
#### To leave a datum table

Select a different type of file in file management and choose the desired file.

### **Status Displays**

If datums in the table are referenced to the machine datum, then:

- The actual position values are referenced to the active (shifted) datum.
- All of the position values shown in the additional status display are referenced to the machine datum, whereby the TNC accounts for the manually set datum.



### **DATUM SETTING (Cycle 247)**

With the cycle DATUM SETTING, you can activate a datum defined in a datum table as the new datum.

#### **Effect**

After a DATUM SETTING cycle definition, all of the coordinate inputs and datum shifts (absolute and incremental) are referenced to the new datum. Setting datums for rotary axes is also possible.



Number for datum?: Enter the number of the datum in the datum table.

#### Cancellation

You can reactivate the last datum set in the Manual mode by entering the miscellaneous function M104.

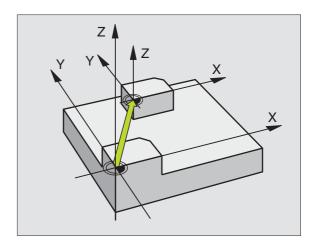


The TNC only sets the datum for those axes which are active in the datum table. An axis displayed as a column in the datum table, but not existing on the TNC, will cause an error message.

Cycle 247 always interprets the values saved in the datum table as coordinates referenced to the machine datum. Machine parameter 7475 has no influence on this.

When using Cycle 247, you cannot use the block scan function for mid-program startup.

Cycle G247 is not functional in Test Run mode.



**Example: NC blocks** 

13 CYCL DEF 247 DATUM SETTING

Q339=4 ; DATUM NUMBER



### **MIRROR IMAGE (Cycle 8)**

The TNC can machine the mirror image of a contour in the working plane.

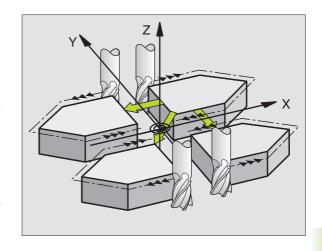
### **Effect**

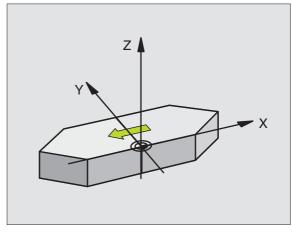
The mirror image cycle becomes effective as soon as it is defined in the program. It is also effective in the Positioning with MDI mode of operation. The active mirrored axes are shown in the additional status display.

- If you mirror only one axis, the machining direction of the tool is reversed (except in fixed cycles).
- If you mirror two axes, the machining direction remains the same. The result of the mirror image depends on the location of the datum:
- If the datum lies on the contour to be mirrored, the element simply flips over.
- If the datum lies outside the contour to be mirrored, the element also "jumps" to another location.



If you mirror only one axis, the machining direction is reversed for the new machining cycles (cycles 2xx). The machining direction remains the same for older machining cycles, such as Cycle 4 POCKET MILLING.



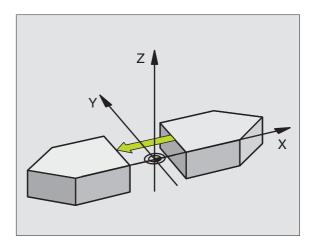




▶ Mirrored axis?: Enter the axis to be mirrored. You can mirror all axes, including rotary axes, except for the spindle axis and its auxiliary axes. You can enter up to three axes.

### Reset

Program the MIRROR IMAGE cycle once again with NO ENT.



**Example: NC blocks** 

79 CYCL DEF 8.0 MIRROR IMAGE

80 CYCL DEF 8.1 X Y U

### **ROTATION (Cycle 10)**

The TNC can rotate the coordinate system about the active datum in the working plane within a program.

### **Effect**

The ROTATION cycle becomes effective as soon as it is defined in the program. It is also effective in the Positioning with MDI mode of operation. The active rotation angle is shown in the additional status display.

Reference axis for the rotation angle:

- X/Y plane X axis
- Y/Z plane Y axis
- Z/X plane Z axis



### Before programming, note the following:

An active radius compensation is canceled by defining Cycle 10 and must therefore be reprogrammed, if necessary.

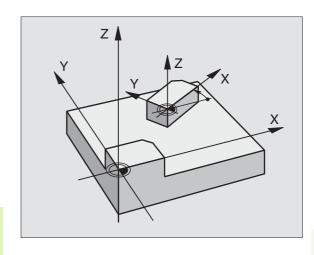
After defining Cycle 10, you must move both axes of the working plane to activate rotation for all axes.

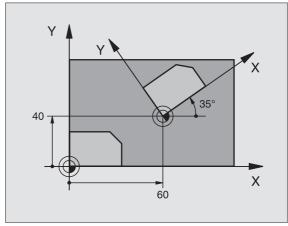


▶ **Rotation**: Enter the rotation angle in degrees (°). Input range: –360° to +360° (absolute or incremental).

#### Cancellation

Program the ROTATION cycle once again with a rotation angle of 0°.





### **Example: NC blocks**

12 CALL LBL1	
13 CYCL DEF 7.0 DATUM SHIFT	
14 CYCL DEF 7.1 X+60	
15 CYCL DEF 7.2 Y+40	
16 CYCL DEF 10.0 DREHUNG	
17 CYCL DEF 10.1 ROT+35	
18 CALL LBL1	

### **SCALING FACTOR (Cycle 11)**

The TNC can increase or reduce the size of contours within a program, enabling you to program shrinkage and oversize allowances.

### **Effect**

The SCALING FACTOR becomes effective as soon as it is defined in the program. It is also effective in the Positioning with MDI mode of operation. The active scaling factor is shown in the additional status display.

### Scaling factor

- in the working plane, or on all three coordinate axes at the same time (depending on machine parameter 7410)
- to the dimensions in cycles
- to the parallel axes U,V,W

### **Prerequisite**

It is advisable to set the datum to an edge or a corner of the contour before enlarging or reducing the contour.

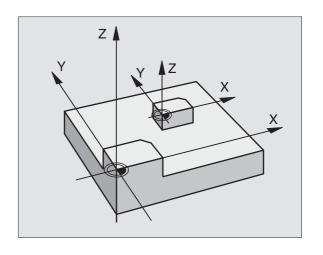


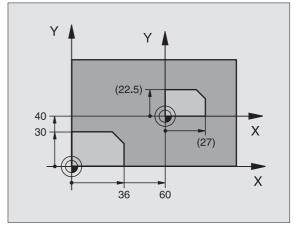
Scaling factor ?: Enter the scaling factor SCL. The TNC multiplies the coordinates and radii by the SCL factor (as described under "Effect" above)

Enlargement: SCL greater than 1 (up to 99.999 999) Reduction: SCL less than 1 (down to 0.000 001)

#### Cancellation

Program the SCALING FACTOR cycle once again with a scaling factor of 1.





### **Example: NC blocks**

11 CALL LBL1
12 CYCL DEF 7.0 DATUM SHIFT
13 CYCL DEF 7.1 X+60
14 CYCL DEF 7.2 Y+40
15 CYCL DEF 11.0 SCALING
16 CYCL DEF 11.1 SCL 0.75
17 CALL LBL1

### **AXIS-SPECIFIC SCALING (Cycle 26)**



### Before programming, note the following:

Coordinate axes sharing coordinates for arcs must be enlarged or reduced by the same factor.

You can program each coordinate axis with its own axisspecific scaling factor.

In addition, you can enter the coordinates of a center for all scaling factors.

The size of the contour is enlarged or reduced with reference to the center, and not necessarily (as in Cycle 11 SCALING FACTOR) with reference to the active datum.

### **Effect**

The SCALING FACTOR becomes effective as soon as it is defined in the program. It is also effective in the Positioning with MDI mode of operation. The active scaling factor is shown in the additional status display.

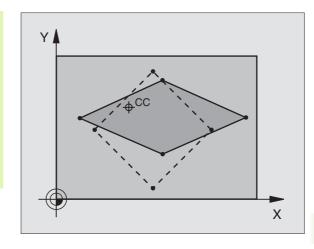


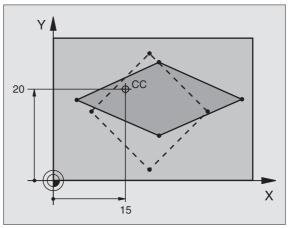
- ▶ Axis and scaling factor: Enter the coordinate axis/ axes as well as the factor(s) involved in enlarging or reducing. Enter a positive value up to 99.999 999.
- ▶ Center coordinates: Enter the center of the axisspecific enlargement or reduction.

The coordinate axes are selected with soft keys.

#### Cancellation

Program the SCALING FACTOR cycle once again with a scaling factor of 1 for the same axis.





**Example: NC blocks** 

25 CALL LBL1

26 CYCL DEF 26.0 AXIS-SPEC. SCALING

27 CYCL DEF 26.1 X 1.4 Y 0.6 CCX+15 CCY+20

28 CALL LBL1

### **WORKING PLANE (Cycle 19)**



The functions for tilting the working plane are interfaced to the TNC and the machine tool by the machine tool builder. With some swivel heads and tilting tables, the machine tool builder determines whether the entered angles are interpreted as coordinates of the tilt axes or as mathematical angles of a tilted plane. Refer to your machine manual.



The working plane is always tilted around the active datum

For fundamentals, see "Tilting the working plane," page 24. Please read this section completely.

#### **Effect**

In Cycle 19 you define the position of the working plane — i.e. the position of the tool axis referenced to the machine coordinate system — by entering tilt angles. There are two ways to determine the position of the working plane:

- Enter the position of the tilting axes directly.
- Describe the position of the working plane using up to 3 rotations (spatial angle) of the **machine-referenced** coordinate system. The required spatial angle can be calculated by cutting a perpendicular line through the tilted working plane and considering it from the axis around which you wish to tilt. With two spatial angles, every tool position in space can be defined exactly.

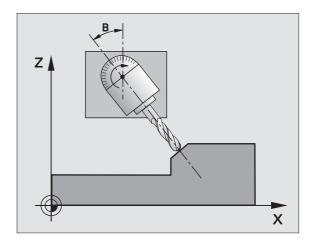


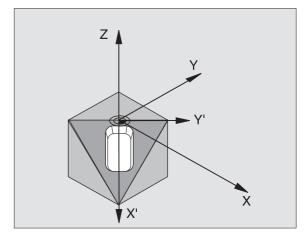
Note that the position of the tilted coordinate system, and therefore also all movement in the tilted system, are dependent on your description of the tilted plane.

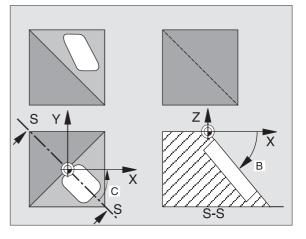
If you program the position of the working plane via spatial angles, the TNC will calculate the required angle positions of the tilted axes automatically and will store these in the parameters Q120 (A axis) to Q122 (C axis). If two solutions are possible, the TNC will choose the shorter path from the zero position of the rotary axes.

The axes are always rotated in the same sequence for calculating the tilt of the plane: The TNC first rotates the A axis, then the B axis, and finally the C axis.

Cycle 19 becomes effective as soon as it is defined in the program. As soon as you move an axis in the tilted system, the compensation for this specific axis is activated. You have to move all axes to activate compensation for all axes.







If you set the function TILTING program run to ACTIVE in the Manual Operation mode see "Tilting the working plane," page 24, the angular value entered in this menu is overwritten by Cycle 19 WORKING PLANE.



▶ Tilt axis and tilt angle?: The axes of rotation together with the associated tilt angles. The rotary axes A, B and C are programmed using soft keys.

If the TNC automatically positions the rotary axes, you can enter the following parameters

- ▶ Feed rate ? F=: Traverse speed of the rotary axis during automatic positioning
- ▶ Set-up clearance ? (incremental value): The TNC positions the tilting head so that the position that results from the extension of the tool by the set-up clearance does not change relative to the workpiece.

#### Cancellation

To cancel the tilt angle, redefine the WORKING PLANE cycle and enter an angular value of 0° for all axes of rotation. You must then program the WORKING PLANE cycle once again by answering the dialog question with the NO ENT key to disable the function.

#### Position the axis of rotation



The machine tool builder determines whether Cycle 19 positions the axes of rotation automatically or whether they must be pre-positioned in the program. Refer to your machine manual.

If the rotary axes are positioned automatically in Cycle 19:

- The TNC can position only controlled axes
- In order for the tilted axes to be positioned, you must enter a feed rate and a set-up clearance in addition to the tilting angles, during cycle definition.
- You can use only preset tools (with the full tool length defined in the TOOL DEF block or in the tool table).
- The position of the tool tip as referenced to the workpiece surface remains nearly unchanged after tilting
- The TNC tilts the working plane at the last programmed feed rate. The maximum feed rate that can be reached depends on the complexity of the swivel head or tilting table.

If the axes are not positioned automatically in Cycle 19, position them before defining the cycle, for example with an L block.

Example NC blocks:

10 L Z+100 RO FMAX	
11 L X+25 Y+10 RO FMAX	
12 L B+15 RO F1000	Position the axis of rotation
13 CYCL DEF 19.0 WORKING PLANE	Define the angle for calculation of the compensation
14 CYCL DEF 19.1 B+15	

15 L Z+80 R0 FMAX

Activate compensation for the tool axis

16 L X-7.5 Y-10 R0 FMAX

Activate compensation for the working plane

### Position display in the tilted system

On activation of Cycle 19, the displayed positions (**ACTL** and **NOML**) and the datum indicated in the additional status display are referenced to the tilted coordinate system. The positions displayed immediately after cycle definition may not be the same as the coordinates of the last programmed position before Cycle 19.

### Workspace monitoring

The TNC monitors only those axes in the tilted coordinate system that are moved. If necessary, the TNC outputs an error message.

### Positioning in a tilted coordinate system

With the miscellaneous function M130 you can move the tool, while the coordinate system is tilted, to positions that are referenced to the non-tilted coordinate system see "Miscellaneous Functions for Coordinate Data," page 178.

Positioning movements with straight lines that are referenced to the machine coordinate system (blocks with M91 or M92), can also be executed in a tilted working plane. Constraints:

- Positioning is without length compensation.
- Positioning is without machine geometry compensation.
- Tool radius compensation is not permitted.

### Combining coordinate transformation cycles

When combining coordinate transformation cycles, always make sure the working plane is swiveled around the active datum. You can program a datum shift before activating Cycle 19. In this case, you are shifting the "machine-based coordinate system."

If you program a datum shift after having activated Cycle 19, you are shifting the "tilted coordinate system."

Important: When resetting the cycles, use the reverse sequence used for defining the them:

1. Activate the datum shift.

2nd: Activate tilting function.

3rd: Activate rotation.

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Machining

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1st: Reset the rotation.

2nd: Reset the tilting function.

3rd: Reset the datum shift.

### Automatic workpiece measurement in the tilted system

The TNC measuring cycles enable you to have the TNC measure a workpiece in a tilted system automatically. The TNC stores the measured data in Q parameters for further processing (for example, for printout).

### **Procedure for working with Cycle 19 WORKING PLANE**

### 1 Write the program

- ▶ Define the tool (not required, when TOOL.T is active), and enter the full tool length.
- Call the tool.
- ▶ Retract the tool in the tool axis to a position where there is no danger of collision with the workpiece (clamping devices) during tilting.
- ▶ If required, position the tilt axis or axes with an L block to the appropriate angular value(s) (depending on a machine parameter).
- Activate datum shift if required.
- ▶ Define Cycle 19 WORKING PLANE; enter the angular values for the tilt axes
- Traverse all main axes (X, Y, Z) to activate compensation.
- Write the program as if the machining process were to be executed in a non-tilted plane.
- ▶ If required, define Cycle 19 WORKING PLANE with other angular values to execute machining in a different axis position. In this case, it is not necessary to reset Cycle 19. You can define the new angular values directly.
- ▶ Reset Cycle 19 WORKING PLANE; program 0° for all tilt axes.
- Disable the WORKING PLANE function; redefine Cycle 19 and answer the dialog question with NO ENT.
- Reset datum shift if required.
- ▶ Position the tilt axes to the 0° position, if required.

### 2 Clamp the workpiece

# 3 Preparations in the operating mode Positioning with Manual Data Input (MDI)

Pre-position the tilt axis/axes to the corresponding angular value(s) for setting the datum. The angular value depends on the selected reference plane on the workpiece.

# 4 Preparations in the operating mode Manual Operation

Use the 3D-ROT soft key to set the function TILT WORKING PLANE to ACTIVE in the Manual Operation mode. Enter the angular values for the tilt axes into the menu if the axes are not controlled.

If the axes are not controlled, the angular values entered in the menu must correspond to the actual position(s) of the tilted axis or axes, respectively. The TNC will otherwise calculate a wrong datum.

#### 5 Set the datum

- Manually by touching the workpiece with the tool in the untilted coordinate system see "Datum Setting(Without a 3-D Touch Probe)," page 22
- Automatically by using a HEIDENHAIN 3-D touch probe (see the new Touch Probe Cycles Manual, chapter 2)
- Automatically by using a HEIDENHAIN 3-D touch probe (see the new Touch Probe Cycles Manual, chapter 3)

# 6 Start the part program in the operating mode Program Run, Full Sequence

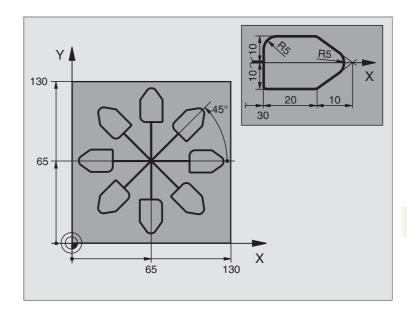
### 7 Manual Operation mode

Use the 3D-ROT soft key to set the function TILT WORKING PLANE to INACTIVE. Enter an angular value of 0° for each axis in the menu see "To activate manual tilting:," page 27.

## **Example: Coordinate transformation cycles**

## Program sequence

- Program the coordinate transformations in the main program
- For subprograms within a subprogram, see "Subprograms," page 343



O BEGIN PGM KOUMR MM	
1 BLK FORM 0.1 Z X+0 Y+0 Z-20	Define the workpiece blank
2 BLK FORM 0.2 X+130 Y+130 Z+0	
3 TOOL DEF 1 L+0 R+1	Define the tool
4 T00L CALL 1 Z S4500	Tool call
5 L Z+250 RO F MAX	Retract the tool
6 CYCL DEF 7.0 DATUM SHIFT	Shift datum to center
7 CYCL DEF 7.1 X+65	
8 CYCL DEF 7.2 Y+65	
9 CALL LBL 1	Call milling operation
10 LBL 10	Set label for program section repeat
11 CYCL DEF 10.0 DREHUNG	Rotate by 45° (incremental)
12 CYCL DEF 10.1 IROT+45	
13 CALL LBL 1	Call milling operation
14 CALL LBL 10 REP 6/6	Return jump to LBL 10; execute the milling operation six times
15 CYCL DEF 10.0 DREHUNG	Reset the rotation
16 CYCL DEF 10.1 ROT+0	
17 CYCL DEF 7.0 DATUM SHIFT	Reset the datum shift
18 CYCL DEF 7.1 X+0	
19 CYCL DEF 7.2 Y+0	

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20	L Z+250 RO F MAX M2	Retract in the tool axis, end program
21	LBL 1	Subprogram 1:
22	L X+O Y+O RO F MAX	Define milling operation
23	L Z+2 RO F MAX M3	
24	L Z-5 R0 F200	
25	L X+30 RL	
26	L IY+10	
27	RND R5	
28	L IX+20	
29	L IX+10 IY-10	
30	RND R5	
31	L IX-10 IY-10	
32	L IX-20	
33	L IY+10	
34	L X+0 Y+0 R0 F500	
35	L Z+20 RO F MAX	
36	LBL 0	
37	END PGM KOUMR MM	

## 8.9 Special Cycles

## **DWELL TIME (Cycle 9)**

This causes the execution of the next block within a running program to be delayed by the programmed dwell time. A dwell time can be used for such purposes as chip breaking.

#### **Effect**

Cycle 9 becomes effective as soon as it is defined in the program. Modal conditions such as spindle rotation are not affected.



▶ Dwell time in seconds: Enter the dwell time in seconds

Input range 0 to 3600 s (1 hour) in 0.001 s steps



#### **Example: NC blocks**

89 CYCL DEF 9.0 DWELL TIME

90 CYCL DEF 9.1 DWELL 1.5

## **PROGRAM CALL (Cycle 12)**

Routines that you have programmed (such as special drilling cycles or geometrical modules) can be written as main programs and then called like fixed cycles.



#### Before programming, note the following:

If the program you are defining to be a cycle is located in the same directory as the program you are calling it from, you need only to enter the program name.

If the program you are defining to be a cycle is not located in the same directory as the program you are calling it from, you must enter the complete path (for example TNC:\KLAR35\FK1\50.H.

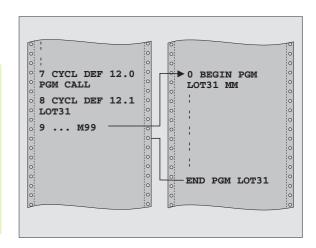
If you want to define an ISO program to be a cycle, enter the file type .I behind the program name.



▶ Program name: Enter the name of the program you want to call and, if necessary, the directory it is located in.

Call the program with

- CYCL CALL (separate block) or
- M99 (blockwise) or
- M89 (executed after every positioning block)



#### **Example: NC blocks**

55 CYCL DEF 12.0 PGM CALL

56 CYCL DEF 12.1 PGM TNC:\KLAR35\FK1\50.H

57 L X+20 Y+50 FMAX M99

#### **Example: Program call**

A callable program 50 is to be called into a program via a cycle call.

## **ORIENTED SPINDLE STOP (Cycle 13)**



Machine and control must be specially prepared by the machine tool builder for use of this cycle.



Cycle 13 is used internally for machining cycles 202, 204 and 209. Please note that, if required, you must program Cycle 13 again in your NC program after one of the machining cycles mentioned above.

The control can control the machine tool spindle and rotate it to a given angular position.

Oriented spindle stops are required for

- Tool changing systems with a defined tool change position
- Orientation of the transmitter/receiver window of HEIDENHAIN 3-D touch probes with infrared transmission

#### **Effect**

The angle of orientation defined in the cycle is positioned to by entering M19 or M20 (depending on the machine).

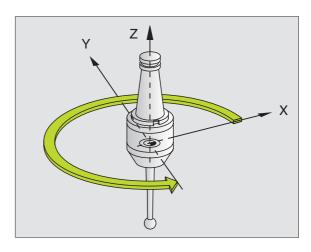
If you program M19 or M20 without having defined Cycle 13, the TNC positions the machine tool spindle to an angle that has been set in a machine parameter (see your machine manual).



▶ Angle of orientation: Enter the angle according to the reference axis of the working plane

Input range: 0 to 360°

Input resolution: 0.1°



**Example: NC blocks** 

93 CYCL DEF 13.0 ORIENTATION

94 CYCL DEF 13.1 ANGLE 180

## **TOLERANCE (Cycle 32)**



Machine and control must be specially prepared by the machine tool builder for use of this cycle.

The TNC automatically smoothens the contour between two path elements (whether compensated or not). The tool has constant contact with the workpiece surface. If necessary, the TNC automatically reduces the programmed feed rate so that the program can be machined at the fastest possible speed without short pauses for computing time. As a result the surface quality is improved and the machine is protected.

A contour deviation results from the smoothing out. The size of this deviation **(tolerance value)** is set in a machine parameter by the machine manufacturer. You can change the pre-set tolerance value with Cycle 32.



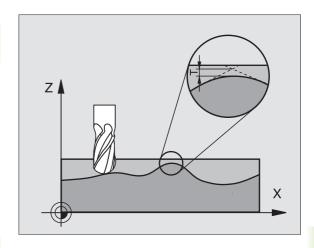
#### Before programming, note the following:

Cycle 32 is DEF active which means that it becomes effective as soon as it is defined in the part program.

You can reset Cycle 32 by defining it again and confirming the dialog question after the **tolerance value** with NO ENT. Resetting Cycle 32 reactivates the pre-set tolerance:



▶ Tolerance value: Permissible contour deviation in mm



**Example: NC blocks** 

95 CYCL DEF 32.0 TOLERANCE

96 CYCL DEF 32.1 TO.05





9

Programming: Subprograms and Program Section Repeats

# 9.1 Labeling Subprograms and Program Section Repeats

Subprograms and program section repeats enable you to program a machining sequence once and then run it as often as desired.

## Labels

The beginnings of subprograms and program section repeats are marked in a part program by labels.

A label is identified by a number between 1 and 254. Each label can be set only once with LABEL SET in a program.



If a label is set more than once, the TNC sends an error message at the end of the LBL SET block. With very long programs, you can limit the number of blocks to be checked for repeated labels with MP7229.

LABEL 0 (LBL 0) is used exclusively to mark the end of a subprogram and can therefore be used as often as desired.

## 9.2 Subprograms

## **Operating sequence**

- 1 The TNC executes the part program up to the block in which a subprogram is called with CALL LBL.
- **2** The subprogram is then executed from beginning to end. The subprogram end is marked LBL 0.
- **3** The TNC then resumes the part program from the block after the subprogram call.

## **Programming notes**

- A main program can contain up to 254 subprograms.
- You can call subprograms in any sequence and as often as desired.
- A subprogram cannot call itself.
- Write subprograms at the end of the main program (behind the block with M2 or M30).
- If subprograms are located before the block with M02 or M30, they will be executed at least once even if they are not called.

# CALL LBL1 L Z+100 M2 LBL1 2 LBL0 END PGM ...

## Programming a subprogram



- To mark the beginning, press the LBL SET key and enter a label number.
- Enter the subprogram number.
- To mark the end, press the LBL SET key and enter the label number "0".

## Calling a subprogram



- To call a subprogram, press the LBL CALL key.
- ▶ Label number: Enter the label number of the subprogram you wish to call.
- ▶ Repeat REP: Ignore the dialog question with the NO ENT key. Repeat REP is used only for program section repeats.



CALL LBL 0 is not permitted (label 0 is only used to mark the end of a subprogram).

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## 9.3 Program Section Repeats

## **Label LBL**

The beginning of a program section repeat is marked by the label LBL. The end of a program section repeat is identified by CALL LBL /REP.

## **Operating sequence**

- 1 The TNC executes the part program up to the end of the program section (CALL LBL /REP).
- 2 Then the program section between the called LBL and the label call is repeated the number of times entered after REP.
- 3 The TNC then resumes the part program after the last repetition.

## **Programming notes**

- You can repeat a program section up to 65 534 times in succession.
- The number behind the slash after REP indicates the number of repetitions remaining to be run.
- The total number of times the program section is executed is always one more than the programmed number of repeats.

## Programming a program section repeat

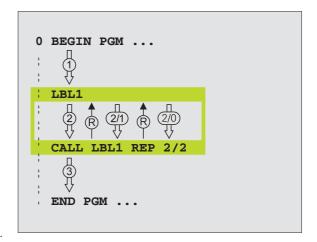


- To mark the beginning, press the LBL SET key and enter a LABEL NUMBER for the program section you wish to repeat.
- Enter the program section.

## Calling a program section repeat



▶ Press the LBL CALL key and enter the label number of the program section you want to repeat as well as the number of repeats (with Repeat REP).



# 9.4 Separate Program as Subprogram

## **Operating sequence**

- 1 The TNC executes the part program up to the block in which another program is called with CALL PGM.
- **2** Then the other program is run from beginning to end.
- **3** The TNC then resumes the first (calling) part program with the block behind the program call.

## **Programming notes**

- No labels are needed to call any program as a subprogram.
- The called program must not contain the miscellaneous functions M2 or M30.
- The called program must not contain a program call into the calling program, otherwise an infinite loop will result.

## Calling any program as a subprogram



▶ To select the functions for program call, press the PGM CALL key.



Press the PROGRAM soft key.

Enter the complete path name of the program you want to call and confirm your entry with the END key.



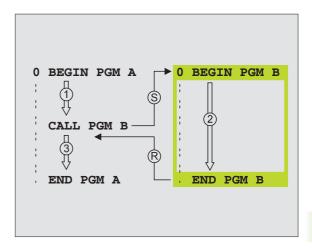
The program you are calling must be stored on the hard disk of your TNC.

You need only enter the program name if the program you want to call is located in the same directory as the program you are calling it from.

If the called program is not located in the same directory as the program you are calling it from, you must enter the complete path, e.g. TNC:\ZW35\ROUGH\PGM1.H

If you want to call an ISO program, enter the file type .I after the program name.

You can also call a program with Cycle 12 PGM CALL.



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## 9.5 Nesting

## Types of nesting

- Subprograms within a subprogram
- Program section repeats within a program section repeat
- Subprograms repeated
- Program section repeats within a subprogram

## **Nesting depth**

The nesting depth is the number of successive levels in which program sections or subprograms can call further program sections or subprograms.

- Maximum nesting depth for subprograms: 8
- Maximum nesting depth for calling main programs: 4
- You can nest program section repeats as often as desired

## Subprogram within a subprogram

## **Example NC blocks**

O BEGIN PGM SUBPGMS MM	
•••	
17 CALL LBL 1	Calling a subprogram at LBL 1
•••	
35 L Z+100 RO FMAX M2	Last program block of the
	main program (with M2)
36 LBL 1	Beginning of subprogram 1
•••	
39 CALL LBL 2	Call the subprogram marked with LBL2
•••	
45 LBL 0	End of subprogram 1
46 LBL 2	Beginning of subprogram 2
•••	
62 LBL 0	End of subprogram 2
63 END PGM SUBPGMS MM	

#### **Program execution**

- 1 Main program SUBPGMS is executed up to block 17.
- 2 Subprogram 1 is called, and executed up to block 39.
- **3** Subprogram 2 is called, and executed up to block 62. End of subprogram 2 and return jump to the subprogram from which it was called.
- **4** Subprogram 1 is executed from block 40 up to block 45. End of subprogram 1 and return jump to the main program SUBPGMS.
- **5** Main program SUBPGMS is executed from block 18 up to block 35. Return jump to block 1 and end of program.

## Repeating program section repeats

#### **Example NC blocks**

O BEGIN PGM REPS MM	
•••	
15 LBL 1	Beginning of program section repeat 1
•••	
20 LBL 2	Beginning of program section repeat 2
•••	
27 CALL LBL 2 REP 2/2	The program section between this block and LBL 2
•••	(block 20) is repeated twice
35 CALL LBL 1 REP 1/1	The program section between this block and LBL 1
•••	(block 15) is repeated once.
50 END PGM REPS MM	

#### **Program execution**

- 1 Main program REPS is executed up to block 27.
- 2 Program section between block 27 and block 20 is repeated twice.
- 3 Main program REPS is executed from block 28 to block 35.
- **4** Program section between block 35 and block 15 is repeated once (including the program section repeat between 20 and block 27).
- **5** Main program REPS is executed from block 36 to block 50 (end of program).



## Repeating a subprogram

## **Example NC blocks**

O BEGIN PGM SUBREP MM	
•••	
10 LBL 1	Beginning of program section repeat 1
11 CALL LBL 2	Subprogram call
12 CALL LBL 1 REP 2/2	The program section between this block and LBL1
•••	(block 10) is repeated twice
19 L Z+100 RO FMAX M2	Last block of the main program with M2
20 LBL 2	Beginning of subprogram
•••	
28 LBL 0	End of subprogram
29 END PGM SUBREP MM	

## **Program execution**

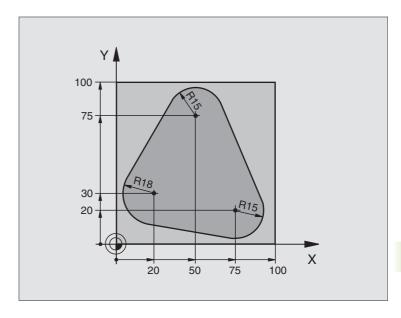
- 1 Main program SUBREP is executed up to block 11.
- 2 Subprogram 2 is called and executed.
- **3** Program section between block 12 and block 10 is repeated twice. This means that subprogram 2 is repeated twice.
- **4** Main program UPGREP is executed from block 13 to block 19. End of program.



## **Example: Milling a contour in several infeeds**

## Program sequence

- Pre-position the tool to the workpiece surface
- Enter the infeed depth in incremental values
- Mill the contour
- Repeat downfeed and contour-milling



O BEGIN PGM PGMWDH MM	
1 BLK FORM 0.1 Z X+0 Y+0 Z-40	
2 BLK FORM 0.2 X+100 Y+100 Z+0	
3 TOOL DEF 1 L+0 R+10	Define the tool
4 TOOL CALL 1 Z S500	Tool call
5 L Z+250 RO F MAX	Retract the tool
6 L X-20 Y+30 RO F MAX	Pre-position in the working plane
7 L Z+O RO F MAX M3	Pre-position to the workpiece surface

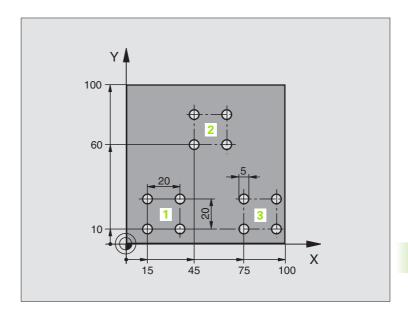
i

8 LBL 1	Set label for program section repeat	
9 L IZ-4 RO F MAX	Infeed depth in incremental values (in the open)	
10 APPR CT X+2 Y+30 CCA90 R+5 RL F250	Approach contour	
11 FC DR- R18 CLSD+ CCX+20 CCY+30	Contour	
12 FLT		
13 FCT DR- R15 CCX+50 CCY+75		
14 FLT		
15 FCT DR- R15 CCX+75 CCY+20		
16 FLT		
17 FCT DR- R18 CLSD- CCX+20 CCY+30		
18 DEP CT CCA90 R+5 F1000	Depart contour	
19 L X-20 Y+0 RO F MAX	Retract tool	
20 CALL LBL 1 REP 4/4	Return jump to LBL 1; section is repeated a total of 4 times.	
21 L Z+250 RO F MAX M2	Retract in the tool axis, end program	
22 END PGM PGMWDH MM		

## **Example: Groups of holes**

## Program sequence

- Approach the groups of holes in the main program
- Call the group of holes (subprogram 1)
- Program the group of holes only once in subprogram 1



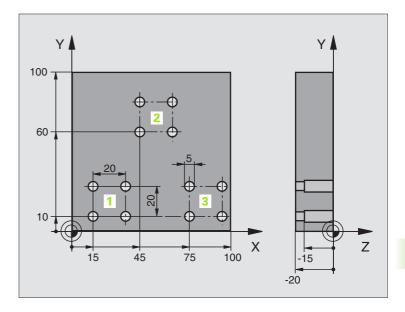
O BEGIN PGM UP1 MM	
1 BLK FORM 0.1 Z X+0 Y+0 Z-20	
2 BLK FORM 0.2 X+100 Y+100 Z+0	
3 TOOL DEF 1 L+0 R+2.5	Define the tool
4 TOOL CALL 1 Z S5000	Tool call
5 L Z+250 RO F MAX	Retract the tool
6 CYCL DEF 200 DRILLING	Cycle definition: drilling
Q200=2; SET-UP CLEARANCE	
Q201=-10; DEPTH	
Q206=250; FEED RATE FOR PLNGNG	
Q202=5; PLUNGING DEPTH	
Q210=0; DWELL TIME AT TOP	
Q203=+0; SURFACE COORDINATE	
Q204=10; 2ND SET-UP CLEARANCE	
Q211=0.25; DWELL TIME AT BOTTOM	

7 L X+15 Y+10 RO F MAX M3	Move to starting point for group 1	
8 CALL LBL 1	Call the subprogram for the group	
9 L X+45 Y+60 RO F MAX	Move to starting point for group 2	
10 CALL LBL 1	Call the subprogram for the group	
11 L X+75 Y+10 RO F MAX	Move to starting point for group 3	
12 CALL LBL 1	Call the subprogram for the group	
13 L Z+250 RO F MAX M2	End of main program	
14 LBL 1	Beginning of subprogram 1: Group of holes	
15 CYCL CALL	Hole 1	
16 L IX+20 RO F MAX M99	Move to 2nd hole, call cycle	
17 L IY+20 RO F MAX M99	Move to 3rd hole, call cycle	
18 L IX-20 RO F MAX M99	Move to 4th hole, call cycle	
19 LBL 0	End of subprogram 1	
20 END PGM UP1 MM		

## **Example: Groups of holes with several tools**

## Program sequence

- Program the fixed cycles in the main program
- Call the entire hole pattern (subprogram 1)
- Approach the groups of holes in subprogram 1, call group of holes (subprogram 2)
- Program the group of holes only once in subprogram 2



O BEGIN PGM UP2 MM	
1 BLK FORM 0.1 Z X+0 Y+0 Z-20	
2 BLK FORM 0.2 X+100 Y+100 Z+0	
3 TOOL DEF 1 L+0 R+4	Define tool: center drill
4 TOOL DEF 2 L+0 R+3	Define tool: drill
5 TOOL DEF 3 L+0 R+3.5	Define tool: reamer
6 TOOL CALL 1 Z S5000	Call tool: center drill
7 L Z+250 RO F MAX	Retract the tool
8 CYCL DEF 200 DRILLING	Cycle definition: Centering
Q200=2; SET-UP CLEARANCE	
Q201=-3; DEPTH	
Q206=250; FEED RATE FOR PLNGNG	
Q202=3; PLUNGING DEPTH	
Q210=0; DWELL TIME AT TOP	
Q203=+0; SURFACE COORDINATE	
Q204=10; 2ND SET-UP CLEARANCE	
Q211=0.25; DWELL TIME AT BOTTOM	
9 CALL LBL 1	Call subprogram 1 for the entire hole pattern

i

10 L Z+250 RO F MAX M6	Tool change
11 TOOL CALL 2 Z S4000	Call the drilling tool
12 FN 0: Q201 = -25	New depth for drilling
13 FN 0: Q202 = +5	New plunging depth for drilling
14 CALL LBL 1	Call subprogram 1 for the entire hole pattern
15 L Z+250 RO F MAX M6	Tool change
16 TOOL CALL 3 Z S500	Tool call: reamer
17 CYCL DEF 201 REAMING	Cycle definition: REAMING
Q200=2; SET-UP CLEARANCE	
Q201=-15; DEPTH	
Q206-250; FEED RATE FOR PLNGNG	
Q211=0.5; DWELL TIME AT DEPTH	
Q208=400; RETRACTION FEED RATE	
Q203=+0; SURFACE COORDINATE	
Q204=10; 2ND SET-UP CLEARANCE	
18 CALL LBL 1	Call subprogram 1 for the entire hole pattern
19 L Z+250 RO F MAX M2	End of main program
20 LBL 1	Beginning of subprogram 1: Entire hole pattern
21 L X+15 Y+10 RO F MAX M3	Move to starting point for group 1
22 CALL LBL 2	Call subprogram 2 for the group
23 L X+45 Y+60 RO F MAX	Move to starting point for group 2
24 CALL LBL 2	Call subprogram 2 for the group
25 L X+75 Y+10 RO F MAX	Move to starting point for group 3
26 CALL LBL 2	Call subprogram 2 for the group
27 LBL 0	End of subprogram 1
28 LBL 2	Beginning of subprogram 2: Group of holes
29 CYCL CALL	1st hole with active fixed cycle
30 L IX+20 RO F MAX M99	Move to 2nd hole, call cycle
31 L IY+20 RO F MAX M99	Move to 3rd hole, call cycle
32 L IX-20 RO F MAX M99	Move to 4th hole, call cycle
33 LBL 0	End of subprogram 2
34 END PGM UP2 MM	







**Programming: Q Parameters** 

## 10.1 Principle and Overview

You can program an entire family of parts in a single part program. You do this by entering variables called Q parameters instead of fixed numerical values.

Q parameters can represent information such as:

- Coordinate values
- Feed rates
- RPM
- Cycle data

 $\Omega$  parameters also enable you to program contours that are defined through mathematical functions. You can also use  $\Omega$  parameters to make the execution of machining steps depend on logical conditions. In conjunction with FK programming you can also combine contours that do not have NC-compatible dimensions with  $\Omega$  parameters.

Q parameters are designated by the letter Q and a number between 0 and 299. They are grouped according to three ranges:

Meaning	Range
Freely applicable parameter, global for all programs in the TNC memory	Q0 to Q99
Parameters for special TNC functions	Q100 to Q199
Parameters that are primarily used for cycles, globally effective for all programs that are stored in the TNC memory	Q200 to Q399

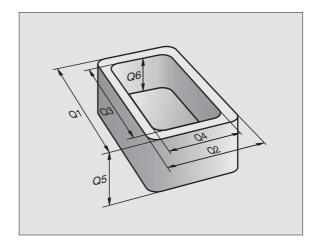
## **Programming notes**

You can mix  $\ensuremath{\Omega}$  parameters and fixed numerical values within a program.

Q parameters can be assigned numerical values between -99 999.9999 and +99 999.9999. Internally, the TNC can calculate up to a width of 57 bits before and 7 bits after the decimal point (32-bit data width corresponds to a decimal value of 4 294 967 296).



Some Q parameters are always assigned the same data by the TNC. For example, Q108 is always assigned the current tool radius, see "Preassigned Q Parameters," page 386. If you are using the parameters Q60 to Q99 in OEM cycles, define via MP7251 whether the parameters are only to be used locally in the OEM cycles, or may be used globally.



## Calling Q parameter functions

When you are writing a part program, press the "Q" key (in the keypad for numerical input, below the -/+ key). The TNC then displays the following soft keys:

Function group	Soft key
Basic arithmetic (assign, add, subtract, multiply, divide, square root)	BASIC ARITHM.
Trigonometric functions	TRIGO- NOMETRY
Function for calculating circles	CIRCLE CALCU- LATION
If/then conditions, jumps	JUMP
Other functions	DIVERSE FUNCTION
Entering formulas directly	FORMULA

# 10.2 Part Families – Q Parameters in Place of Numerical Values

The Q parameter function FN0: ASSIGN assigns numerical values to Q parameters. This enables you to use variables in the program instead of fixed numerical values.

## **Example NC blocks**

15 FNO: Q10=25	Assign
•••	Q10 contains the value 25
25 L X +Q10	Means L X +25

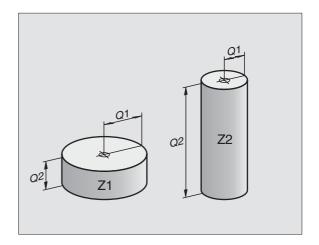
You need write only one program for a whole family of parts, entering the characteristic dimensions as Q parameters.

To program a particular part, you then assign the appropriate values to the individual Q parameters.

## **Example**

Cylinder with Q parameters

Cylinder radius	R = Q1
Cylinder height	H = Q2
Cylinder Z1	Q1 = +30
	Q2 = +10
Cylinder Z2	Q1 = +10
	Q2 = +50



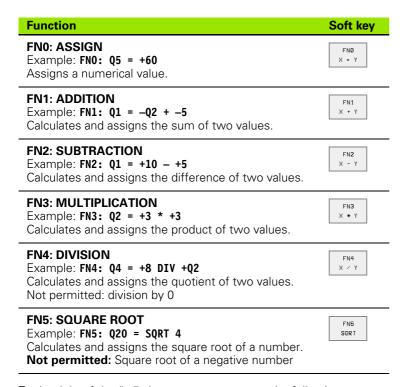
## 10.3 Describing Contours through **Mathematical Operations**

#### **Function**

The Q parameters listed below enable you to program basic mathematical functions in a part program:

- ▶ Select a Q parameter function: Press the Q key (in the numerical keypad at right). The Q parameter functions are displayed in a softkey row.
- ▶ To select the mathematical functions: Press the BASIC ARITHMETIC The TNC then displays the following soft keys:

#### Overview



To the right of the "=" character you can enter the following:

- Two numbers
- Two Q parameters
- A number and a Q parameter

The Q parameters and numerical values in the equations can be entered with positive or negative signs.

## **Programming fundamental operations**

Example:



To select Q parameter functions, press the Q key.



To select the mathematical functions: Press the BASIC ARITHMETIC soft key.



To select the Q parameter function ASSIGN, press the FN0 X = Y soft key.

#### Parameter number for result?

5 ENT

Enter the number of the Q parameter: 5

#### 1. value or parameter ?

10



Assign the value 10 to Q5.

Q

To select Q parameter functions, press the Q key.

BASIC ARITHM. To select the mathematical functions: Press the BASIC ARITHMETIC soft key.

FN3 X \* Y To select the Q parameter function MULTIPLICATION, press the FN3 X \* Y soft key.

#### Parameter number for result?

12



Enter the number of the Q parameter: 12

#### 1. value or parameter ?

Q5



Enter Q5 for the first value.

#### 2. value or parameter ?

7



Enter 7 for the second value.

#### **Example: Program blocks in the TNC**

16 FNO: Q5 = +10

17 FN3: Q12 = +Q5 \* +7



## 10.4 Trigonometric Functions

## **Definitions**

Sine, cosine and tangent are terms designating the ratios of sides of right triangles. For a right triangle, the trigonometric functions of the angle a are defined by the following equations:

Sine:  $\sin \alpha = a/c$ Cosine:  $\cos \alpha = b/c$ 

**Tangent:**  $\tan \alpha = a / b = \sin \alpha / \cos \alpha$ 

where

c is the side opposite the right angle

a is the side opposite the angle a

■ b is the third side.

The TNC can find the angle from the tangent:

 $\alpha$  = arc tan (a / b) = arc tan (sin  $\alpha$  / cos  $\alpha$ )

## Example:

 $a = 25 \, \text{mm}$ 

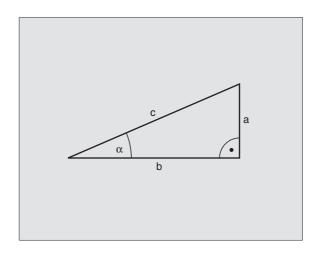
b = 50 mm

 $\alpha$  = arc tan (a / b) = arc tan 0.5 = 26.57°

Furthermore:

 $a^{2} + b^{2} = c^{2}$  (where  $a^{2} = a \times a$ )

$$C = \sqrt{(a^2 + b^2)}$$



## **Programming trigonometric functions**

Press the TRIGONOMETRY soft key to call the trigonometric functions. The TNC then displays the soft keys that are listed in the table below.

Programming: Compare "Example: Programming fundamental operations."

Function	Soft key
FN6: SINE Example: FN6: Q20 = SIN-Q5 Calculate the sine of an angle in degrees (°) and assign it to a parameter.	FN6 SIN(X)
FN7: COSINE Example: FN7: Q21 = COS-Q5 Calculate the cosine of an angle in degrees (°) and assign it to a parameter.	FN7 COS(X)
FN8: ROOT SUM OF SQUARES  Example: FN8: Q10 = +5 LEN +4  Calculate and assign length from two values.	FN8 X LEN Y
FN13: ANGLE Example: FN13: Q20 = +25 ANG-Q1 Calculate the angle from the arc tangent of two sides or from the sine and cosine of the angle (0 < angle < 360°) and assign it to a parameter.	FN13 X RNG Y

## 10.5 Calculating Circles

#### **Function**

The TNC can use the functions for calculating circles to calculate the circle center and the circle radius from three or four given points on the circle. The calculation is more accurate if four points are used.

Application: These functions can be used if you wish to determine the location and size of a bore hole or a pitch circle using the programmable probing function.

#### Function Soft key

FN23: Determining the CIRCLE DATA from three

points

Example: FN23: Q20 = CDATA Q30



The coordinate pairs for three points of the circle must be stored in Parameter Q30 and in the following five parameters – here to Q35.

The TNC then stores the circle center of the reference axis (X with spindle axis Z) in Parameter Q20, the circle center of the minor axis (Y with spindle axis Z) in Parameter Q21 and the circle radius in Parameter Q22.

#### Function Soft kev

FN24: Determining the CIRCLE DATA from four

points

Example: FN24: Q20 = CDATA Q30



The coordinate pairs for four points of the circle must be stored in Parameter Q30 and in the following seven parameters – here to Q37.

The TNC then stores the circle center of the reference axis (X with spindle axis Z) in Parameter Q20, the circle center of the minor axis (Y with spindle axis Z) in Parameter Q21 and the circle radius in Parameter Q22.



Note that FN23 and FN24 beside the resulting parameter also overwrite the two following parameters.

# 10.6 If-Then Decisions with Q Parameters

## **Function**

The TNC can make logical If-Then decisions by comparing a Q parameter with another Q parameter or with a numerical value. If the condition is fulfilled, the TNC continues the program at the label that is programmed after the condition (for information on labels, see "Labeling Subprograms and Program Section Repeats," page 342). If it is not fulfilled, the TNC continues with the next block.

To call another program as a subprogram, enter PGM CALL after the block with the target label.

## **Unconditional jumps**

An unconditional jump is programmed by entering a conditional jump whose condition is always true. Example:

FN9: IF+10 EQU+10 GOTO LBL1

## **Programming If-Then decisions**

Press the JUMP soft key to call the if-then conditions. The TNC then displays the following soft keys:

Function	Soft key
FN9: IF EQUAL, JUMP Example: FN9: IF +Q1 EQU +Q3 GOTO LBL 5 If the two values or parameters are equal, jump to the given label.	FN9 IF X EQ Y GOTO
FN10: IF NOT EQUAL, JUMP Example: FN10: IF +10 NE -Q5 G0T0 LBL 10 If the two values or parameters are not equal, jump to the given label.	FN10 IF X NE Y GOTO
FN11: IF GREATER THAN, JUMP  Example: FN11: IF+Q1 GT+10 G0T0 LBL 5  If the first parameter or value is greater than the second value or parameter, jump to the given label.	FN11 IF X GT Y GOTO
FN12: IF LESS THAN, JUMP Example: FN12: IF+Q5 LT+0 GOTO LBL 1 If the first value or parameter is less than the second value or parameter, jump to the given label.	FN12 IF X LT Y GOTO

## **Abbreviations used:**

**IF** : If

EQU : EqualsNE : Not equalGT : Greater thanLT : Less thanGOTO : Go to

# 10.7 Checking and changing Q parameters

## **Procedure**

During a program run or test run, you can check or change Q parameters if necessary.

▶ If you are in a program run, interrupt it (for example by pressing the machine STOP button and the INTERNAL STOP soft key). If you are doing a test run, interrupt it.



- To call the Q parameter functions, press the Q key.
- ► Enter the Q parameter number and press the ENT key. The TNC displays the current value of the Q parameter in the dialog line.
- If you wish to change the value, enter a new value, confirm it with the ENT key and conclude your entry with the END key.
- To leave the value unchanged, terminate the dialog with the END key.

```
Manua 1
       Test run
operation
       Q25 = +23.35
   TOOL CALL 1 Z
   L Z+250 R0 F MAX
   L X-20 Y+30 R0 F MAX
   L Z-10 R0 F1000 M3
   APPR CT X+2 Y+30 CCA90 R+5 RL F250
   FC DR- R18 CLSD+ CCX+20 CCY+30
   FLT
10
   FCT DR- R15 CCX+50 CCY+75
    FLT
11
12
    FCT DR- R15 CCX+75 CCY+20
13
    FLT
    FCT DR- R18 CLSD- CCX+20 CCY+30
14
15
    DEP CT CCA90 R+5 F1000
16
    L X-30 Y+0 R0 F MAX
17
    CYCL DEF 262 THREAD MILLING
                                     END
```

## 10.8 Additional Functions

## **Overview**

Press the DIVERSE FUNCTION soft key to call the additional functions. The TNC then displays the following soft keys:

Function	Soft key
FN14:ERROR Output error messages	FN14 ERROR=
FN15:PRINT Unformatted output of texts or Q parameter values	FN15 PRINT
FN16:PRINT Formatted output of texts or Q parameter values	FN16 F-PRINT
FN18:SYS-DATUM READ Read system data	FN18 SYS-DATUM READ
FN19:PLC Transfer values to the PLC	FN19 PLC=
FN20:WAIT FOR Synchronize NC and PLC	FN20 WAIT FOR
FN25:PRESET Set datum during program run	FN25 SET DATUM
FN26:TABOPEN Open a freely definable table	FN26 OPEN TABLE
FN27:TABWRITE Write to a freely definable table	FN27 URITE TO TABLE
FN28:TABREAD Read from a freely definable table	FN28 READ FROM TABLE

## FN14: ERROR: Displaying error messages

With the function FN14: ERROR you can call messages under program control. The messages were preprogrammed by the machine tool builder or by HEIDENHAIN. The program must then be restarted. The error number are listed in the table below.

Range of error numbers	Standard dialog text
0 299	FN 14: Error code 0 299
300 999	Machine-dependent dialog
1000 1099	Internal error messages (see table at right)

## **Example NC block**

The TNC is to display the text stored under error number 254:

180 FN14: ERROR = 254

Error number	Text
1000	Spindle ?
1001	Tool axis is missing
1002	Slot width too large
1003	Tool radius too large
1004	Range exceeded
1005	Start position incorrect
1006	ROTATION not permitted
1007	SCALING FACTOR not permitted
1008	MIRRORING not permitted
1009	Datum shift not permitted
1010	Feed rate is missing
1011	Entry value incorrect
1012	Wrong sign programmed
1013	Entered angle not permitted
1014	Touch point inaccessible
1015	Too many points
1016	Contradictory entry
1017	CYCL incomplete
1018	Plane wrongly defined
1019	Wrong axis programmed
1020	Wrong RPM
1021	Radius comp. undefined
1022	Rounding-off undefined
1023	Rounding radius too large
1024	Program start undefined
1025	Excessive subprogramming
1026	Angle reference missing
1027	No fixed cycle defined
1028	Slot width too small
1029	Pocket too small
1030	Q202 not defined
1031	Q205 not defined
1032	Enter Q218 greater than Q219
1033	CYCL 210 not permitted
1034	CYCL 211 not permitted
1035	Q220 too large
1036	Enter Q222 greater than Q223
1037	Q244 must be greater than 0
1038	Q245 must not equal Q246
1039	Angle range must be < 360°
1040	Enter Q223 greater than Q222
1041	Q214: 0 not permitted

Error number	Text
1042	Traverse direction not defined
1043	No datum table active
1044	Position error: center in axis 1
1045	Position error: center in axis 2
1046	Hole diameter too small
1047	Hole diameter too large
1048	Stud diameter too small
1049	Stud diameter too large
1050	Pocket too small: rework axis 1
1051	Pocket too small: rework axis 2
1052	Pocket too large: scrap axis 1
1053	Pocket too large: scrap axis 2
1054	Stud too small: scrap axis 1
1055	Stud too small: scrap axis 2
1056	Stud too large: rework axis 1
1057	Stud too large: rework axis 2
1058	TCHPROBE 425: length exceeds max
1059	TCHPROBE 425: length below min
1060	TCHPROBE 426: length exceeds max
1061	TCHPROBE 426: length below min
1062	TCHPROBE 430: diameter too large
1063	TCHPROBE 430: diameter too small
1064	No measuring axis defined
1065	Tool breakage tolerance exceeded
1066	Enter Q247 unequal 0
1067	Enter Q247 greater than 5
1068	Datum table?
1069	Enter direction Q351 unequal 0
1070	Thread depth too large
1071	Missing calibration data
1072	Tolerance exceeded
1073	Block scan active
1074	ORIENTATION not permitted
1075	3DROT not permitted
1076	Activate 3DROT
1077	Enter depth as a negative value

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## FN15: PRINT: Output of texts or Q parameter values



Setting the data interface: In the menu option PRINT or PRINT-TEST, you must enter the path for storing the texts or Q parameters. See "Assign," page 423.

The function FN15: PRINT transfers Q parameter values and error messages through the data interface, for example to a printer. When you save the data in the TNC memory or transfer them to a PC, the TNC stores the data in the file %FN 15RUN.A (output in program run mode) or in the file %FN15SIM.A (output in test run mode).

## To output dialog texts and error messages with FN 15: PRINT "numerical value"

Numerical values from 0 to 99: Dialog texts for OEM cycles Numerical values exceeding 100: PLC error messages

Example: Output of dialog text 20

67 FN15: PRINT 20

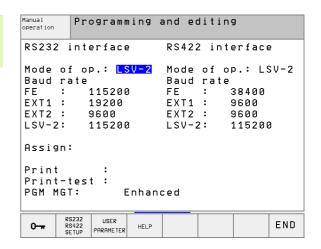
## Outputting dialog texts and Q parameters with FN15: PRINT "Q parameter"

Application example: Recording workpiece measurement.

You can transfer up to six Q parameters and numerical values simultaneously. The TNC separates them with slashes.

Example: Output of dialog text 1 and numerical value for Q1

70 FN15: PRINT1/Q1



# FN16: F-PRINT: Formatted output of texts or Q parameter values



Setting the data interface: In the menu option PRINT or PRINT-TEST, you must enter the path for storing the text file. See "Assign," page 423.

The function FN16: F-PRINT transfers Q parameter values and texts in a selectable format through the data interface, for example to a printer. If you save the values internally or send them to a computer, the TNC saves the data in the file that you defined in the FN 16 block.

To output the formatted texts and  $\Omega$  parameter values, create a text file with the TNC's text editor. In this file, you then define the output format and  $\Omega$  parameters you want to output.

Example of a text file to define the output format:

When you create a text file, use the following formatting functions:

Special character	Function
""	Define output format for texts and variables between the quotation marks
%5.3LF	Define format for Q parameter: 5 places before and 4 places behind the decimal point; long, floating (decimal number)
%S	Format for text variable
,	Separation character between output format and parameter
;	End of block character

The following functions allow you to include the following additional information in the protocol log file:

Code word	Function
CALL_PATH	Gives the path for the NC program where you will find the FN16 function. Example: "Measuring program: %S",CALL_PATH;
M_CLOSE	Closes the file to which you are writing with FN16. Example: M_CLOSE;
L_ENGLISH	Output text only for English conversational language
L_GERMAN	Output text only for German conversational language
L_CZECH	Output text only for Czech conversational language
L_FRENCH	Output text only for French conversational language
L_ITALIAN	Output text only for Italian conversational language
L_SPANISH	Output text only for Spanish conversational language
L_SWEDISH	Output text only for Swedish conversational language
L_DANISH	Output text only for Danish conversational language
L_FINNISH	Output text only for Finnish conversational language
L_DUTCH	Output text only for Dutch conversational language
L_POLISH	Output text only for Polish conversational language
L_HUNGARIA	Output text only for Hungarian conversational language
L_ALL	Output text independent of the conversational language
HOUR	Number of hours from the real-time clock
MIN	Number of minutes from the real-time clock
SEC	Number of seconds from the real-time clock
DAY	Day from the real-time clock
MONTH	Month as a number from the real-time clock
STR_MONTH	Month as a string abbreviation from the real-time clock
YEAR2	Two-digit year from the real-time clock
YEAR4	Four-digit year from the real-time clock

## In the part program, program FN 16: F-PRINT, to activate the output:

#### 96 FN16: F-PRINT TNC:\MASKE\MASKE1.A/RS232:\PROT1.TXT

The TNC then outputs the file PROT1.TXT through the serial interface:

CALIBRAT. CHART IMPELLER CENTER GRAVITY

NO. OF MEASURED VALUES : = 1

\*\*\*\*\*\*\*\*\*\*

X1 = 149.360

Y1 = 25.509

Z1 = 37.000



If you use FN 16 several times in the program, the TNC saves all texts in the file that you have defined with the first FN 16 function. The file is not output until the TNC reads the END PGM block, or you press the NC stop button, or you close the file with M\_CLOSE.

#### FN18: SYS-DATUM READ Read system data

With the function FN 18: SYS-DATUM READ you can read system data and store them in Q parameters. You select the system data through a group number (ID number), and additionally through a number and an index.

Number	Index	Meaning
1	-	MM/inch condition
2	-	Overlap factor for pocket milling
3	-	Number of active fixed cycle
1	-	Active tool number
2	-	Prepared tool number
3	-	Active tool axis 0=X, 1=Y, 2=Z, 6=U, 7=V, 8=W
4	-	Programmed spindle rpm
5	-	Active spindle status: -1=undefined, 0=M3 active, 1=M4 active, 2=M5 after M3, 3=M5 after M4
8	-	Coolant status: 0=off, 1=on
9	-	Active feed rate
10	-	Index of the prepared tool
	1 2 3 1 2 3 4 5 8 9	1 - 2 - 3 - 1 - 2 - 3 - 4 - 5 - 8 - 9

Group name, ID No.	Number	Index	Meaning
	11	-	Index of the active tool
Cycle parameter, 30	1	-	Setup clearance of active fixed cycle
	2	-	Drilling depth / milling depth of active fixed cycle
	3	-	Plunging depth of active fixed cycle
	4	-	Feed rate for pecking in active fixed cycle
	5	-	1st side length for rectangular pocket cycle
	6	-	2nd side length for rectangular pocket cycle
	7	-	1st side length for slot cycle
	8	-	2nd side length for slot cycle
	9	-	Radius for circular pocket cycle
	10	-	Feed rate for milling in active fixed cycle
	11	-	Direction of rotation for active fixed cycle
	12	-	Dwell time for active fixed cycle
	13	-	Thread pitch for Cycles 17, 18
	14	-	Milling allowance for active fixed cycle
	15	-	Direction angle for rough out in active fixed cycle
Data from the tool table, 50	1	Tool no.	Tool length
	2	Tool no.	Tool radius
	3	Tool no.	Tool radius R2
	4	Tool no.	Oversize for tool length DL
	5	Tool no.	Oversize for tool radius DR
	6	Tool no.	Oversize for tool radius DR2
	7	Tool no.	Tool inhibited (0 or 1)
	8	Tool no.	Number of replacement tool
	9	Tool no.	Maximum tool age TIME1
	10	Tool no.	Maximum tool age TIME2
	11	Tool no.	Current tool age CUR. TIME
	12	Tool no.	PLC status
	13	Tool no.	Maximum tooth length LCUTS



Group name, ID No.	Number	Index	Meaning
	14	Tool no.	Maximum plunge angle ANGLE
	15	Tool no.	TT: Number of teeth CUT
	16	Tool no.	TT: Wear tolerance for length LTOL
	17	Tool no.	TT: Wear tolerance for radius RTOL
	18	Tool no.	TT: Rotational direction DIRECT (0=positive/-1=negative)
	19	Tool no.	TT: Offset for radius R-OFFS
	20	Tool no.	TT: Offset for length L-OFFS
	21	Tool no.	TT: Breakage tolerance in length LBREAK
	22	Tool no.	TT: Breakage tolerance in radius RBREAK
	No index: [	Data of the cu	rrently active tool
Data from the tool table, 51	1	Pocket number	Tool number
	2	Pocket number	Special tool: 0=no, 1=yes
	3	Pocket number	Fixed pocket: 0=no, 1=yes
	4	Pocket number	Locket pocket: 0=no, 1=yes
	5	Pocket number	PLC status
Pocket number of a tool in the tool- pocket table, 52	1	Tool no.	Pocket number
Immediately after TOOL CALL programmed position, 70	1	-	Position valid / invalid (1/0)
	2	1	X axis
	2	2	Y axis
	2	3	Z axis
	3	-	Programmed feed rate (-1: no feed rate programmed)
Active tool compensation, 200	1	-	Tool radius (including delta values)
	2	-	Tool length (including delta values)
Active transformations, 210	1	-	Basic rotation in MANUAL OPERATION mode
_	2	-	Programmed rotation with Cycle 10
_	3	-	Active mirror axis

Group name, ID No.	Number	Index	Meaning
			0: mirroring not active
			+1: X axis mirrored
			+2: Y axis mirrored
			+4: Z axis mirrored
			+64: U axis mirrored
			+128: V axis mirrored
			+256: W axis mirrored
			Combinations = sum of individual axes
	4	1	Active scaling factor in X axis
	4	2	Active scaling factor in Y axis
	4	3	Active scaling factor in Z axis
	4	7	Active scaling factor in U axis
	4	8	Active scaling factor in V axis
	4	9	Active scaling factor in W axis
	5	1	3D ROT A axis
	5	2	3D ROT B axis
	5	3	3D ROT C axis
	6	-	Tilted working plane active / inactive (-1/0)
Active datum shift, 220	2	1	X axis
		2	Y axis
		3	Z axis
		4	A axis
		5	B axis
		6	C axis
		7	U axis
		8	V axis
		9	W axis
Traverse range, 230	2	1 to 9	Negative software limit switch in axes 1 to 9
	3	1 to 9	Positive software limit switch in axes 1 to 9



Group name, ID No.	Number	Index	Meaning
Nominal position in the REF system, 240	1	1	X axis
		2	Y axis
		3	Z axis
		4	A axis
		5	B axis
		6	C axis
		7	U axis
		8	V axis
		9	W axis
Nominal positions in the input system, 270	1	1	X axis
		2	Y axis
		3	Z axis
		4	A axis
		5	B axis
		6	C axis
		7	U axis
		8	V axis
		9	W axis
Status of M128, 280	1	-	0: M128 inactive, -1: M128 active
	2	-	Feed rate that was programmed with M128
Triggering touch probe, 350	10	-	Touch probe axis
	11	-	Effective ball radius
	12	-	Effective length
	13	-	Radius setting ring
	14	1	Center misalignment in ref. axis
		2	Center misalignment in minor axis
	15	-	Direction of center misalignment compared with 0° position
Tool touch probe 130	20	1	Center point X-axis (REF system)

Group name, ID No.	Number	Index	Meaning
		2	Center point Y-axis (REF system)
		3	Center point Z axis (REF system)
	21	-	Probe contact radius
Measuring touch probe, 350	30	-	Calibrated stylus length
	31	-	Stylus radius 1
	32	-	Stylus radius 2
	33	-	Setting ring diameter
	34	1	Center misalignment in ref. axis
		2	Center misalignment in minor axis
	35	1	Compensation factor for 1st axis
		2	Compensation factor for 2nd axis
		3	Compensation factor for 3rd axis
	36	1	Power ratio for 1st axis
		2	Power ratio for 2nd axis
		3	Power ratio for 3rd axis
Last touch point in TCH PROBE- cycle 0 or last touch point from manual operating mode, 360	1	1 to 9	Position in the active coordinate system in axes 1 to 9
	2	1 to 9	Position in the REF system in axes 1 to 9
Value from the active datum table in the active coordinate system, 500	Datum number	1 to 9	X axis to W axis
REF value from the active datum table, 500	Datum number	1 to 9	X axis to W axis
Datum table selected, 505	1	-	Acknowledgement value = 0: No datum table active Return code = 1: Datum table active
Data from the active pallet table, 510	1	-	Active line
	2	-	Palette number from PAL/PGM field
Machine parameter exists, 1010	MP number	MP index	Acknowledgement value = 0: MP does not exist Return code = 1: MP exists



Example: Assign the value of the active scaling factor for the Z axis to  $\Omega 25$ .

55 FN18: SYSREAD Q25 = ID210 NR4 IDX3

#### FN19: PLC: Transferring values to the PLC

The function FN 19: PLC transfers up to two numerical values or Q parameters to the PLC.

Increments and units: 0.1 µm or 0.0001°

Example: Transfer the numerical value 10 (which means 1  $\mu m$  or 0.001°) to the PLC

56 FN19: PLC=+10/+Q3

#### FN20: WAIT FOR NC and PLC synchronization



This function may only be used with the permission of your machine tool builder.

With function FN 20: WAIT FOR you can synchronize the NC and PLC with each other during a program run. The NC stops machining until the condition that you have programmed in the FN 20 block is fulfilled. With FN10 the TNC can check the following operands:

PLC Operand	Abbreviation	Address range
Marker	М	0 to 4999
Input	T	0 to 31, 128 to 152 64 to 126 (first PL 401 B) 192 to 254 (second PL 401 B)
Output	0	0 to 30 32 to 62 (first PL 401 B) 64 to 94 (second PL 401 B)
Counter	С	48 to 79
Timer	Т	0 to 95
Byte	В	0 to 4095
Word	W	0 to 2047
Double word	D	2048 to 4095

The following conditions are permitted in the FN 20 block:

Condition	Abbreviation
Equals	==
Less than	<
Greater than	>
Less than or equal	<=
Greater than or equal	>=

Example: Stop program run until the PLC sets marker 4095 to 1

32 FN20: WAIT FOR M4095==1

#### FN 25: PRESET: Setting a new datum



This function can only be programmed if you have entered the code number 555343, see "Code Number," page 421.

With the function FN 25: PRESET, it is possible to set a new datum in an axis of choice during program run.

- Select a Q parameter function: Press the Q key (in the numerical keypad at right). The Q parameter functions are displayed in a softkey row.
- ▶ To select the additional functions, press the DIVERSE FUNCTIONS soft key.
- Select FN25: Switch the soft-key row to the second level, press the FN25 DATUM SET soft key
- ▶ Axis?: Enter the axis where you wish to set the new datum and confirm with ENT
- ▶ Value to be calculated?: Enter the coordinate for the new datum point in the active coordinate system
- ▶ New datum?: Enter the value that the new datum point will have in the new coordinate system

Example: Set a new datum at the current coordinate X+100

56 FN25: PRESET = X/+100/+0

Example: The current coordinate Z+50 will have the value -20 in the new coordinate system

56 FN25: PRESET = Z/+50/-20

## FN26: TABOPEN: Opening a Freely Definable Table

With FN 26: TABOPEN you can define a table to be written with FN27, or to be read from with FN28.



Only one table can be open in an NC program. A new block with TABOPEN automatically closes the last opened table.

The table to be opened must have the file name extension .TAB.

.Example: Open the table TAB1.TAB, which is save in the directory TNC:\DIR1.

56 FN26: TABOPEN TNC:\SIR1\TAB1.TAB

# FN27: TABWRITE: writing to a freely definable table

After you have opened a table with FN 26 TABOPEN, you can use function FN 27: TABWRITE to write to it.

You can define and write up to 8 column names in a TABWRITE block. The column names must be written between quotation marks and separated by a comma. You define the values that the TNC is to write to the respective column with Q parameters.



You can write only to numerical table fields.

If you wish to write to more than one column in a block, you must save the values under successive Q parameter numbers.

#### Example:

You wish to write to the columns "Radius," "Depth" and "D" in line 5 of the presently opened table. The values to be written in the table must be saved in the Q parameters Q5, Q6 and Q7.

53 FNO: Q5 = 3.75

54 FNO: Q6 = -5

55 FNO: Q7 = 7.5

56 FN27: TABWRITE 5/"radius, depth, D" = Q5

# FN28: TABREAD: Reading a Freely Definable Table

After you have opened a table with FN 26 TABOPEN, you can use function FN 28: TABREAD to read from it.

You can define, i.e. read in, up to 8 column names in a TABREAD block. The column names must be written between quotation marks and separated by a comma. In the FN 28 block you can define the Q parameter number in which the TNC is to write the value that is first read.



You can read only numerical table fields.

If you wish to read from more than one column in a block, the TNC will save the values under successive Q parameter numbers.

#### Example:

You wish to read the values of the columns "Radius," "Depth" and "D" from line 6 of the presently opened table. Save the first value in Q parameter Q10 (second value in Q11, third value in Q12).

56 FN28: TABREAD Q10 = 6/"radius,depth,D"

### 10.9 Entering Formulas Directly

#### **Entering formulas**

You can enter mathematical formulas that include several operations directly into the part program by soft key.

Press the FORMULA soft key to call the formula functions. The TNC displays the following soft keys in several soft-key rows:

Mathematical function	Soft key
Addition Example: Q10 = Q1 + Q5	+
Subtraction Example: Q25 = Q7 - Q108	_
Multiplication Example: Q12 = 5 * Q5	*
Division Example: Q25 = Q1 / Q2	/
Opening parenthesis Example: Q12 = Q1 * (Q2 + Q3)	(
Closing parenthesis Example: Q12 = Q1 * (Q2 + Q3)	)
Square of a value Example: Q15 = SQ 5	SQ
Square root Example: Q22 = SQRT 25	SQRT
Sine of an angle Example: Q44 = SIN 45	SIN
Cosine of an angle Example: Q45 = COS 45	cos
Tangent of an angle Example: Q46 = TAN 45	TAN
Arc sine Inverse of the sine. Determine the angle from the ratio of the opposite side to the hypotenuse. Example: Q10 = ASIN 0.75	ASIN
Arc cosine Inverse of the cosine. Determine the angle from the ratio of the adjacent side to the hypotenuse. Example: Q11 = ACOS Q40	ACOS

	0.61
Mathematical function	Soft key
Arc tangent Inverse of the tangent. Determine the angle from the ratio of the opposite to the adjacent side. Example: Q12 = ATAN Q50	ATAN
Powers of values Example: Q15 = 3^3	^
Constant "pi" (3.14159) Example: Q15 = PI	PI
Natural logarithm (LN) of a number Base 2.7183 Example: Q15 = LN Q11	LN
Logarithm of a number, base 10 Example: Q33 = L0G Q22	LOG
Exponential function, 2.7183 to the power of n Example: Q1 = EXP Q12	ЕХР
Negate (multiplication by -1) Example: Q2 = NEG Q1	NEG
Truncate decimal places (form an integer) Example: Q3 = INT Q42	INT
Absolute value of a number Example: Q4 = ABS Q22	ABS
Truncate places before the decimal point (form a fraction) Example: Q5 = FRAC Q23	FRAC

#### **Rules for formulas**

Mathematical formulas are programmed according to the following rules:

Higher-level operations are performed first (multiplication and division before addition and subtraction)

**1st** step 5 \* 3 = 15 **2nd** step 2 \* 10 = 20 **3rd** step 15 + 20 = 35 13  $Q2 = SQ 10 - 3^3 = 73$ 

**1st** step 10 squared = 100

**2nd** step 3 to the powers 3 = 27

**3rd** step 100 - 27 = 73

**Distributive law** 

for calculating with parentheses

a \* (b + c) = a \* b + a \* c

#### **Programming example**

Calculate an angle with arc tangent as opposite side (Q12) and adjacent side (Q13); then store in Q25.

Q

FORMULA

To select the formula entering function, press the Q key and FORMULA soft key.

Parameter number for result?

Enter the parameter number. 25

ATAN

Shift the soft-key row and select the arc tangent function.

(

Shift the soft-key row and open the parentheses.

12

Enter Q parameter number 12.

Select division.

13

Enter Q parameter number 13.

END

Close parentheses and conclude formula entry.

#### **Example NC block**

37 Q25 = ATAN (Q12/Q13)

#### 10.10 Preassigned Q Parameters

The Q parameters Q100 to Q122 are assigned values by the TNC. These values include:

- Values from the PLC
- Tool and spindle data
- Data on operating status, etc.

#### Values from the PLC: Q100 to Q107

The TNC uses the parameters Q100 to Q107 to transfer values from the PLC to an NC program.

#### Active tool radius: Q108

The active value of the tool radius is assigned to Q108. Q108 is calculated from:

- Tool radius R (Tool table or TOOL DEF block)
- Delta value DR from the tool table
- Delta value DR from the TOOL CALL block

#### Tool axis: Q109

The value of Q109 depends on the current tool axis:

Tool axis	Parameter value
No tool axis defined	Q109 = -1
X axis	Q109 = 0
Y axis	Q109 = 1
Z axis	Q109 = 2
U axis	Q109 = 6
V axis	Q109 = 7
W axis	Q109 = 8

#### Spindle status: Q110

The value of Q110 depends on which M function was last programmed for the spindle:

M Function	Parameter value
No spindle status defined	Q110 = -1
M03: Spindle ON, clockwise	Q110 = 0

M Function	Parameter value
M04: Spindle ON, counterclockwise	Q110 = 1
M05 after M03	Q110 = 2
M05 after M04	Q110 = 3

#### Coolant on/off: Q111

M Function	Parameter value
M08: Coolant ON	Q111 = 1
M09: Coolant OFF	Q111 = 0

#### Overlap factor: Q112

The overlap factor for pocket milling (MP7430) is assigned to Q112.

# Unit of measurement for dimensions in the program: Q113

The value of parameter Q113 specifies whether the highest-level NC program (for nesting with PGM CALL) is programmed in millimeters or inches.

Dimensions of the main program	Parameter value
Metric system (mm)	Q113 = 0
Inch system (inches)	Q113 = 1

#### Tool length: Q114

The current value for the tool length is assigned to Q114.

#### Coordinates after probing during program run

The parameters Q115 to Q119 contain the coordinates of the spindle position at the moment of contact during programmed measurement with the 3-D touch probe. The coordinates are referenced to the datum that is currently active in the Manual operating mode.

The length and radius of the probe tip are not compensated in these coordinates.

Coordinate axis	Parameter value
X axis	Q115
Y axis	Q116
Z axis	Q117

Coordinate axis	Parameter value
IVth axis dependent on MP100	Q118
Vth axis dependent on MP100	Q119

# Deviation between actual value and nominal value during automatic tool measurement with the TT 130

Actual-nominal deviation	Parameter value
Tool length	Q115
Tool radius	Q116

# Tilting the working plane with mathematical angles: Rotary axis coordinates calculated by the TNC

coordinates	Parameter value
A axis	Q120
B axis	Q121
C axis	Q122

#### Results of measurements with touch probe cycles

(see also Touch Probe Cycles User's Manual)

Measured actual values	Parameter value
Angle of a straight line	Q150
Center in reference axis	Q151
Center in minor axis	Q152
Diameter	Q153
Length of pocket	Q154
Width of pocket	Q155
Length in the axis selected in the cycle	Q156
Position of the center line	Q157
Angle of the A axis	Q158
Angle of the B axis	Q159
Coordinate of the axis selected in the cycle	Q160

Measured deviation	Parameter value
Center in reference axis	Q161
Center in minor axis	Q162
Diameter	Q163
Length of pocket	Q164
Width of pocket	Q165
Measured length	Q166
Position of the center line	Q167

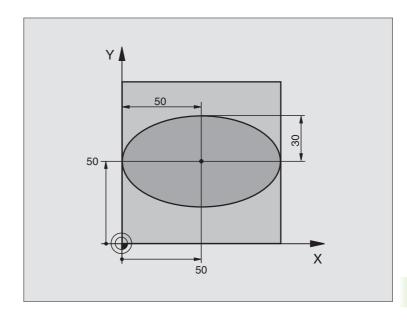
Measured solid angle	Parameter value
Rotation about the A axis	Q170
Rotation about the B axis	Q171
Rotation about the C axis	Q172

Workpiece status	Parameter value
Good	Q180
Re-work	Q181
Scrap	Q182
Measured deviation with cycle 440	Parameter value
X axis	Q185
Y axis	Q186
Z axis	Q187
Reserved for internal use	Parameter value
Markers for cycles (point patterns)	Q197
Status during tool measurement with TT	Parameter value
Tool within tolerance	Q199 = 0.0
Tool is worn (LTOL/RTOL exceeded)	Q199 = 1.0
Tool is broken (LBREAK/RBREAK exceeded)	Q199 = 2.0

#### **Example: Ellipse**

#### Program sequence

- The contour of the ellipse is approximated by many short lines (defined in Q7). The more calculating steps you define for the lines, the smoother the curve becomes.
- The machining direction can be altered by changing the entries for the starting and end angles in the plane:
  Clockwise machining direction:
  starting angle > end angle
  Counterclockwise machining direction:
  starting angle < end angle
- The tool radius is not taken into account.



O BEGIN PGM ELLIPSE MM	
1 FN 0: Q1 = +50	Center in X axis
2 FN 0: Q2 = +50	Center in Y axis
3 FN 0: Q3 = +50	Semiaxis in X
4 FN 0: Q4 = +30	Semiaxis in Y
5 FN 0: Q5 = +0	Starting angle in the plane
6 FN 0: Q6 = +360	End angle in the plane
7 FN 0: Q7 = +40	Number of calculating steps
8 FN 0: Q8 = +0	Rotational position of the ellipse
9 FN 0: Q9 = +5	Milling depth
10 FN 0: Q10 = +100	Feed rate for plunging
11 FN 0: Q11 = +350	Feed rate for milling
12 FN 0: Q12 = +2	Setup clearance for pre-positioning
13 BLK FORM 0.1 Z X+0 Y+0 Z-20	Define the workpiece blank
14 BLK FORM 0.2 X+100 Y+100 Z+0	
15 TOOL DEF 1 L+0 R+2.5	Define the tool
16 TOOL CALL 1 Z S4000	Tool call
17 L Z+250 RO F MAX	Retract the tool
18 CALL LBL 10	Call machining operation
19 L Z+100 RO F MAX M2	Retract in the tool axis, end program

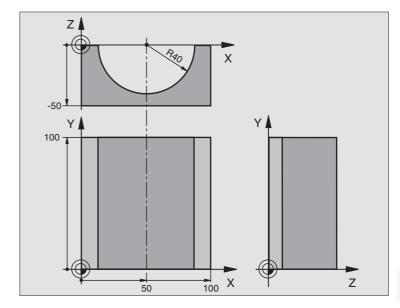
20 LBL 10	Cubaragram 10: Machining appretion	
	Subprogram 10: Machining operation	
21 CYCL DEF 7.0 DATUM SHIFT	Shift datum to center of ellipse	
22 CYCL DEF 7.1 X+Q1		
23 CYCL DEF 7.2 Y+Q2		
24 CYCL DEF 10.0 DREHUNG	Account for rotational position in the plane	
25 CYCL DEF 10.1 ROT+Q8		
26 Q35 = (Q6 - Q5) / Q7	Calculate angle increment	
27 Q36 = Q5	Copy starting angle	
28 Q37 = 0	Set counter	
29 Q21 = Q3 * COS Q36	Calculate X coordinate for starting point	
30 Q22 = Q4 * SIN Q36	Calculate Y coordinate for starting point	
31 L X+Q21 Y+Q22 RO F MAX M3	Move to starting point in the plane	
32 L Z+Q12 RO F MAX	Pre-position in tool axis to setup clearance	
33 L Z-Q9 R0 FQ10	Move to working depth	
34 LBL 1		
35 Q36 = Q36 + Q35	Update the angle	
36 Q37 = Q37 + 1	Update the counter	
37 Q21 = Q3 * COS Q36	Calculate the current X coordinate	
38 Q22 = Q4 * SIN Q36	Calculate the current Y coordinate	
39 L X+Q21 Y+Q22 R0 FQ11	Move to next point	
40 FN 12: IF +Q37 LT +Q7 G0T0 LBL 1	Unfinished? If not finished, return to LBL 1	
41 CYCL DEF 10.0 DREHUNG	Reset the rotation	
42 CYCL DEF 10.1 ROT+0		
43 CYCL DEF 7.0 DATUM SHIFT	Reset the datum shift	
44 CYCL DEF 7.1 X+0		
45 CYCL DEF 7.2 Y+0		
46 L Z+Q12 RO F MAX	Move to setup clearance	
47 LBL 0	End of subprogram	
48 END PGM ELLIPSE MM		

#### **Example: Concave cylinder machined with spherical cutter**

#### Program sequence

- Program functions only with a spherical cutter. The tool length refers to the sphere center.
- The contour of the cylinder is approximated by many short line segments (defined in Q13). The more line segments you define, the smoother the curve becomes.
- The cylinder is milled in longitudinal cuts (here: parallel to the Y axis).
- The machining direction can be altered by changing the entries for the starting and end angles in space: Clockwise machining direction: starting angle > end angle Counterclockwise machining direction:
- The tool radius is compensated automatically.

starting angle < end angle



O BEGIN PGM CYLIN MM	
1 FN 0: Q1 = +50	Center in X axis
2 FN 0: Q2 = +0	Center in Y axis
3 FN 0: Q3 = +0	Center in Z axis
4 FN 0: Q4 = +90	Starting angle in space (Z/X plane)
5 FN 0: Q5 = +270	End angle in space (Z/X plane)
6 FN 0: Q6 = +40	Radius of the cylinder
7 FN 0: Q7 = +100	Length of the cylinder
8 FN 0: Q8 = +0	Rotational position in the X/Y plane
9 FN 0: Q10 = +5	Allowance for cylinder radius
10 FN 0: Q11 = +250	Feed rate for plunging
11 FN 0: Q12 = +400	Feed rate for milling
12 FN 0: Q13 = +90	Number of cuts
13 BLK FORM 0.1 Z X+0 Y+0 Z-50	Define the workpiece blank
14 BLK FORM 0.2 X+100 Y+100 Z+0	
15 TOOL DEF 1 L+0 R+3	Define the tool
16 TOOL CALL 1 Z S4000	Tool call
17 L Z+250 RO F MAX	Retract the tool
18 CALL LBL 10	Call machining operation
19 FN 0: Q10 = +0	Reset allowance

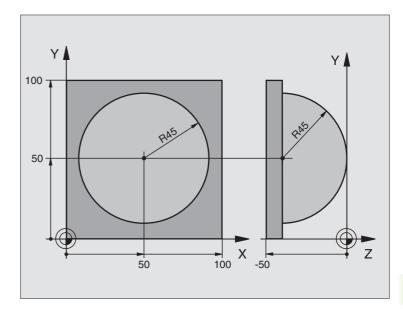
20 CALL LBL 10	Call machining operation	
21 L Z+100 RO F MAX M2	Retract in the tool axis, end program	
22 LBL 10	Subprogram 10: Machining operation	
23 Q16 = Q6 - Q10 - Q108	Account for allowance and tool, based on the cylinder radius	
24 FN 0: Q20 = +1	Set counter	
25 FN 0: Q24 = +Q4	Copy starting angle in space (Z/X plane)	
26 Q25 = (Q5 - Q4) / Q13	Calculate angle increment	
27 CYCL DEF 7.0 DATUM SHIFT	Shift datum to center of cylinder (X axis)	
28 CYCL DEF 7.1 X+Q1		
29 CYCL DEF 7.2 Y+Q2		
30 CYCL DEF 7.3 Z+Q3		
31 CYCL DEF 10.0 DREHUNG	Account for rotational position in the plane	
32 CYCL DEF 10.1 ROT+Q8		
33 L X+0 Y+0 R0 F MAX	Pre-position in the plane to the cylinder center	
34 L Z+5 R0 F1000 M3	Pre-position in the tool axis	
35 LBL 1		
36 CC Z+0 X+0	Set pole in the Z/X plane	
37 LP PR+Q16 PA+Q24 FQ11	Move to starting position on cylinder, plunge-cutting obliquely into	
38 L Y+Q7 R0 FQ12	Longitudinal cut in Y+ direction	
39 FN 1: Q20 = +Q20 + +1	Update the counter	
40 FN 1: Q24 = +Q24 + +Q25	Update solid angle	
41 FN 11: IF +Q20 GT +Q13 GOTO LBL 99	Finished? If finished, jump to end.	
42 LP PR+Q16 PA+Q24 FQ11	Move in an approximated "arc" for the next longitudinal cut.	
43 L Y+0 R0 FQ12	Longitudinal cut in Y- direction	
44 FN 1: Q20 = +Q20 + +1	Update the counter	
45 FN 1: Q24 = +Q24 + +Q25	Update solid angle	
46 FN 12: IF +Q20 LT +Q13 GOTO LBL 1	Unfinished? If not finished, return to LBL 1	
47 LBL 99		
48 CYCL DEF 10.0 DREHUNG	Reset the rotation	
49 CYCL DEF 10.1 ROT+0		
50 CYCL DEF 7.0 DATUM SHIFT	Reset the datum shift	
51 CYCL DEF 7.1 X+0		
52 CYCL DEF 7.2 Y+0		
53 CYCL DEF 7.3 Z+0		
54 LBL 0	End of subprogram	
55 END PGM CYLIN MM		



#### **Example: Convex sphere machined with end mill**

#### Program sequence

- This program requires an end mill.
- The contour of the sphere is approximated by many short lines (in the Z/X plane, defined in Q14). The smaller you define the angle increment, the smoother the curve becomes.
- You can determine the number of contour cuts through the angle increment in the plane (defined in Q18).
- The tool moves upward in three-dimensional
- The tool radius is compensated automatically.



O BEGIN PGM BALL MM		
1 FN 0: Q1 = +50	Center in X axis	
2 FN 0: Q2 = +50	Center in Y axis	
3 FN 0: Q4 = +90	Starting angle in space (Z/X plane)	
4 FN 0: Q5 = +0	End angle in space (Z/X plane)	
5 FN 0: Q14 = +5	Angle increment in space	
6 FN 0: Q6 = +45	Radius of the sphere	
7 FN 0: Q8 = +0	Starting angle of rotational position in the X/Y plane	
8 FN 0: Q9 = +360	End angle of rotational position in the X/Y plane	
9 FN 0: Q18 = +10	Angle increment in the X/Y plane for roughing	
10 FN 0: Q10 = +5	Allowance in sphere radius for roughing	
11 FN 0: Q11 = +2	Setup clearance for pre-positioning in the tool axis	
12 FN 0: Q12 = +350	Feed rate for milling	
13 BLK FORM 0.1 Z X+0 Y+0 Z-50	Define the workpiece blank	
14 BLK FORM 0.2 X+100 Y+100 Z+0		
15 TOOL DEF 1 L+0 R+7.5	Define the tool	
16 TOOL CALL 1 Z S4000	Tool call	
17 L Z+250 RO F MAX	Retract the tool	

18 CALL LBL 10	Call machining operation	
19 FN 0: Q10 = +0	Reset allowance	
20 FN 0: Q18 = +5	Angle increment in the X/Y plane for finishing	
21 CALL LBL 10	Call machining operation	
22 L Z+100 RO F MAX M2	Retract in the tool axis, end program	
23 LBL 10	Subprogram 10: Machining operation	
24 FN 1: Q23 = +Q11 + +Q6	Calculate Z coordinate for pre-positioning	
25 FN 0: Q24 = +Q4	Copy starting angle in space (Z/X plane)	
26 FN 1: Q26 = +Q6 + +Q108	Compensate sphere radius for pre-positioning	
27 FN 0: Q28 = +Q8	Copy rotational position in the plane	
28 FN 1: Q16 = +Q6 + -Q10	Account for allowance in the sphere radius	
29 CYCL DEF 7.0 DATUM SHIFT	Shift datum to center of sphere	
30 CYCL DEF 7.1 X+Q1		
31 CYCL DEF 7.2 Y+Q2		
32 CYCL DEF 7.3 Z-Q16		
33 CYCL DEF 10.0 DREHUNG	Account for starting angle of rotational position in the plane	
34 CYCL DEF 10.1 ROT+Q8		
35 CC X+0 Y+0	Set pole in the X/Y plane for pre-positioning	
36 LP PR+Q26 PA+Q8 R0 FQ12	Pre-position in the plane	
37 LBL 1	Pre-position in the tool axis	
38 CC Z+0 X+Q108	Set pole in the Z/X plane, offset by the tool radius	
39 L Y+0 Z+0 FQ12	Move to working depth	

40 LBL 2		
41 LP PR+Q6 PA+Q24 RO FQ12	Move upward in an approximated "arc"	
42 FN 2: Q24 = +Q24 - + Q14	Update solid angle	
43 FN 11: IF +Q24 GT +Q5 GOTO LBL 2	Inquire whether an arc is finished. If not finished, return to LBL 2.	
44 LP PR+Q6 PA+Q5	Move to the end angle in space	
45 L Z+Q23 R0 F1000	Retract in the tool axis	
46 L X+Q26 RO F MAX	Pre-position for next arc	
47 FN 1: Q28 = +Q28 + +Q18	Update rotational position in the plane	
48 FN 0: Q24 = +Q4	Reset solid angle	
49 CYCL DEF 10.0 DREHUNG	Activate new rotational position	
50 CYCL DEF 10.1 ROT+Q28		
51 FN 12: IF +Q28 LT +Q9 GOTO LBL 1		
52 FN 9: IF +Q28 EQU +Q9 GOTO LBL 1	Unfinished? If not finished, return to label 1	
53 CYCL DEF 10.0 DREHUNG	Reset the rotation	
54 CYCL DEF 10.1 ROT+0		
55 CYCL DEF 7.0 DATUM SHIFT	Reset the datum shift	
56 CYCL DEF 7.1 X+0		
57 CYCL DEF 7.2 Y+0		
58 CYCL DEF 7.3 Z+0		
59 LBL 0	End of subprogram	
60 END PGM BALL MM		

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Test run and Program Run

#### 11.1 Graphics

#### **Function**

In the program run modes of operation as well as in the Test Run mode, the TNC provides the following three display modes: Using soft keys, select whether you desire:

- Plan view
- Projection in 3 planes
- 3-D view

The TNC graphic depicts the workpiece as if it were being machined with a cylindrical end mill. If a tool table is active, you can also simulate the machining operation with a spherical cutter. For this purpose, enter R2 = R in the tool table.

The TNC will not show a graphic if

- the current program has no valid blank form definition
- no program is selected

With machine parameters 7315 to 7317 you can have the TNC display a graphic even if no tool axis is defined or moved.



A graphic simulation is not possible for program sections or programs in which rotary axis movements or a tilted working plane are defined. In this case, the TNC will display an error message.

The TNC graphic does not show a radius oversize DR that has been programmed in the TOOL CALL block.

The TNC can display the graphic only if the ratio of the short side to the long sides of the **BLK FORM** is greater than 1:64!

#### Overview of display modes

The TNC displays the following soft keys in the program run and test run modes of operation:

Display mode	Soft key
Plan view	
Projection in 3 planes	
3-D view	



#### Limitations during program run

A graphical representation of a running program is not possible if the microprocessor of the TNC is already occupied with complicated machining tasks or if large areas are being machined. Example: Multipass milling over the entire blank form with a large tool. The TNC interrupts the graphics and displays the text **ERROR** in the graphics window. The machining process is continued, however.

#### Plan view



- Press the soft key for plan view.
- Select the number of depth levels (after shifting the soft-key row). You can choose between 16 or 32 shades of depth.

The deeper the surface, the darker the shade.

Plan view is the fastest of the three graphic display modes.

#### **Projection in 3 planes**

Similar to a workpiece drawing, the part is displayed with a plan view and two sectional planes. A symbol to the lower left indicates whether the display is in first angle or third angle projection according to ISO 6433 (selected with MP7310).

Details can be isolated in this display mode for magnification, see "Magnifying details," page 402.

In addition, you can shift the sectional planes with the corresponding soft keys:



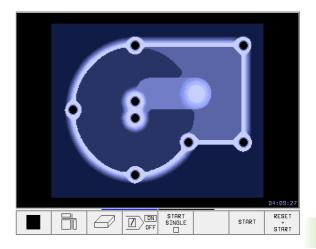
- ▶ Press the soft key for projection in three planes.
- Shift the soft-key row until the TNC displays the following soft keys:

Function	Soft keys
Shift the vertical sectional plane to the right or left	<b>‡</b>
Shift the horizontal sectional plane upwards or downwards	<del>†</del> □

The positions of the sectional planes are visible during shifting.

#### Coordinates of the line of intersection

At the bottom of the graphics window, the TNC displays the coordinates of the line of intersection, referenced to the workpiece datum. Only the coordinates of the working plane are shown. This function is activated with machine parameter 7310.



#### 3-D view

The workpiece is displayed in three dimensions, and can be rotated about the vertical axis.

The workpiece is displayed in three dimensions, and can be rotated about the vertical axis. The shape of the workpiece blank can be depicted by a frame overlay at the beginning of the graphic simulation.

In the Test Run mode of operation you can isolate details for magnification, see "Magnifying details," page 402.



Press the soft key for 3-D view.

#### To rotate the 3-D view

Shift the soft-key row until the following soft keys appear:

Function	Soft keys
Rotate the workpiece in 27° steps about the vertical axis	

# SHOW OMIT RESET STORE BLK FORM BLK-FORM BLK-FORM BLK-FORM BLK-FORM BLK FORM FORM

#### Switch the frame overlay display for the workpiece blank on/off:



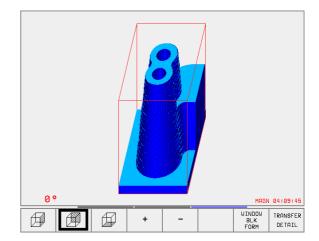
- ▶ Show the frame overlay with SHOW BLK-FORM
- ▶ Omit the frame overlay with OMIT BLK-FORM

#### Magnifying details

You can magnify details in the Test Run mode of operation in the following display modes, provided that the graphic simulation is stopped:

- Projection in three planes
- 3-D view

The graphic simulation must first have been stopped. A detail magnification is always effective in all display modes.



Shift the soft-key row in the Test Run mode of operation until the following soft keys appear:

Function	Soft keys
Select the left/right workpiece surface	
Select the front/back workpiece surface	
Select the top/bottom workpiece surface	
Shift the sectional plane to reduce or magnify the blank form	- +
Select the isolated detail	TRANSFER DETAIL

#### To change the detail magnification:

The soft keys are listed in the table above.

- Interrupt the graphic simulation, if necessary.
- Select the workpiece surface with the corresponding soft key (see table).
- ▶ To reduce or magnify the blank form, press and hold the MINUS or PLUS soft key, respectively.
- Restart the test run or program run by pressing the START soft key (RESET + START returns the workpiece blank to its original state).

#### Cursor position during detail magnification

During detail magnification, the TNC displays the coordinates of the axis that is currently being isolated. The coordinates describe the area determined for magnification. To the left of the slash is the smallest coordinate of the detail (MIN point), to the left is the largest (MAX point).

If a graphic display is magnified, this is indicated with **MAGN** at the lower right of the graphics window.

If the workpiece blank cannot be further enlarged or reduced, the TNC displays an error message in the graphics window. To clear the error message, reduce or enlarge the workpiece blank.

#### Repeating graphic simulation

A part program can be graphically simulated as often as desired, either with the complete workpiece or with a detail of it.

Function	Soft key
Restore workpiece blank to the detail magnification in which it was last shown	RESET BLK FORM
Reset detail magnification so that the machined workpiece or workpiece blank is displayed as it was programmed with BLK FORM	WINDOW BLK FORM



With the WINDOW BLK FORM soft key, you return the displayed workpiece blank to its originally programmed dimensions, even after isolating a detail—without TRANSFER DETAIL.

#### Measuring the machining time

#### program run modes of operation

The timer counts and displays the time from program start to program end. The timer stops whenever machining is interrupted.

#### Test run

The timer displays the approximate time which the TNC calculates from the duration of tool movements. The time calculated by the TNC cannot be used for calculating the production time because the TNC does not account for the duration of machine-dependent interruptions, such as tool change.

#### To activate the stopwatch function

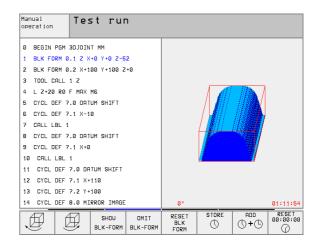
Shift the soft-key rows until the TNC displays the following soft keys with the stopwatch functions:

Stopwatch functions	Soft key
Store displayed time	STORE
Display the sum of stored time and displayed time	ADD ()+()
Clear displayed time	RESE T 00:00:00



The soft keys available to the left of the stopwatch functions depend on the selected screen layout.

The time is reset when a new BLK form is entered.

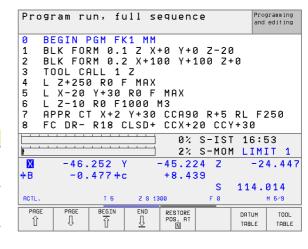


#### 11.2 Functions for Program Display

#### **Overview**

In the program run modes of operation as well as in the Test Run mode, the TNC provides the following soft keys for displaying a part program in pages:

Function	Soft key
Go back in the program by one screen	PAGE Î
Go forward in the program by one screen	PAGE
Go to the beginning of the program	BEGIN
Go to the end of the program	END



#### 11.3 Test run

#### **Function**

In the Test Run mode of operation you can simulate programs and program sections to prevent errors from occurring during program run. The TNC checks the programs for the following:

- Geometrical incompatibilities
- Missing data
- Impossible jumps
- Violation of the machine's working space

The following functions are also available:

- Blockwise test run
- Interrupt test at any block
- Optional Block Skip
- Functions for graphic simulation
- Measuring the machining time
- Additional status display

#### Running a program test

If the central tool file is active, a tool table must be active (status S) to run a program test. Select a tool table via the file manager (PGM MGT) in the Test Run mode of operation.

With the MOD function BLANK IN WORK SPACE, you can activate work space monitoring for the test run, see "Showing the workpiece in the working space," page 435.



- ▶ Select the Test Run mode of operation.
- Call the file manager with the PGM MGT key and select the file you wish to test, or
- ▶ Go to the program beginning: Select line "0" with the GOTO key and confirm you entry with the ENT key.

The TNC then displays the following soft keys:

Function	Soft key
Test the entire program	START
Test each program block individually	START SINGLE
Show the blank form and test the entire program	RESET + START
Interrupt the test run	STOP



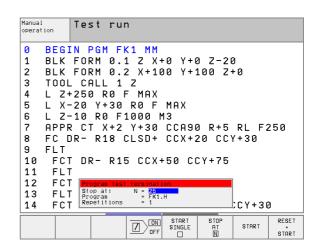
#### Run a program test up to a certain block

With the STOP AT N function the TNC does a test run up to the block with block number N.

- ▶ Go to the beginning of program in the Test Run mode of operation.
- To run a program test up to a specific block, press the STOP AT N soft key.



- Stop at N: Enter the block number at which you wish the test to stop.
- ▶ Program: Enter the name of the program that contains the block with the selected block number. The TNC displays the name of the selected program. If the test run is to be interrupted in a program that was called with PGM CALL, you must enter this name.
- ▶ Repetitions: If N is located in a program section repeat, enter the number of repeats that you want to run.
- ➤ To test a program section, press the START soft key. The TNC will test the program up to the entered block.



# 11.4 Program run

# **Application**

In the Program Run, Full Sequence mode of operation the TNC executes a part program continuously to its end or up to a program stop.

In the Program Run, Single Block mode of operation you must start each block separately by pressing the machine START button.

The following TNC functions can be used in the program run modes of operation:

- Interrupt program run
- Start program run from a certain block
- Optional Block Skip
- Editing the tool table TOOL.T
- Checking and changing Q parameters
- Superimposing handwheel positioning
- Functions for graphic simulation
- Additional status display

# Running a part program

#### Preparation

- 1 Clamp the workpiece to the machine table.
- 2 Set the datum.
- **3** Select the necessary tables and pallet files (status M).
- **4** Select the part program (status M).



You can adjust the feed rate and spindle speed with the override knobs.

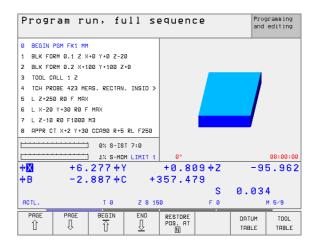
It is possible to reduce the rapid traverse speed when starting the NC program using the FMAX soft key. The entered value remains in effect even after the machine has been turned off and on again. In order to re-establish the original rapid traverse speed, you need to re-enter the corresponding value.

#### **Program Run, Full Sequence**

▶ Start the part program with the machine START button.

#### Program Run, Single Block

Start each block of the part program individually with the machine START button.



# Interrupting machining

There are several ways to interrupt a program run:

- Programmed interruptions
- Machine STOP button
- Switching to Program Run, Single Block

If the TNC registers an error during program run, it automatically interrupts the machining process.

#### **Programmed interruptions**

You can program interruptions directly in the part program. The TNC interrupts the program run at a block containing one of the following entries:

- STOP (with and without a miscellaneous function)
- Miscellaneous function M0, M2 or M30
- Miscellaneous function M6 (determined by the machine tool builder)

#### To interrupt machining with the machine STOP button:

- ▶ Press the machine STOP button: The block which the TNC is currently executing is not completed. The asterisk in the status display blinks.
- If you do not wish to continue the machining process you can reset the TNC with the INTERNAL STOP soft key. The asterisk in the status display goes out. In this case, the program must be restarted from the program beginning.

# Interruption of machining by switching to the Program Run, Single Block mode of operation.

You can interrupt a program that is being run in the Program Run, Full Sequence mode of operation by switching to Program Run, Single Block. The TNC interrupts the machining process at the end of the current block.

# Moving the machine axes during an interruption

You can move the machine axes during an interruption in the same way as in the Manual Operation mode.



#### **Danger of collision**

If you interrupt program run while the working plane is tilted, you can change from a tilted to a non-tilted coordinate system, and vice versa, by pressing the 3-D ON/OFF soft key.

The functions of the axis direction buttons, the electronic handwheel and the positioning logic for return to contour are then evaluated by the TNC. When retracting the tool make sure the correct coordinate system is active and the angular values of the tilt axes are entered in the 3-D ROT menu.

# Example application: Retracting the spindle after tool breakage

- ► Interrupting machining
- Enable the external direction keys: Press the MANUAL OPERATION soft key.
- Move the axes with the machine axis direction buttons.



On some machines you may have to press the machine START button after the MANUAL OPERATION soft key to enable the axis direction buttons. Refer to your machine manual.

# Resuming program run after an interruption



If a program run is interrupted during a fixed cycle, the program must be resumed from the beginning of the cycle.

This means that some machining operations will be repeated.

If you interrupt a program run during execution of a subprogram or program section repeat, use the RESTORE POS AT N function to return to the position at which the program run was interrupted.

When a program run is interrupted, the TNC stores:

- The data of the last defined tool
- Active coordinate transformations (e.g. datum shift, rotation, mirroring)
- The coordinates of the circle center that was last defined



Note that the stored data remains active until it is reset (e.g. if you select a new program).

The stored data are used for returning the tool to the contour after manual machine axis positioning during an interruption (RESTORE POSITION soft key).

#### Resuming program run with the START button

You can resume program run by pressing the machine START button if the program was interrupted in one of the following ways:

- The machine STOP button was pressed
- A programmed interruption

#### Resuming program run after an error

If the error message is not blinking:

- ▶ Remove the cause of the error.
- To clear the error message from the screen, press the CE key.
- Restart the program, or resume program run at the place at which it was interrupted.

If the error message is blinking:

- Press and hold the END key for two seconds. This induces a TNC system restart.
- ▶ Remove the cause of the error.
- ▶ Start again.

If you cannot correct the error, write down the error message and contact your repair service agency.



# Mid-program startup (block scan)



The RESTORE POS AT N feature must be enabled and adapted by the machine tool builder. Refer to your machine manual.

With the RESTORE POS AT N feature (block scan) you can start a part program at any block you desire. The TNC scans the program blocks up to that point. Machining can be graphically simulated.

If you have interrupted a part program with an INTERNAL STOP, the TNC automatically offers the interrupted block N for mid-program startup.



Mid-program startup must not begin in a subprogram.

All necessary programs, tables and pallet files must be selected in a program run mode of operation (status M).

If the program contains a programmed interruption before the startup block, the block scan is interrupted. Press the machine START button to continue the block scan.

After a block scan, return the tool to the calculated position with RESTORE POSITION.

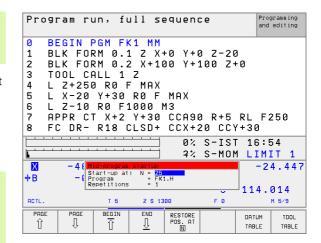
If you are working with nested programs, you can use machine parameter 7680 to define whether the block scan is to begin at block 0 of the main program or at block 0 of the last interrupted program.

If the working plane is tilted, you can use the 3-D ON/OFF soft key to define whether the TNC is to return to the contour in a tilted or in a non-tilted coordinate system.

The function M128 is not permitted during a mid-program startup.

If you want to use the block scan feature in a pallet table, select the program in which a mid-program startup is to be performed from the pallet table by using the arrow keys. Then press the RESTORE POS AT N soft key.

All touch probe cycles and the Cycle 247 are skipped in a mid-program startup. Result parameters that are written to from these cycles might therefore remain empty.



▶ To go to the first block of the current program to start a block scan, enter GOTO "0".



- To select mid-program startup, press the RESTORE POS AT N soft key.
- Start-up at N: Enter the block number N at which the block scan should end.
- Program: Enter the name of the program containing block N.
- ▶ **Repetitions**: If block N is located in a program section repeat, enter the number of repetitions to be calculated in the block scan.
- To start the block scan, press the machine START button.
- To return to the contour, see "Returning to the contour," page 413

# Returning to the contour

With the RESTORE POSITION function, the TNC returns to the workpiece contour in the following situations:

- Return to the contour after the machine axes were moved during a program interruption that was not performed with the INTERNAL STOP function.
- Return to the contour after a block scan with RESTORE POS AT N, for example after an interruption with INTERNAL STOP.
- Depending on the machine, if the position of an axis has changed after the control loop has been opened during a program interruption:
- ▶ To select a return to contour, press the RESTORE POSITION soft key.
- ▶ To move the axes in the sequence that the TNC suggests on the screen, press the machine START button.
- ▶ To move the axes in any sequence, press the soft keys RESTORE X, RESTORE Z, etc., and activate each axis with the machine START key.
- To resume machining, press the machine START key.

# 11.5 Automatic Program Start

# **Function**

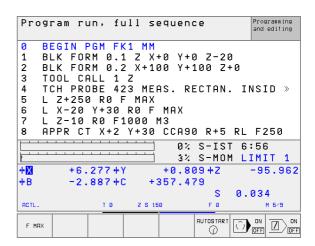


The TNC must be specially prepared by the machine tool builder for use of the automatic program start function. Refer to your machine manual.

In a Program Run operating mode, you can use the soft key AUTOSTART (see figure at upper right) to define a specific time at which the program that is currently active in this operating mode is to be started:



- Show the window for entering the starting time (see figure at center right).
- ▶ Time (h:min:sec): Time of day at which the program is to be started
- ▶ Date (DD.MM.YYYY): Date at which the program is to be started
- To activate the start, set the AUTOSTART soft key to ON.



```
Automatic program start
Time: 26.08.1999 06:56:04
Start program at:
Time (hrs:min:sec): 22:00:00
Date (DD.MM.YYYY): 26.08.1999
Inactive
```



# 11.6 Optional Block Skip

# **Function**

In a test run or program run, the TNC can skip over blocks that begin with a slash "/":



To run or test the program without the blocks preceded by a slash, set the soft key to ON.



To run or test the program with the blocks preceded by a slash, set the soft key to OFF.



This function does not work for TOOL DEF blocks.

After a power interruption the TNC returns to the most recently selected setting.

# 11.7 Optional Program Run Interruption

# **Function**

The TNC optionally interrupts the program or test run at blocks containing M01. If you use M01 in the Program Run mode, the TNC does not switch off the spindle or coolant.



▶ Do not interrupt program run or test run at blocks containing M01: Set soft key to OFF



Interrupt program run or test run at blocks containing M01: Set soft key to ON





# 12

**MOD Functions** 

# 12.1 MOD functions

The MOD functions provide additional displays and input possibilities. The available MOD functions depend on the selected operating mode.

# Selecting the MOD functions

Call the mode of operation in which you wish to change the MOD function.



➤ To select the MOD functions, press the MOD key. The figures at right show typical screen menus in Programming and Editing (figure at upper right), Test Run (figure at lower right) and in a machine operating mode (see figure on next page).

# Changing the settings

Select the desired MOD function in the displayed menu with the arrow keys.

There are three possibilities for changing a setting, depending on the function selected:

- Enter a numerical value directly, e.g. when determining traverse range limit
- Change a setting by pressing the ENT key, e.g. when setting program input
- Change a setting via a selection window. If there are more than one possibilities for a particular setting available, you can superimpose a window listing all of the given possibilities by pressing the GOTO key. Select the desired setting directly by pressing the corresponding numerical key (to the left of the colon), or using the arrow keys and then confirming with ENT. If you don't want to change the setting, close the window again with END.

# Exiting the MOD functions

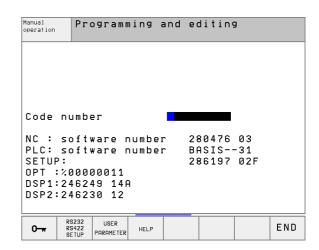
Close the MOD functions with the END soft key or key.

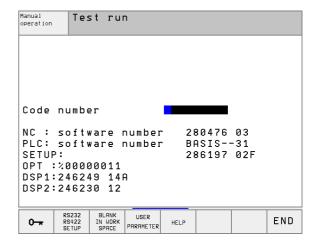
#### **Overview of MOD functions**

Depending on the selected mode of operation, you can make the following changes:

Programming and Editing:

- Display software numbers
- Enter code number
- Set data interface
- Machine-specific user parameters (if provided)
- HELP files (if provided)





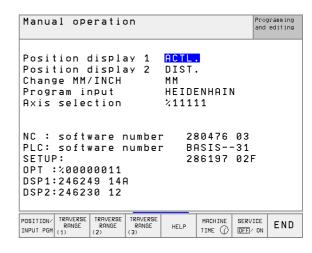
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#### Test Run:

- Display software numbers
- Enter code number
- Setting the data interface
- Showing the workpiece in the working space
- Machine-specific user parameters (if provided)
- Displaying HELP files (if provided)

#### In all other modes:

- Display software numbers
- Display code digits for installed options
- Select position display
- Unit of measurement (mm/inches)
- Programming language for MDI
- Select the axes for actual position capture
- Set the axis traverse limits
- Display the datums
- Displaying Operating Time
- HELP files (if provided)
- Activate Teleservice functions (if provided)



# 12.2 Software Numbers and Option Numbers

# **Function**

The software numbers of the NC, PLC and the SETUP floppy disks appear in the TNC screen after the MOD functions have been selected. Directly below them are the code numbers for the installed options (OPT:):

No option OPT 00000000

Option for digitizing with triggering touch probe OPT 00000001 Option for digitizing with measuring touch probe OPT 00000011



# 12.3 Code Number

# **Function**

The TNC requires a code number for the following functions:

Function	Code number
Select user parameters	123
Configuring an Ethernet card	NET123
Enabling special functions for Q parameter programming	555343

# 12.4 Setting the Data Interfaces

#### **Function**

To setup the data interfaces, press the RS 232-/RS 422 - SETUP soft key to call a menu for setting the data interfaces:

# Setting the RS-232 interface

The mode of operation and baud rates for the RS-232 interface are entered in the upper left of the screen.

# **Setting the RS-422 interface**

The mode of operation and baud rates for the RS-422 interface are entered in the upper right of the screen.

# Setting the OPERATING MODE of the external device

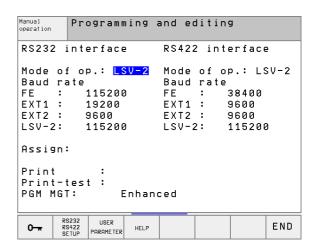


The functions "Transfer all files," "Transfer selected file," and "Transfer directory" are not available in the operating modes FE2 and EXT.

# **Setting the BAUD RATE**

You can set the BAUD-RATE (data transfer speed) from 110 to 115,200 baud.

External device	Operating mode	Symbol
PC with HEIDENHAIN software TNCremo for remote operation of the TNC	LSV2	呂
PC with HEIDENHAIN data transfer software TNCremo	FE1	
HEIDENHAIN floppy disk units FE 401 B FE 401 from prog. no. 230 626 03	FE1 FE1	
HEIDENHAIN floppy disk unit FE 401 up to prog. no. 230 626 02	FE2	
Non-HEIDENHAIN devices such as punchers, PC without TNCremo	EXT1, EXT2	Þ



# **Assign**

This function sets the destination for the transferred data.

#### Applications:

- Transferring values with Q parameter function FN15
- Transferring values with Q parameter function FN16
- Path on the TNC's hard disk in which the digitized data are stored

The TNC mode of operation determines whether the PRINT or PRINT TEST function is used:

TNC mode of operation	Transfer function
Program Run, Single Block	PRINT
Program Run, Full Sequence	PRINT
Test run	PRINT TEST

You can set PRINT and PRINT TEST as follows:

Function	Path
Output data via RS-232	RS232:\
Output data via RS-422	RS422:\
Save data to the TNC's hard disk	TNC:\
Save data in directory in which the program with FN15/FN16 or the program with the digitizing cycles is located	- vacant -

#### File names

Data	Operating mode	File name
Surface data	Program run	Defined in the RANGE cycle
Values with FN15	Program run	%FN15RUN.A
Values with FN15	Test run	%FN15SIM.A
Values with FN16	Program run	%FN16RUN.A
Values with FN16	Test run	%FN16SIM.A

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#### Software for data transfer

For transfer of files to and from the TNC, we recommend using one the HEIDENHAIN TNCremo data transfer software products for data transfer, such as TNCremo or TNCremoNT. With TNCremo/TNCremoNT, data transfer is possible with all HEIDENHAIN controls via serial interface.



Please contact your HEIDENHAIN agent if you would like to receive the TNCremo or TNCremoNT data transfer software for a nominal fee.

System requirements for TNCremo:

- AT personal computer or compatible system
- Operating system MS-DOS/PC-DOS 3.00 or later, Windows 3.1, Windows for Workgroups 3.11, Windows NT 3.51, OS/2
- 640 KB working memory
- 1 MB free memory space on your hard disk
- One free serial interface
- A Microsoft-compatible mouse (for ease of operation, not essential)

System requirements for TNCremoNT:

- PC with 486 processor or higher
- Operating system Windows 95, Windows 98, Windows NT 4.0
- 16 MB working memory
- 5 MB free memory space on your hard disk
- One free serial interface or connection to the TCP/IP network on TNCs with Ethernet card

#### Installation under Windows

- Start the SETUP.EXE installation program in the file manager (Explorer).
- Follow the instructions of the setup program.

#### Starting TNCremo under Windows 3.1, 3.11 and NT 3.51

Windows 3.1, 3.11, NT 3.51:

Double-click on the icon in the program group HEIDENHAIN Applications.

When you start TNCremo for the first time, you will be asked for the type of control you have connected, the interface (COM1 or COM2) and the data transfer speed. Enter the necessary information.

#### Starting TNCremoNT under Windows 95, Windows 98 and NT 4.0

Click on <Start>, <Programs>, <HEIDENHAIN Applications>, <TNCremoNT>

When you start TNCremoNT for the first time, TNCremoNT automatically tries to set up a connection with the TNC.



#### Data transfer between the TNC and TNCremo

Ensure that:

- The TNC is connected to the correct serial port on your PC.
- The operating mode of the interface is set to **LSV2** on the TNC.
- The data transfer speed set on the TNC for LSV2 operation is the same as that set on TNCremo.

Once you have started TNCremo, you will see a list of all of the files that are stored in the active directory on the left side of the main window 1. Using the menu items <Directory>, <Change>, you can change the active directory or select another directory on your PC.

If you want to control data transfer from the PC, establish the connection with your PC in the following way:

- Select <Connect>, <Link>. TNCremo now receives the file and directory structure from the TNC and displays this at the bottom left of the main window 2.
- ➤ To transfer a file from the TNC to the PC, select the file in the TNC window (highlighted with a mouse click) and activate the functions <File> <Transfer>.
- ▶ To transfer a file from the PC to the TNC, select the file in the PC window (highlighted with a mouse click) and activate the functions <File> <Transfer>.

If you want to control data transfer from the TNC, establish the connection with your PC in the following way:

- ▶ Select <Connect>, <File server (LSV2)>. TNCremo is now in server mode. It can receive data from the TNC and send data to the TNC.
- ▶ You can now call the file management functions on the TNC by pressing the key PGM MGT (see "Data transfer to or from an external data medium" on page 59) and transfer the desired files.

#### **End TNCremo**

Select the menu items <File>, <Exit>, or press the key combination ALT+X.



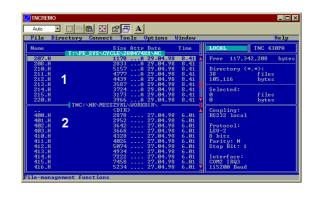
Refer also to the TNCremoNT help texts where all of the functions are explained in more detail.

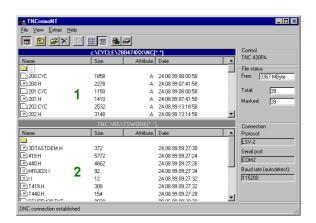
#### Data transfer between the TNC and TNCremoNT

Ensure that:

- The TNC is connected to the correct serial port on your PC or to the network, respectively.
- The operating mode of the interface is set to **LSV2** on the TNC.

Once you have started TNCremoNT, you will see a list of all of the files that are stored in the active directory on the upper section of the main window 1. Using the menu items <File>, <Change directory>, you can change the active directory or select another directory on your PC.





If you want to control data transfer from the PC, establish the connection with your PC in the following way:

- ▶ Select <File>, <Setup connection>. TNCremoNT now receives the file and directory structure from the TNC and displays this at the bottom left of the main window 2.
- ▶ To transfer a file from the TNC to the PC, select the file in the TNC window with a mouse click and drag and drop the highlighted file into the PC window 1.
- ▶ To transfer a file from the PC to the TNC, select the file in the PC window with a mouse click and drag and drop the highlighted file into the PC window 2.

If you want to control data transfer from the TNC, establish the connection with your PC in the following way:

- ▶ Select <Extras>, <TNCserver>. TNCremoNT is now in server mode. It can receive data from the TNC and send data to the TNC.
- ▶ You can now call the file management functions on the TNC by pressing the key PGM MGT (see "Data transfer to or from an external data medium" on page 59) and transfer the desired files.

#### **End TNCremoNT**

Select the menu items <File>, <Exit>.



Refer also to the TNCremoNT help texts where all of the functions are explained in more detail.



# 12.5 Ethernet Interface

#### Introduction

As an option, you can equip the TNC with an Ethernet card to connect the control as a client in your network. The TNC transmits data through the Ethernet card in accordance with the Transmission Control Protocol/Internet Protocol (TCP/IP) family of protocols and with the aid of the Network File System (NFS). Since TCP/IP and NFS are implemented in UNIX systems, you can usually connect the TNC in the UNIX world without any additional software.

The PC world with Microsoft operating systems, however, also works with TCP/IP, but not with NFS. You will therefore need additional software to connect the TNC to a PC network. For the operating systems Windows 95, Windows 98 and Windows NT 4.0, HEIDENHAIN recommends the network software **CimcoNFS for HEIDENHAIN** which you can order separately or together with the Ethernet card for the TNC.:

Item	HEIDENHAIN ID number
Only software CimcoNFS for HEIDENHAIN	339 737-01
Ethernet card and software CimcoNFS for HEIDENHAIN	293 890-73

# Installing an Ethernet card



Switch-off the TNC and the machine before you install an Ethernet card!

Read the installation instruction supplied with the Ethernet card!

# **Connection possibilities**

You can connect the Ethernet card in your TNC to your network through the RJ45 connection (X26, 10BaseT). The connection is metallically isolated from the control electronics.

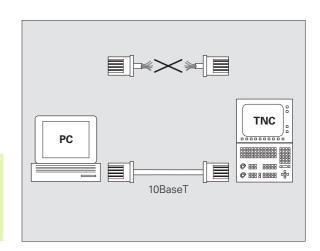
RJ45 connection X26 (10BaseT)

For a 10BaseT connection you need a Twisted Pair cable to connect the TNC to your network.



For unshielded cable, the maximum cable length between the TNC and a node is 100 meters (329 ft). For shielded cable, it is 400 meters (1300 ft).

If you connect the TNC directly with a PC you must use a transposed cable.



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# **Configuring the TNC**



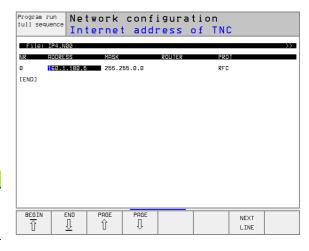
Make sure that the person configuring your TNC is a network specialist.

▶ In the Programming and Editing mode of operation, press the MOD key. Enter the code word NET123. The TNC will then display the main screen for network configuration.

#### **General network settings**

▶ Press the DEFINE NET soft key to enter the general network settings and enter the following information:

Setting	Meaning
ADDRESS	Address that your network manager must assign to the TNC. Input: four decimal numbers separated by points, e.g. 160.1.180.20
MASK	The SUBNET MASK for expanding the number of available addresses within your network. Input: four decimal numbers separated by points. Ask your network manager for the number of your subnet mask, e.g. 255.255.0.0.
ROUTER	Internet address of your default router. Enter the Internet address only if your network consists of several parts. Input: four decimal numbers separated by points. Ask your network manager for your address, e.g. 160.2.0.2.
PROT	Definition of the transmission protocol.
	RFC: Transmission protocol according to RFC 894 IEEE: Transmission protocol according to IEEE 802.2/802.3
HW	Definition of the connection used 10BASET: for use of 10BaseT
HOST	Name, under which the TNC identifies itself in the network. If you are using a host name, you must enter the "Fully Qualified Hostname" here. If you do not enter a name here, the TNC uses the so-called null authentication. The UID, GID, DCM and FCM settings specific to the device (see next page), are then ignored by the TNC.

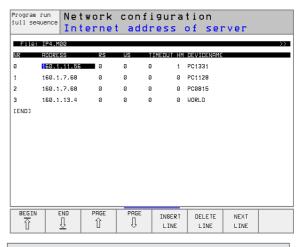


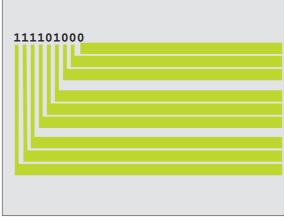


#### Network settings specific to the device

▶ Press the soft key DEFINE MOUNT to enter the network settings for a specific device. You can define any number of network settings, but you can manage only seven at one time.

Setting	Meaning
ADDRESS	Address of your server. Input: four decimal numbers separated by points. Ask your network manager for the number of your address. e.g. 160.1.13.4.
RS	Packet size in bytes for data reception. Input range: 512 to 4 096. Input 0: The TNC uses the optimal packet size as reported by the server.
WS	Packet size in bytes for data transmission. Input range: 512 to 4 096. Input 0: The TNC uses the optimal packet size as reported by the server.
TIMEOUT	Time in ms, after which the TNC repeats a Remote Procedure Call. Input range: 0 to 100 000. Standard input: 700, which corresponds to a TIMEOUT of 700 milliseconds. Use higher values only if the TNC must communicate with the server through several routers. Ask your network manager for the proper timeout setting.
НМ	Definition of whether the TNC should repeat the Remote Procedure Call until the NFS server answers.  0: Always repeat the Remote Procedure Call 1: Do not repeat the Remote Procedure Call
DEVICENAME	Name that the TNC shows in the file manager for a connected device.
PATH	Directory of the NFS server that you wish to connect to the TNC. Be sure to differentiate between small and capital letters when entering the path.
UID	Definition of the User Identification under which you access files in the network. Ask your network manager for the proper timeout setting.
GID	Definition of the group identification with which you access files in the network. Ask your network manager for the proper timeout setting.
DCM	Here you enter the rights of access to the NFS server (see figure at center right). Enter a binary coded value. Example: 111101000 0: Access not permitted 1: Access permitted





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Setting	Meaning
DCM	Here you enter the rights of access to files on the NFS server (see figure at upper right). Enter a binary coded value. Example: 111101000 0: Access not permitted 1: Access permitted
AM	Definition of whether the TNC upon switch-on should automatically connect with the network.  0: Do not automatically connect  1: Connect automatically

#### Defining the network printer

▶ Press the DEFINE PRINT soft key if you wish to print the files on the network printer directly from the TNC.

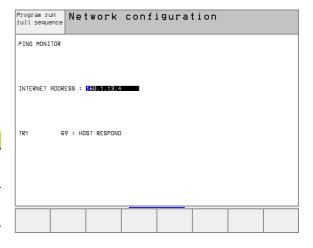
Setting	Meaning
ADDRESS	Address of your server. Input: four decimal numbers separated by points. Ask your network manager for the number of your address. e.g. 160.1.13.4.
DEVICE NAME	Name of printer that the TNC shows when the PRINT soft key is pressed, see "Advanced File Management," page 49
PRINTER NAME	Name of the printer in your network. Ask your network manager.

#### Checking the network connection

- ▶ Press the PING soft key.
- ▶ Enter the Internet address of the device with which you wish to check the connection, and confirm your entry with ENT. The TNC transmits data packets until you exit the test monitor by pressing the END key.

In the TRY line the TNC shows the number of data packets that were transmitted to the previously defined addressee. Behind the number of transmitted data packets the TNC shows the status:

Status display	Meaning
HOST RESPOND	Data packet was received again, connection is OK.
TIMEOUT	Data packet was not received, check the connection.
CAN NOT ROUTE	Data packet could not be transmitted. Check the Internet address of the server and of the router to the TNC.



#### Displaying the error log

▶ Press the SHOW ERROR soft key if you would like to see the error log. Here the TNC records all errors that have occurred in the network since the TNC was last switched on.

The listed error messages are divided into two categories:

Warnings are indicated with (W). Warnings occur when the TNC was able to establish the network connection, but had to correct settings in order to do so.

Error messages are indicated with (E). Error messages occur when the TNC was unable to establish a network connection.

Error message	Cause
LL: (W) CONNECTION xxxxx UNKNOWN USING DEFAULT 10BASET	The name you entered in DEFINE NET, HW was incorrect
LL: (E) PROTOCOL xxxxx UNKNOWN	The name you entered in DEFINE NET, PROT was incorrect
IP4: (E) INTERFACE NOT PRESENT	The TNC was unable to find an Ethernet card.
IP4: (E) INTERNETADDRESS NOT VALID	You used an invalid Internet address for the TNC.
IP4: (E) SUBNETMASK NOT VALID	The SUBNET MASK does not match the Internet address of the TNC.
IP4: (E) SUBNETMASK OR HOST ID NOT VALID	You used an invalid Internet address for the TNC, or you entered an incorrect SUBNET MASK, or you set all of the HostID bits to 0 (1)
IP4: (E) SUBNETMASK OR SUBNET ID NOT VALID	All bits of the SUBNET ID are 0 or 1
IP4: (E) DEFAULTROUTERADRESS NOT VALID	You used an invalid Internet address for the router.
IP4: (E) CAN NOT USE DEFAULTROUTER	The default router does not have the same net ID or subnet ID as the TNC.
IP4: (E) I AM NOT A ROUTER	You defined the TNC as a router.
MOUNT: <device name=""> (E) DEVICENAME NOT VALID</device>	The device name is either too long or it contains illegal characters.
MOUNT: <device name=""> (E) DEVICENAME ALREADY ASSIGNED</device>	You have already defined a device with this name.
MOUNT: <device name=""> (E) DEVICETABLE OVERFLOW</device>	You have attempted to connect more than seven network drives to the TNC.
NFS2: <device name=""> (W) READSIZE SMALLER THEN x SET TO x</device>	The value that you entered for DEFINE MOUNT, RS is too small. The TNC sets RS to 512 bytes.
NFS2: <device name=""> (W) READSIZE LARGER THEN x SET TO x</device>	The value that you entered for DEFINE MOUNT, RS is too large. The TNC sets RS to 4096 bytes.
NFS2: <device name=""> (W) WRITESIZE SMALLER THEN x SET TO x</device>	The value that you entered for DEFINE MOUNT, WS is too small. The TNC sets WS to 512 bytes.

Error message	Cause
NFS2: <device name=""> (W) WRITESIZE LARGER THEN x SET TO x</device>	The value that you entered for DEFINE MOUNT, WS is too large. The TNC sets WS to 4096 bytes.
NFS2: <device name=""> (E) MOUNTPATH TO LONG</device>	The value that you entered for DEFINE MOUNT, PATH is too long.
NFS2: <device name=""> (E) NOT ENOUGH MEMORY</device>	At the moment there is too little main memory available to establish a network connection.
NFS2: <device name=""> (E) HOSTNAME TO LONG</device>	The name you entered in DEFINE NET, HOST is too long.
NFS2: <device name=""> (E) CAN NOT OPEN PORT</device>	The TNC cannot open the port required to establish the network connection.
NFS2: <device name=""> (E) ERROR FROM PORTMAPPER</device>	The TNC has received implausible data from the portmapper.
NFS2: <device name=""> (E) ERROR FROM MOUNTSERVER</device>	The TNC has received implausible data from the mountserver.
NFS2: <device name=""> (E) CANT GET ROOTDIRECTORY</device>	The mount server does not permit a connection with the directory defined in DEFINE MOUNT, PATH.
NFS2: <device name=""> (E) UID OR GID 0 NOT ALLOWED</device>	You entered 0 for DEFINE MOUNT, UID or GID 0. The input value 0 is reserved for the system administrator.



# 12.6 Configuring PGM MGT

# **Function**

With this function you can determine the features of the file manager:

- Standard: Simple file management without directory display
- Expanded range: File management with additional functions and directory display



Note: see "Standard File Management," page 41, and see "Advanced File Management," page 49.

# Changing the setting

- Select the file manager in the Programming and Editing mode of operation: press the PGM MGT key
- ▶ Select the MOD function: Press the MOD key
- ▶ Select the PGM MGT setting: using the arrow keys, move the highlight onto the PGM MGT setting and use the ENT key to switch between STANDARD and ENHANCED.

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# 12.7 Machine-Specific User Parameters

# **Function**

To enable you to set machine-specific functions, your machine tool builder can define up to 16 machine parameters as user parameters.



This function is not available on every TNC. Refer to your machine manual.

ions 1

# 12.8 Showing the workpiece in the working space

#### **Function**

This MOD function enables you to graphically check the position of the workpiece blank in the machine's working space and to activate work space monitoring in the Test Run mode of operation. This function is activated with the BLANK IN WORD SPACE soft key.

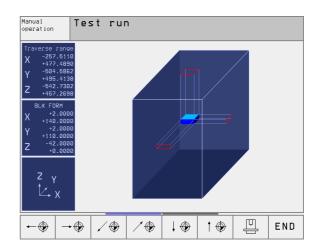
The TNC displays a cuboid for the working space. Its dimensions are shown in the "Traverse range" window. The TNC takes the dimensions for the working space from the machine parameters for the active traverse range. Since the traverse range is defined in the reference system of the machine, the datum of the cuboid is also the machine datum. You can see the position of the machine datum in the cuboid by pressing the soft key M91 in the 2nd soft-key row.

Another cuboid represents the blank form. The TNC takes its dimensions from the workpiece blank definition in the selected program. The workpiece cuboid defines the coordinate system for input. Its datum lies within the cuboid. You can see in the cuboid the position of the datum for input by pressing the corresponding soft key in the 2nd soft-key row.

For a test run it normally does not matter where the workpiece blank is located within the working space. However, if you test programs that contain movements with M91 or M92, you must graphically shift the workpiece blank to prevent contour damage. Use the soft keys shown in the table at right.

You can also activate the working-space monitor for the Test Run mode in order to test the program with the current datum and the active traverse ranges (see table below, last line).

Function	Soft key
Move workpiece blank to the left	
Move workpiece blank to the right	$\boxed{\rightarrow \bigoplus}$
Move workpiece blank forward	/⊕
Move workpiece blank backward	/⊕
Move workpiece blank upward	↑ →
Move workpiece blank downward	↓ ⊕
Show workpiece blank referenced to the set datum	



Function	Soft key
Show the entire traversing range referenced to the displayed workpiece blank	
Show the machine datum in the working space	M91 🍑
Show a position determined by the machine tool builder (e.g. tool change position) in the working space	M92 🔷
Show the workpiece datum in the working space.	•
Enable (ON) or disable (OFF) work space monitoring	H <del> →</del> H OFF ∕ ON

DD Functions 1

# 12.9 Position Display Types

# **Function**

In the Manual Operation mode and in the program run modes of operation, you can select the type of coordinates to be displayed.

The figure at right shows the different tool positions:

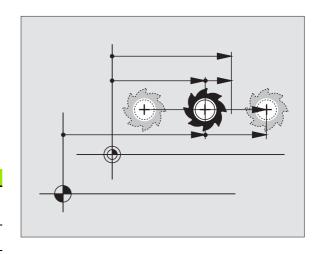
- Starting position
- Target position of the tool
- Workpiece datum
- Machine datum

The TNC position displays can show the following coordinates:

Function	Display
Nominal position: the value presently commanded by the TNC	NOML.
Actual position; current tool position	ACTL.
Reference position; the actual position relative to the machine datum	REF
Distance remaining to the programmed position; difference between actual and target positions	DIST.
Servo lag: difference between nominal and actual positions (following error)	LAG
Deflection of the measuring touch probe	DEFL.
Traverses that were carried out with handwheel superpositioning (M118) (only position display 2)	M118

With the MOD function Position display 1 you can select the position display in the status display.

With Position display 2 you can select the position display in the additional status display.



# 12.10 Select the unit of measurement

# **Function**

This MOD function determines whether the coordinates are displayed in millimeters (metric system) or inches.

- To select the metric system (e.g. X = 15.789 mm) set the Change mm/inches function to mm. The value is displayed to 3 decimal places.
- To select the inch system (e.g. X = 0.6216 inch) set the Change mm/inches function to inches. The value is displayed to 4 decimal places.

If you would like to activate the inch display, the TNC shows the feed rate in inch/min. In an inch program you must enter the feed rate large by a factor of 10.

12 MOD Functions

# 12.11 Select the programming Language for \$MDI

# **Function**

The Program input mod function lets you decide whether to program the \$MDI file in HEIDENHAIN conversational dialog or in ISO format.

- To program the \$MDI.H file in conversational dialog, set the Program input function to HEIDENHAIN
- To program the \$MDI.I file according to ISO, set the Program input function to ISO

12.11 Sel<mark>ect</mark> the programming Language for \$MD

# 12.12 Selecting the Axes for Generating L Blocks

# **Function**

The axis selection input field enables you to define the current tool position coordinates that are transferred to an L block. To generate a separate L block, press the ACTUAL-POSITION-CAPTURE soft key. The axes are selected by bit-oriented definition similar to programming the machine parameters:

Axis selection %11111Transfer the X, Y, Z, IV and V axes

Axis selection %01111Transfer the X, Y, Z and IV axes

Axis selection %00111Transfer the X, Y and Z axes

Axis selection %00011Transfer the X and Y axes

Axis selection %00001Transfer the X axis

# 12.13 Enter the axis traverse limits, datum display

#### **Function**

The AXIS LIMIT mod function allows you to set limits to axis traverse within the machine's actual working envelope.

Possible application: to protect an indexing fixture against tool collision.

The maximum range of traverse of the machine tool is defined by software limit switches. This range can be additionally limited through the TRAVERSE RANGE mod function. With this function, you can enter the maximum and minimum traverse positions for each axis, referenced to the machine datum. If several traverse ranges are possible on your machine, you can set the limits for each range separately using the soft keys TRAVERSE RANGE (1) to TRAVERSE RANGE (3).

# Working without additional traverse limits

To allow a machine axis to use its full range of traverse, enter the maximum traverse of the TNC (+/- 99999 mm) as the TRAVERSE RANGE

#### To find and enter the maximum traverse:

- ▶ Set the Position display mod function to REF.
- Move the spindle to the positive and negative end positions of the X, Y and Z axes.
- Write down the values, including the algebraic sign.
- ▶ To select the MOD functions, press the MOD key.



- ▶ Enter the limits for axis traverse: Press the TRAVERSE RANGE soft key and enter the values that you wrote down as limits in the corresponding axes
- To exit the MOD function, press the END soft key

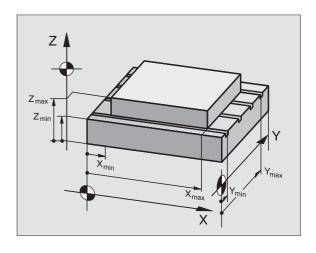


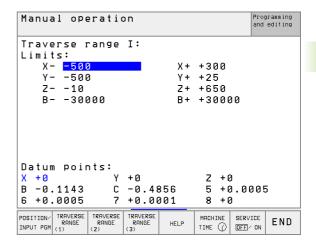
The tool radius is not automatically compensated in the axis traverse limit value.

The traverse range limits and software limit switches become active as soon as the reference points are traversed.

# **Datum display**

The values shown at the lower left of the screen are the manually set datums referenced to the machine datum. They cannot be changed in the menu.





# 12.14 Displaying HELP Files

# **Function**

Help files can aid you in situations in which you need clear instructions before you can continue (for example, to retract the tool after an interruption of power). The miscellaneous functions may also be explained in a help file. The figure at right shows the screen display of a help file.



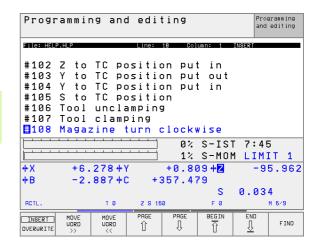
HELP files are not provided on every machine. Your machine tool builder can provide you with further information on this feature.

# **Selecting HELP files**

Select the MOD function: Press the MOD key



- To select the last active HELP file, press the HELP soft key.
- Call the file manager (PGM MGT key) and select a different help file, if necessary.



# 12.15 Displaying Operating Time

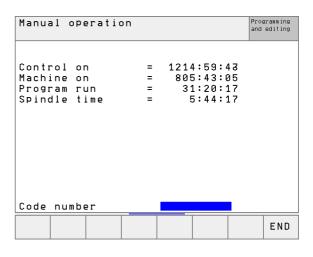
# **Function**



The machine tool builder can provide further operating time displays. The machine tool manual provides further information.

The MACHINE TIME soft key enables you to show different operating time displays:

Operating time	Meaning
Control ON	Operating time of the control since its commissioning
Machine ON	Operating time of the machine tool since commissioning
Program run	Duration of controlled operation since initial setup



# 12.16 Teleservice

## **Function**



The Teleservice functions are enabled and adapted by the machine tool builder. The machine tool manual provides further information.

The TNC provides two soft keys for the Teleservice, making it possible to configure two different service agencies.

The TNC allows you to carry out Teleservice. To be able to use this feature, your TNC should be equipped with an Ethernet card which achieves a higher data transfer rate than the serial RS232-C interface.

With the HEIDENHAIN TeleService software, your machine tool builder can then establish a connection to the TNC via an ISDN modem and carry out diagnostics. The following functions are available:

- On-line screen transfer
- Polling of machine states
- Data transfer
- Remote control of the TNC

Generally, a connection via the Internet would also be possible. First tests have shown, however, that the transfer rate that can currently be achieved is not sufficient due to the high degree of utilization of the networks.

# **Calling/Exiting Teleservice**

- ▶ Select any machine mode of operation.
- To select the MOD function, press the MOD key.



- ▶ Establish a connection to the service agency: Set the SERVICE or SUPPORT soft key to ON. The TNC breaks the connection automatically if no new data have been transferred for a time set by the machine tool builder (default: 15 min).
- ▶ To break the connection to the service agency: Set the SERVICE or SUPPORT soft key to OFF. The TNC terminates the connection after approx. one minute.



12 MOD Functions

# 12.17 External Access

### **Function**



The machine tool builder can configure Teleservice settings with the LSV-2 interface. The machine tool manual provides further information.

The soft key SERVICE can be used to grant or restrict access through the LSV-2 interface.

With an entry in the configuration file TNC.SYS you can protect a directory and its subdirectories with a password. The password is requested when data from this directory is accessed from the LSV-2 interface. Enter the path and password for external access in the configuration file TNC.SYS.



The TNC.SYS file must be stored in the root directory TNC:\.

If you only supply one entry for the password, then the entire drive TNC:\ is protected.

You should use the updated versions of the HEIDENHAIN software TNCremo or TNCremoNT to transfer the data.

Entries in TNC.SYS	Meaning
REMOTE.TNCPASSWORD=	Password for LSV-2 access
REMOTE.TNCPRIVATEPATH=	Path to be protected

#### **Example of TNC.SYS**

REMOTE.TNCPASSWORD=KR1402

REMOTE.TNCPRIVATEPATH=TNC:\RK

#### Permitting/Restricting external access

- ▶ Select any machine mode of operation.
- ▶ To select the MOD function, press the MOD key.



- ▶ Permit a connection to the TNC: Set the EXTERNAL ACCESS soft key to ON. The TNC will then permit data access through the LSV-2 interface. The password is requested when a directory that was entered in the configuration file TNC.SYS is accessed.
- Block connections to the TNC: Set the EXTERNAL ACCESS soft key to OFF. The TNC will then block access through the LSV-2 interface.



# 13

# 13.1 General User Parameters

General user parameters are machine parameters affecting TNC settings that the user may want to change in accordance with his requirements.

Some examples of user parameters are:

- Dialog language
- Interface behavior
- Traversing speeds
- Sequence of machining
- Effect of overrides

# Input possibilities for machine parameters

Machine parameters can be programmed as

#### ■ Decimal numbers

Enter only the number

#### ■ Pure binary numbers

Enter a percent sign (%) before the number

#### Hexadecimal numbers

Enter a dollar sign (\$) before the number

#### **Example:**

Instead of the decimal number 27 you can also enter the binary number %11011 or the hexadecimal number \$1B.

The individual machine parameters can be entered in the different number systems.

Some machine parameters have more than one function. The input value for these machine parameters is the sum of the individual values. For these machine parameters the individual values are preceded by a plus sign.

# Selecting general user parameters

General user parameters are selected with code number 123 in the MOD functions.



The MOD functions also include machine-specific user parameters.

External data transfer	
Integrating TNC interfaces EXT1 (5020.0) and EXT2 (5020.1) to an external device	MP5020.x 7 data bits (ASCII code, 8th bit = parity): +0 8 data bits (ASCII code, 9th bit = parity): +1
	Block Check Character (BCC) any: <b>+0</b> Block Check Character (BCC) control character not permitted: <b>+2</b>
	Transmission stop through RTS active: <b>+4</b> Transmission stop through RTS inactive: <b>+0</b>
	Transmission stop through DC3 active: <b>+8</b> Transmission stop through DC3 inactive: <b>+0</b>
	Character parity even: <b>+0</b> Character parity odd: <b>+16</b>
	Character parity not desired: <b>+0</b> Character parity desired: <b>+32</b>
	11/2 stop bits: <b>+0</b> 2 stop bit: <b>+64</b>
	1 stop bit: <b>+128</b> 1 stop bit: <b>+192</b>
	Example:
	Use the following setting to adjust the TNC interface EXT2 (MP 5020.1) to an external non-HEIDENHAIN device:
	8 data bits, any BCC, transmission stop through DC3, even character parity, character parity desired, 2 stop bits
	Input for <b>MP 5020.1</b> : 1+0+8+0+32+64 = <b>105</b>
Interface type for EXT1 (5030.0) and EXT2 (5030.1)	MP5030.x Standard transmission: 0 Interface for blockwise transfer: 1
3-D touch probes and digitizing	
Select touch probe (only with option for digitizing with measuring touch probe)	MP6200 Triggering touch probe: 0 Measuring touch probe: 1
Select signal transmission	MP6010 Touch probe with cable transmission: 0 Touch probe with infrared transmission: 1
Probing feed rate for triggering touch probes	MP6120 1 to 3 000 [mm/min]
Maximum traverse to first probe point	MP6130 0.001 to 99 999.9999 [mm]
Safety clearance to probing point during automatic measurement	MP6140 0.001 to 99 999.9999 [mm]

Rapid traverse for triggering touch probes	MP6150
hapid traverse for triggering touch probes	1 to 300 000 [mm/min]
Measure center misalignment of the stylus when calibrating a triggering touch probe	MP6160  No 180° rotation of the 3-D touch probe during calibration: 0  M function for 180° rotation of the touch probe during calibration: 1 to 99
M function for orienting the infrared sensor before each measuring cycle	MP6161 Function inactive: 0 Orientation directly through the NC: -1 M function for orienting the touch probe: 1 to 999
Angle of orientation for the infrared sensor	MP6162 0 to 359.9999 [°]
Difference between the current angle of orientation and the angle of orientation set in MP 6162; when the entered difference is reached, an oriented spindle stop is to be carried out.	MP6163 0 to 3.0000 [°]
Automatically orient the infrared sensor before probing to the programmed probing direction	MP6165 Function inactive: 0 Orient infrared sensor: 1
Multiple measurement for programmable probe function	MP6170 1 to 3
Confidence range for multiple measurement	MP6171 0.001 to 0.999 [mm]
Automatic calibration cycle: Center of the calibration ring in the X-axis referenced to the machine datum	MP6180.0 (traverse range 1) to MP6180.2 (traverse range3) 0 to 99 999.9999 [mm]
Automatic calibration cycle: Center of the calibration ring in the Y-axis referenced to the machine datum for	MP6181.x (traverse range 1) to MP6181.2 (traverse range3) 0 to 99 999.9999 [mm]
Automatic calibration cycle: Center of the calibration ring in the Z-axis referenced to the machine datum for	MP6182.x (traverse range 1) to MP6182.2 (traverse range3) 0 to 99 999.9999 [mm]
Automatic calibration cycle: distance below the upper edge of the ring where the calibration is carried out by the TNC	MP6185.x (traverse range 1) to MP6185.2 (traverse range 3) 0.1 to 99 999.9999 [mm]
Infeed of the stylus when digitizing with the measuring touch probe	MP6310 0.1 to 2.0000 [mm] (recommended: 1 mm)
Measure center misalignment of the stylus when calibrating a measuring touch probe	MP6321 Measure center misalignment: 0 Do not measure center misalignment: 1

3-D touch probes and digitizing	
Assign touch probe axis to machine axis for a measuring touch probe	MP6322.0  Machine X axis parallel to touch probe axis X: 0, Y: 1, Z: 2
Note:	MP6322.1
Ensure that the touch probe axes are correctly	Machine Y axis parallel to touch probe axis X: 0, Y: 1, Z: 2
assigned to the machine axes. Wrong assignment could lead to a stylus break.	MP6322.2
assignment could lead to a stylus broak.	Machine <b>Z</b> axis parallel to touch probe axis X: <b>0</b> , Y: <b>1</b> , Z: <b>2</b>
Maximum stylus deflection of the	MP6330
measuring touch probe	<b>0.1</b> to <b>4.0000</b> [mm]
Feed rate for positioning measuring touch probes at MIN point and approaching the contour	MP6350 1 to 3 000 [mm/min]
Probe feed rate for measuring touch probes	MP6360 1 to 3 000 [mm/min]
Rapid traverse for measuring touch probes in the probe cycle	MP6361 10 to 3 000 [mm/min]
Feed rate reduction when the stylus of a measuring touch probe is deflected to the side	MP6362 Feed rate reduction not active: 0 Feed rate reduction active: 1
The TNC decreases the feed rate according to a preset characteristic curve. The minimum input value is 10% of the programmed digitizing feed rate.	
Radial acceleration during digitizing with the measuring touch probe	MP6370 0.001 to 5.000 [m/s <sup>2</sup> ] (recommended input value: 0.1)
MP6370 enables you to limit the feed rate of the TNC for circular movements during digitizing. Circular movements are caused, for example, by sharp changes of direction.	
As long as the programmed digitizing feed rate is less than the feed rate calculated with MP6370, the TNC will move at the programmed feed rate. Determine the appropriate value for your requirements by trial and error.	
Target window for digitizing contour lines with a measuring touch probe	MP6390 0.1 to 4.0000 [mm]
When you are digitizing contour lines the individual contour lines do not end exactly in their starting points.	
With machine parameter MP6390 you can define a square target window within which the end point must lie after the touch probe has orbited the model. Enter half the side length of the target window for the side length.	

Radius measurement with the TT 130 touch	MP6505.0 (traverse range 1) to 6505.2 (traverse range 3)
probe: Probing direction	Positive probing direction in the angle reference axis (0° axis): 0
	Positive probing direction in the +90° axis: 1
	Negative probing direction in the angle reference axis (0° axis): 2
	Negative probing direction in the +90° axis: 3
Probing feed rate for second measurement	MP6507
with TT 120, stylus shape, corrections in TOOL.T	Calculate feed rate for second measurement with TT 130, with constant tolerance: +0
TOOL.1	Calculate feed rate for second measurement with TT 130,
	with variable tolerance: +1
	Constant feed rate for second measurement with TT 130: +2
Maximum permissible measuring error	MP6510
with TT 130 during measurement with	<b>0.001</b> to <b>0.999</b> [mm] (recommended input value: 0.005 mm)
rotating tool	
Required for calculating the probing feed rate in	
connection with MP6570	
Feed rate for probing a stationary tool with	MP6520
the TT 130	1 to 3 000 [mm/min]
Radius measurement with the TT 130:	MP6530.0 (traverse range 1) to MP6530.2 (traverse range 3)
Distance from lower edge of tool to upper	<b>0.001</b> to <b>99.9999</b> [mm]
edge of stylus	
Set-up clearance in the tool axis above the	MP6540.0
stylus of the TT 130 for pre-positioning	<b>0.001</b> to <b>30 000.000</b> [mm]
Clearance zone in the machining plane	MP6540.1
around the stylus of the TT 130 for pre-	<b>0.001</b> to <b>30 000.000</b> [mm]
positioning	
Rapid traverse for TT 130 in the probe cycle	MP6550
	<b>10</b> to <b>10 000</b> [mm/min]
M function for spindle orientation when	MP6560
measuring individual teeth	<b>0</b> to <b>999</b>
Measuring rotating tools: Permissible	MP6570
rotational speed at the circumference of the	<b>1.000</b> to <b>120.000</b> [m/min]
milling tool	
Required for calculating rpm and probe feed	
rate	
Measuring rotating tools: Permissible	MP6572
rotational rpm	<b>0.000</b> to <b>1 000.000</b> [rpm] If you enter 0, the speed is limited to 1000 rpm

#### 3-D touch probes and digitizing

Coordinates of the TT 120 stylus center relative to the machine datum

MP6580.0 (traverse range 1)

X axis

MP6580.1 (traverse range 1)

Y axis

MP6580.2 (traverse range 1)

Z axis

MP6581.0 (traverse range 2)

X axis

MP6581.1 (traverse range 2)

Y axis

MP6581.2 (traverse range 2)

Z axis

MP6582.0 (traverse range 3)

X axis

MP6582.1 (traverse range 3)

Y axis

MP6582.2 (traverse range 3)

Z axis

TNC dis	plays, T	NC editor
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Programming station MP7210

TNC with machine: 0

TNC as programming station with active PLC: **1** TNC as programming station with inactive PLC: **2** 

Acknowledgment of POWER INTERRUPTED after switch-on

**MP7212** 

Acknowledge with key: **0** Acknowledge automatically: **1** 

ISO programming: Set the block number increment

MP7220

0 to 150

Disabling the selection of file types

MP7224.0

All file types selectable via soft key: +0

Disable selection of HEIDENHAIN programs (soft key SHOW .H): +1

Disable selection of ISO programs (soft key SHOW .1): +2
Disable selection of tool tables (soft key SHOW .T): +4
Disable selection of datum tables (soft key SHOW .D): +8
Disable selection of pallet tables (soft key SHOW .P): +16
Disable selection of text files (soft key SHOW .A):+32
Disable selection of point tables (soft key SHOW .PNT): +64

TNC displays, TNC edito	···
Disabling the editor for certain file types  Note:  If a particular file type is inhibited, the TNC will erase all files of this type.	MP7224.1 Do not disable editor: +0 Disable editor for  HEIDENHAIN programs: +1 ISO programs: +2 Tool tables: +4 Datum tables: +8 Pallet tables: +16 Text files: +32 Point tables: +64
Configure pallet files	MP7226.0 Pallet table inactive: 0 Number of pallets per pallet table: 1 to 255
Configure datum files	MP7226.1 Datum table inactive: 0 Number of datums per datum table: 1 to 255
Program length for program check	MP7229.0 Blocks 100 to 9 999
Program length up to which FK blocks are permitted	MP7229.1 Blocks <b>100</b> to <b>9</b> 999
Dialog language	MP7230 English: 0 German: 1 Czech: 2 French: 3 Italian: 4 Spanish: 5 Portuguese: 6 Swedish: 7 Danish: 8 Finnish: 9 Dutch: 10 Polish: 11 Hungarian: 12 reserved: 13 Russian: 14
Internal clock of the TNC	MP7235 Universal time (Greenwich time): 0 Central European Time (CET): 1 Central European Summertime: 2 Time difference to universal time: -23 to +23 [hours]



TNC displays, TNC edito	or and the second se
Configure tool tables	MP7260 Inactive: 0 Number of tools generated by the TNC when a new tool table is opened: 1 to 254 If you require more than 254 tools, you can expand the tool table with the function APPEND N LINES, see "Tool Data," page 99
Configure pocket tables	MP7261.0 (magazine 1) MP7261.1 (magazine 2) MP7261.2 (magazine 3) MP7261.3 (magazine 4) Inactive: 0 Number of pockets in the tool magazine: 1 to 254 If the value 0 is entered in MP 7261.1 to MP7261.3, then only one tool magazine will be used.
Index tool numbers in order to be able to assign different compensation data to one tool number	MP7262 Do not index: 0 Number of permissible indices: 1 to 9
Soft key for pocket tables	MP7263 Show the POCKET TABLE soft key in the tool table: 0 Do not show the POCKET TABLE soft key in the tool table: 1
Configure tool table (To omit from the table: enter 0); Column number in the tool table for	MP7266.0 Tool name – NAME: 0 to 31; column width: 16 characters MP7266.1 Tool length – L: 0 to 31; column width: 11 characters MP7266.2 Tool radius – R: 0 to 31; column width: 11 characters MP7266.3 Tool radius 2 – R2: 0 to 31; column width: 11 characters MP7266.4 Oversize length – DL: 0 to 31; column width: 8 characters MP7266.5 Oversize radius – DR: 0 to 31; column width: 8 characters MP7266.6 Oversize radius 2 – DR2: 0 to 31; column width: 8 characters MP7266.7 Tool locked – TL: 0 to 31; column width: 2 characters MP7266.8 Replacement tool – RT: 0 to 31; column width: 3 characters MP7266.9 Maximum tool life – TIME1: 0 to 31; column width: 5 characters MP7266.10 Maximum tool life for TOOL CALL – TIME2: 0 to 31; column width: 5 characters MP7266.11 Current tool life – CUR. TIME: 0 to 31; column width: 8 characters

#### TNC displays, TNC editor

Configure tool table (To omit from the table: enter 0); Column number in the tool table for MP7266.12

Tool comment – DOC: **0** to **31**; column width: 16 characters

MP7266.13

Number of teeth - CUT.: 0 to 31; column width: 4 characters

MP7266.14

Tolerance for wear detection in tool length – LTOL: 0 to 31; column width: 6 characters

MP7266.15

Tolerance for wear detection in tool radius - RTOL: 0 to 31; column width: 6 characters

MP7266.16

Cutting direction – DIRECT.: 0 to 31; column width: 7 characters

MP7266.17

PLC status - PLC: 0 to 31: column width: 9 characters

MP7266.18

Offset of the tool in the tool axis in addition to MP6530 - TT:L-OFFS: 0 to 31

column width: 11 characters

MP7266.19

Offset of the tool between stylus center and tool center – TT:R-OFFS: 0 to 31

column width: 11 characters

MP7266.20

Tolerance for break detection in tool length - LBREAK: 0 to 31; column width: 6 characters

MP7266.21

Tolerance for break detection in tool radius - RBREAK: 0 to 31; column width: 6 characters

MP7266.22

Tooth length (Cycle 22) – LCUTS: **0** to **31**; column width: 11 characters

MP7266.23

Maximum plunge angle (Cycle 22) - ANGLE.: 0 to 31; column width: 7 characters

MP7266.24

Tool type -TYP: 0 to 31; column width: 5 characters

MP7266.25

Tool material - TMAT: 0 to 31; column width: 16 characters

MP7266.26

Cutting data table - CDT: 0 to 31; column width: 16 characters

MP7266.27

PLC value - PLC-VAL: 0 to 31; column width: 11 characters

MP7266.28

Center misalignment in reference axis – CAL-OFF1: 0 to 31; column width: 11 characters

MP7266.29

Center misalignment in minor axis – CAL-OFF2: 0 to 31: column width: 11 characters

MP7266.30

Spindle angle for calibration – CALL-ANG: 0 to 31; column width: 11 characters

Configure pocket tables; Column number in the tool table for (To omit from the table: enter 0) MP7267.0

Tool number – T: 0 to 7

MP7267.1

Special tool - ST: 0 to 7

MP7267.2

Fixed pocket - F: 0 to 7

MP7267.3

Pocket locked - L: 0 to 7

MP7267.4

PLC status - PLC: 0 to 7

MP7267.5

Tool name from tool table - TNAME: 0 to 7

MP7267.6

Comment from tool table - DOC: 0 to 7

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TNC diaplace TNC adito	
TNC displays, TNC edito	
Manual Operation mode: Display of feed rate	MP7270 Display feed rate F only if an axis direction button is pressed: 0 Display feed rate F even if no axis direction button is pressed (feed rate defined via soft key F or feed rate of the "slowest" axis): 1
Decimal character	MP7280 The decimal character is a comma: 0 The decimal character is a point: 1
Display mode	MP7281.0 Programming and Editing operating mode
	MP7281.1 Program run mode Always display multiple line blocks completely: 0 Display multiline blocks completely if the multiline block is the active block: 1 Display multiline blocks completely if the multiline block is being edited: 2
Position display in the tool axis	MP7285 Display is referenced to the tool datum: 0 Display in the tool axis is referenced to the tool face: 1
Display step for the spindle position	MP7289 0.1 °: 0 0.05 °: 1 0.01 °: 2 0.005 °: 3 0.001 °: 4 0.0005 °: 5 0.0001 °: 6
Display step	MP7290.0 (X axis) to MP7290.8 (9th axis) 0.1 mm: 0 0.05 mm: 1 0.01 mm: 2 0.005 mm: 3 0.001 mm: 4 0.0005 mm: 5 0.0001 mm: 6
Disable datum setting	MP7295  Do not disable datum setting: +0 Disable datum setting in the X axis: +1 Disable datum setting in the Y axis: +2 Disable datum setting in the Z axis: +4 Disable datum setting in the IVth axis: +8 Disable datum setting in the Vth axis: +16 Disable datum setting in the 6th axis: +32 Disable datum setting in the 7th axis: +64 Disable datum setting in the 8th axis: 128 Disable datum setting in the 9th axis: +256
Disable datum setting with the orange axis keys	MP7296 Do not disable datum setting: 0 Disable datum setting with the orange axis keys: 1



Reset status display, Q parameters and tool data  MP7300 Reset them all when a program is selected: 0 Reset only status display and tool data when a program is selected: 2 Reset only status display and tool data when a program is selected: 2 Reset only status display and tool data when a program is selected: 2 Reset only status display and tool data when a program is selected: 4 Reset status display and Q parameters when a program is selected: 4 Reset status display and Q parameters when a program is selected: 4 Reset status display when a program is selected: 6 Reset status display when a program is selected: 6 Reset status display when a program is selected and with M02, M30, END PGM: 5 Reset status display when a program is selected and with M02, M30, END PGM: 7  MP7310 Projection in three planes according to ISO 6433, projection method 1: +1 Projection in three planes according to ISO 6433, projection method 2: +1 Do not rotate coordinate system for graphic display: +0 Rotate coordinate system for		
Reset them all when a program is selected and with M02, M30, END PGM: 1 Reset only status display and tool data when a program is selected: 2 Reset only status display and tool data when a program is selected: 4 Reset status display and Q parameters when a program is selected: 4 Reset status display and Q parameters when a program is selected and with M02, M30, END PGM: 5 Reset status display when a program is selected: 6 Reset status display when a program is selected: 6 Reset status display when a program is selected: 6 Reset status display when a program is selected and with M02, M30, END PGM: 7  Graphic display mode  MP7310 Projection in three planes according to ISO 6433, projection method 1: +1 Projection in three planes according to ISO 6433, projection method 2: +1 Do not rotate coordinate for graphic display by 90°: +2 Display new BLK FORM in Cycle 7 DATUM SHIFT referenced to the old datum: +0 Display new BLK FORM in Cycle 7 DATUM SHIFT referenced to the new datum: +4 Do not show cursor position during projection in three planes: +8  Graphic simulation without programmed tool axis: M function for start  MP7316 0 to 99 999.9999 [mm]  MP7317.0 0 to 88 (0: Function inactive)  MP7317.1 0 to 88 (0: Function inactive)  MP7319.2 0 to 99 [min] (0: Function inactive)	TNC displays, TNC edito Reset status display, Q	MP7300
Projection in three planes according to ISO 6433, projection method 1: +1 Projection in three planes according to ISO 6433, projection method 2: +1 Do not rotate coordinate for graphic display: +0 Rotate coordinate system for graphic display by 90°: +2 Display new BLK FORM in Cycle 7 DATUM SHIFT referenced to the old datum: +0 Display new BLK FORM in Cycle 7 DATUM SHIFT referenced to the new datum: +4 Do not show cursor position during projection in three planes: +0 Show cursor position during projection in three planes: +8  Graphic simulation without programmed tool axis: Penetration depth  MP7315 0 to 99 999.9999 [mm]  MP7316 0 to 99 999.9999 [mm]  MP7317.0 0 to 88 (0: Function inactive)  MP7317.1 0 to 88 (0: Function inactive)  Screen saver Enter the time after which the TNC should		Reset them all when a program is selected and with M02, M30, END PGM: <b>1</b> Reset only status display and tool data when a program is selected: <b>2</b> Reset only status display and tool data when a program is selected and with M02, M30, END PGM: <b>3</b> Reset status display and Q parameters when a program is selected: <b>4</b> Reset status display and Q parameters when a program is selected and with M02, M30, END PGM: <b>5</b> Reset status display when a program is selected: <b>6</b>
without programmed tool axis: Tool radius  Graphic simulation without programmed tool axis: Penetration depth  Graphic simulation without programmed tool axis: M function for start  Graphic simulation without programmed tool axis: M function for start  Graphic simulation without programmed tool axis: M function for end  MP7317.0  0 to 88 (0: Function inactive)  MP7317.1  0 to 88 (0: Function inactive)  Screen saver  Enter the time after which the TNC should	Graphic display mode	Projection in three planes according to ISO 6433, projection method 1: +1 Projection in three planes according to ISO 6433, projection method 2: +1 Do not rotate coordinate for graphic display: +0 Rotate coordinate system for graphic display by 90°: +2 Display new BLK FORM in Cycle 7 DATUM SHIFT referenced to the old datum: +0 Display new BLK FORM in Cycle 7 DATUM SHIFT referenced to the new datum: +4 Do not show cursor position during projection in three planes: +0
without programmed tool axis: Penetration depth  Graphic simulation without programmed tool axis: M function for start  Graphic simulation without programmed tool axis: M function for start  Graphic simulation without programmed tool axis: M function for end  MP7317.1 0 to 88 (0: Function inactive)  Screen saver Enter the time after which the TNC should	Graphic simulation without programmed tool axis: Tool radius	
without programmed tool axis: M function for start  Graphic simulation without programmed tool axis: M function for end  MP7317.1 0 to 88 (0: Function inactive)  MP7317.1 0 to 88 (0: Function inactive)  MP7317.1 0 to 99 [min] (0: Function inactive)	Graphic simulation without programmed tool axis: Penetration depth	70.0
without programmed tool axis: M function for end  Screen saver Enter the time after which the TNC should  O to 88 (0: Function inactive)  MP7392 O to 99 [min] (0: Function inactive)	Graphic simulation without programmed tool axis: M function for start	
Enter the time after which the TNC should  0 to 99 [min] (0: Function inactive)	Graphic simulation without programmed tool axis: M function for end	
Enter the time after which the TNC should	Screen saver	
	which the TNC should	0 to 99 [min] (0: Function inactive)

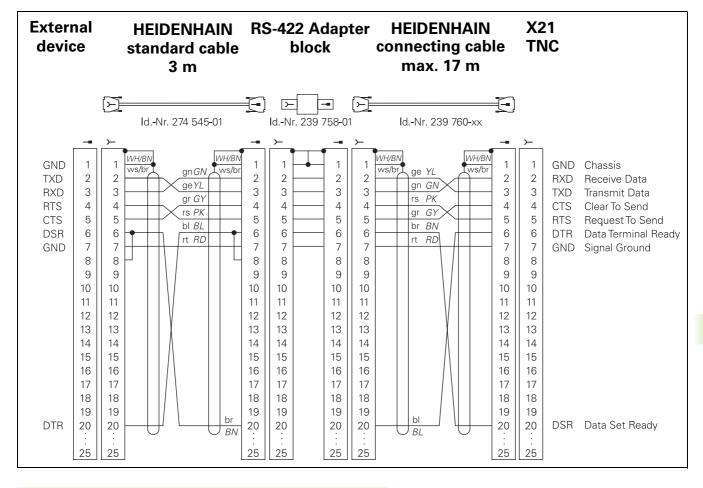


Machining and program run	
Cycle 17: Oriented spindle stop at beginning of cycle	MP7160 Oriented spindle stop: 0 No oriented spindle stop: 1
Effect of Cycle 11 SCALING FACTOR	MP7410 SCALING FACTOR effective in 3 axes: 0 SCALING FACTOR effective in the working plane only: 1
Manage tool data/calibration data	MP7411 Overwrite current tool data by the calibrated data from the 3-D touch probe system: +0 Current tool data are retained: +1 Manage calibrated data in the calibration menu: +0 Manage calibrated data in the tool table: +2
SL cycles	MP7420 Mill channel around the contour - clockwise for islands and counterclockwise for pockets: +0 Mill channel around the contour - clockwise for pockets and counterclockwise for islands: +1 First mill the channel, then rough out the contour: +0 First rough out the contour, then mill the channel: +2 Combine compensated contours: +0 Combine uncompensated contours: +4 Complete one process for all infeeds before switching to the other process: +0 Mill channel and rough-out for each infeed depth before continuing to the next depth: +8  The following note applies to the Cycles 6, 15, 16, 21, 22, 23, and 24: At the end of the cycle, move the tool to the position that was last programmed before the cycle call: +0 At the end of the cycle, retract the tool in the tool axis only: +16
Cycle 4 POCKET MILLING and Cycle 5 CIRCULAR POCKET MILLING: Overlap factor	MP7430 0.1 to 1.414
Permissible deviation of circle radius between circle end point and circle starting point	MP7431 0.0001 to 0.016 [mm]
Operation of various miscellaneous functions M	MP7440 Program stop with M06: +0
Note:	No program stop with M06: <b>+1</b> No cycle call with M89: <b>+0</b>
The k $_{\rm V}$ factors for position loop gain are set by the machine tool builder. Refer to your machine manual.	Cycle call with M89: <b>+2</b> Program stop with M functions: <b>+0</b> No program stop with M functions: <b>+4</b> $k_V$ factors cannot be switched through M105 and M106: <b>+0</b> $k_V$ factors switchable through M105 and M106: <b>+8</b> Reduce the feed rate in the tool axis with M103 F Function inactive: <b>+0</b> Reduce the feed rate in the tool axis with M103 F Function active: <b>+16</b> Exact stop for positioning with rotary axes inactive: <b>+0</b> Exact stop for positioning with rotary axes active: <b>+32</b>

Error message during cycle call	MP7441 Error message when M3/M4 not active: 0 Suppress error message when M3/M4 not active: +1 reserved: +2 Suppress error message when positive depth programmed: +0 Output error message when negative depth programmed: +4
M function for spindle orientation in the fixed cycles	MP7442 Function inactive: 0 Orientation directly through the NC: -1 M function for orienting the spindle: 1 to 999
Maximum contouring speed at feed rate override setting of 100% in the Program Run modes	MP7470 0 to 99 999 [mm/min]
Feed rate for rotary-axis compensation movements	MP7471 0 to 99 999 [mm/min]
Datums from a datum table are referenced to the	MP7475 Workpiece datum: 0 Machine datum: 1
Running pallet tables	MP7683 Program Run, Single Block: Run one line of the active NC program at ever NC start; Program Run, Full Sequence: Run the entire NC program at every NC start: +0 Program Run, Single Block: Run the entire NC program at every NC start:+1 Program Run, Full Sequence: Run all NC programs up to the next pallet every NC start: +2 Program Run, Full Sequence: Run the entire NC pallet file at every NC start:+4 Program Run, Full Sequence: If running of the complete pallet file is selected (+4), then run the pallet file without interruption, i.e. until you press NC stop: +8 Pallet tables can be edited with the EDIT PALLET soft key: +16 Display the AUTOSTART soft key: +32 Pallet table or NC program is displayed: +64

# 13.2 Pin Layout and Connecting Cable for the Data Interfaces

# RS-232-C/V.24 Interface HEIDEHAIN devices



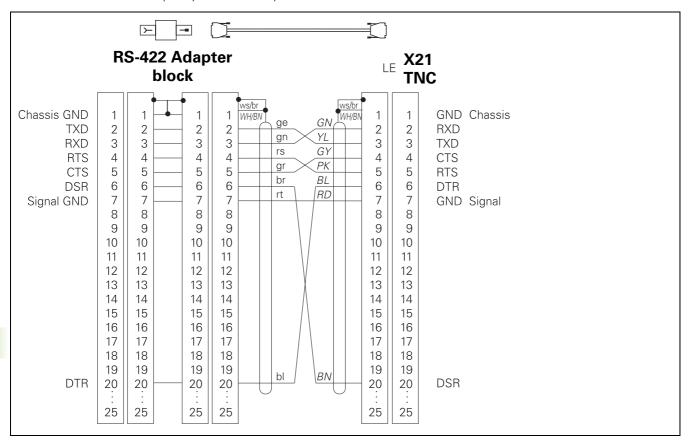


The connector pin layout on the adapter block differs from that on the TNC logic unit (X21).

#### Non-HEIDENHAIN devices

The connector pin layout of a non-HEIDENHAIN device may differ considerably from that on a HEIDENHAIN device.

This often depends on the unit and type of data transfer. The figure below shows the connector pin layout on the adapter block.

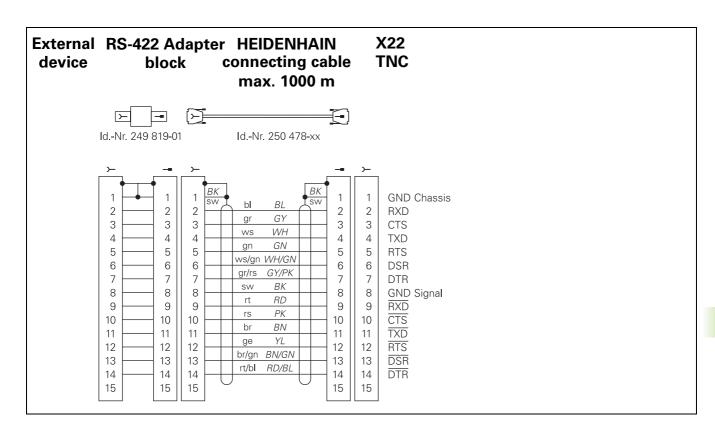


#### RS-422/V.11 Interface

Only non-HEIDENHAIN devices are connected to the RS-422 interface.



The pin layouts on the TNC logic unit (X22) and on the adapter block are identical.



# **Ethernet interface RJ45 socket (option)**

Maximum cable length: Unshielded: 100 m

Shielded: 400 m

Pin	Signal	Description
1	TX+	Transmit Data
2	TX-	Transmit Data
3	REC+	Receive Data
4	Vacant	
5	Vacant	
6	REC-	Receive Data
7	Vacant	
8	Vacant	

# **Ethernet interface BNC socket (option)**

Maximum cable length: 180 m

Pin	Signal	Description
1	Data (RXI, TXO)	Inner conductor (core)
2	GND	Shielding

# **13.3 Technical Information**

TNC features		
Description	Contouring control for machines with up to 9 axes plus oriented spind stop. The TNC 426 CB and TNC 430 CA feature analog speed control, t TNC 426 PB and TNC 430 PB feature digital speed control and integrate current controller.	
Components	■ Logic unit ■ Keyboard	
	Color visual display unit with soft keys	
Data interfaces	<ul><li>RS-232-C / V.24</li><li>RS-422 / V.11</li><li>Ethernet interface (option)</li></ul>	
	<ul> <li>Expanded data interface with LSV-2 protocol for remote operation of the TNC through the data interface with the HEIDENHAIN software TNCremo</li> </ul>	
Simultaneous axis control for contour elements	■ Straight lines: up to 5 axes Export versions TNC 426 CF, TNC 426 PF, TNC 430 CE, TNC 430 PE: 4 axes	
	<ul><li>Circles: up to 3 axes (with tilted working plane)</li><li>Helices: 3 axes</li></ul>	
Look-ahead	<ul> <li>Defined rounding of discontinuous contour transitions (such as for 3-D surfaces)</li> </ul>	
	■ Collision prevention with the SL cycle for open contours	
	<ul> <li>Geometry precalculation of radius-compensated positions for feed rate adaptation with M120</li> </ul>	
Background programming	One part program can be edited while the TNC runs another program	
Graphics	■ Interactive Programming Graphics	
·	■ Test run graphics	
	■ Program run graphics	
File types	■ HEIDENHAIN conversational programming	
•	■ ISO programs	
	■ Tool tables	
	■ Cutting data tables	
	■ Datum tables	
	■ Point tables	
	■ Pallet files	
	■ Text files	
	■ System files	
Program memory	■ Hard disk with 1500 MB for NC programs	
	■ No limit on number of files	

TNC features	
Tool definitions	Up to 254 tools in the program or any number in tables
Programming support	Functions for approaching and departing the contour
	On-screen pocket calculator
	■ Structuring programs
	■ Comment blocks
	■ Direct help on output error messages (context-sensitive)
Programmable functions	
Contour elements	■ Straight line
	■ Chamfer
	■ Circular path
	■ Circle center
	■ Circle radius
	■ Tangentially connecting circle
	■ Corner rounding
	Straight lines and circular arcs for contour approach and departure
	■ B spline
FK free contour programming	For all contour elements not dimensioned for conventional NC programming
Three-dimensional tool radius compensation	For changing tool data without having to recalculate the program
Program jumps	Subprogram
	■ Program section repeat
	■ Program as subprogram
Fixed cycles	Drilling cycles for drilling, pecking, reaming, boring, tapping with a floating tap holder, rigid tapping
	■ Cycles for milling internal and external threads
	■ Milling and finishing rectangular and circular pockets
	Cycles for multipass milling of flat and twisted surfaces
	Cycles for milling linear and circular slots
	Linear and circular hole patterns
	Milling pockets and islands from a list of subcontour elements
	Cylindrical surface interpolation
Coordinate transformations	■ Datum shift
	■ Mirror image
	Rotation
	■ Scaling factor
	■ Tilting the working plane



Programmable functions	
3-D touch probe applications	<ul> <li>Touch probe functions for compensating workpiece misalignment</li> <li>Touch probe functions for setting datums</li> <li>Touch probe functions for automatic workpiece measurement</li> <li>Digitizing 3-D surfaces with the measuring touch probe (optional)</li> <li>Digitizing 3-D surfaces with the triggering touch probe (optional)</li> <li>Automatic tool measurement with the TT 130</li> </ul>
Mathematical functions	<ul> <li>Basic arithmetic +, -, x and /</li> <li>Trigonometry sin, cos, tan, arc sin, arc cos, arc tan</li> <li>Square root and root sum of squares</li> <li>Squaring (SQ)</li> <li>Powers (^)</li> <li>Constant PI (3.14)</li> <li>Logarithms</li> <li>Exponential function</li> <li>Negation (NEG)</li> <li>Forming an integer (INT)</li> <li>Forming an absolute number (ABS)</li> <li>Truncating values before the decimal point (FRAC)</li> <li>Functions for calculating circles</li> <li>Logical comparisons (greater than, less than, equal to, not equal to)</li> </ul>

TNC Specifications	
Block processing time	4 ms/block
Control loop cycle time	<ul> <li>TNC 426 CB, TNC 430 CA:         <ul> <li>Contouring interpolation: 3 ms</li> <li>Fine interpolation: 0.6 ms (contour)</li> </ul> </li> <li>TNC 426 PB, TNC 430 PB:</li> </ul>
	Contouring interpolation: 3 ms Fine interpolation: 0.6 ms (speed)
	■ TNC M, TNC 430 M: Contouring interpolation: 3 ms Fine interpolation: 0.6 ms (speed)
Data transfer rate	Maximum 115,200 baud via V.24/V.11 Maximum 1 megabaud via Ethernet interface (optional)
Ambient temperature	■ Operation: 0° C to +45° C (32° to 113° F) ■ Storage: -30°C to +70°C (-22° F to 158° F)
Traverse range	Maximum 100 m (3973 inches)
Traversing speed	Maximum 300 m/min (11 811 ipm)
Spindle speed	Maximum 99 999 rpm

TNC Specifications		
Input range	■ Minimum 0.1µm (0.00001 in.) or 0.0001° ■ Maximum 99 999.999 mm (3.937 in.) or 99 999.999°	
Input format and unit of TNC functions		
Positions, coordinates, circle radii, chamfer lengths	-99 999.9999 to +99 999.9999 (5.4: places before decimal point, places after decimal point) [mm]	
Tool numbers	0 to 32 767.9 (5.1)	
Tool names	16 characters, enclosed by quotation marks with TOOL CALL. Permitted special characters: #, \$, %, &, -	
Delta values for tool compensation	-99.9999 to +99.9999 (2.4) [mm]	
Spindle speeds	0 to 99 999.999 (5.3) [rpm]	
Feed rates	0 to 99 999.999 (5.3) [mm/min] or [mm/rev]	
Dwell time in Cycle 9	0 to 3 600.000 (4.3) [s]	
Thread pitch in various cycles	-99.9999 to +99.9999 (2.4) [mm]	
Angle of spindle orientation	0 to 360.0000 (3.4) [°]	
Angle for polar coordinates, rotation, tilting the working plane	-360.0000 to 360.0000 (3.4) [°]	
Polar coordinate angle for helical interpolation (CP)	-5 400.0000 to 5 400.0000 (4.4) [°]	
Datum numbers in Cycle 7	0 to 2 999 (4.0)	
Scaling factor in Cycles 11 and 26	0.000001 to 99.999999 (2.6)	
Miscellaneous functions M	0 to 999 (1.0)	
Q parameter numbers	0 to 399 (1.0)	
Q parameter values	-99 999.9999 to +99 999.9999 (5.4)	
Labels (LBL) for program jumps	0 to 254 (3.0)	
Number of program section repeats REP	1 to 65 534 (5.0)	
Error number with Q parameter function FN14	0 to 1 099 (4.0)	
Digitizing parameters in digitizing cycles	0 to 5.0000 (1.4) [mm]	
Spline parameter K	-9.99999999 to +9.99999999 (1.8)	
Exponent for spline parameter	-255 to 255 (3.0)	
Surface-normal vectors N and T with 3-D compensation	-9.99999999 to +9.99999999 (1.8)	



# 13.4 Exchanging the Buffer Battery

A buffer battery supplies the TNC with current to prevent the data in RAM memory from being lost when the TNC is switched off.

If the TNC displays the error message **Exchange buffer battery**, then you must replace the batteries:



To exchange the buffer battery, first switch off the TNC!

The buffer battery must be exchanged only by trained service personnel!

## TNC 426 CB/PB, TNC 430 CA/PA

Battery type:Three AA-size cells, leak-proof, IEC designation "LR6"

- 1 Open the logic unit: The buffer batteries are located next to the power supply unit.
- 2 Open the battery compartment: With a screwdriver, open the cover by turning it counterclockwise by 90°.
- **3** Exchange the batteries and take care to properly close the battery compartment again.

### **TNC 426 M, TNC 430 M**

Battery type:1 Lithium battery, type CR 2450N (Renata) ID No. 315 878-01

- 1 Open the logic unit: The buffer battery is located to the right of the EPROMs of the NC software.
- **2** Exchange the battery. The new battery can only be inserted the right way around.

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